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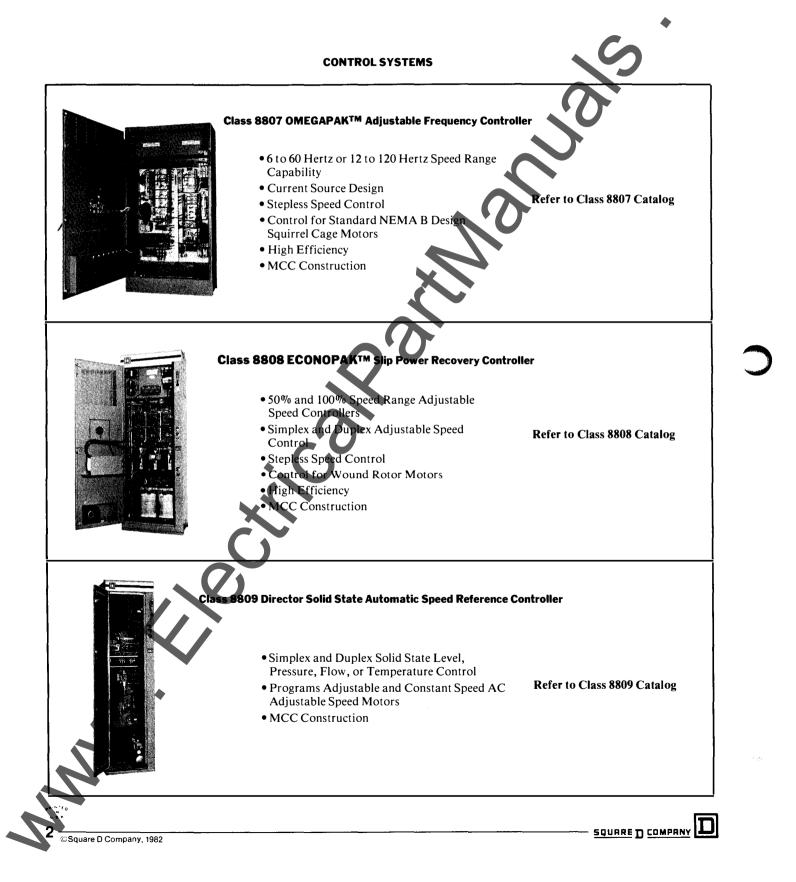


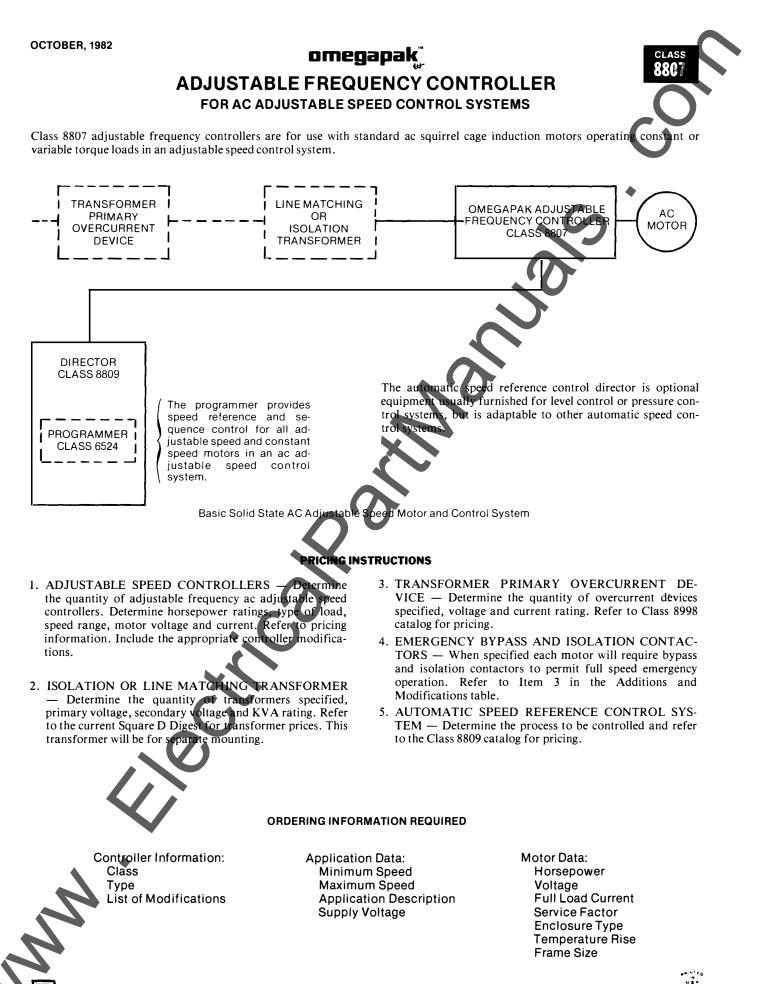
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Class 8807 OCTOBER 1982

AC ADJUSTABLE SPEED CONTROL SYSTEMS SELECTION GUIDE **OCTOBER, 1982**

AC adjustable speed control systems are coordinated solid state ac adjustable speed controllers for all variable torque loads and with proper application, many constant torque and constant horsepower loads. These systems consist of: Class 8807 or Class 8808 adjustable speed controllers and Class 8809 director automatic speed reference and sequence controls.





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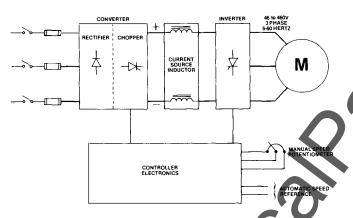
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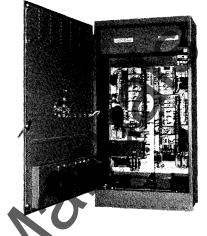


DIFICITION OF CONTROLLER

Adjustable frequency controllers provide stepless speed control for standard 460V, 3 phase, NEMA Design B, ac squirrel cage induction motors. Thyristors (SCR's), diodes and their associated circuits vary the frequency applied to the motor for speed control. Basic controller includes:

- Basic controller includes: Three phase bridge rectifier Thyristor current source chopper Thyristor inverter Output voltage clamp Disconnect switch with external operator, door interlocked Hand - Off - Automatic selector switch Manual speed adjustment
 - Power on light Run light
 - Speed indicating meter
 - NEMA Type 1 enclosure





OCTOBER, 1982

460V, 3 Phase	50/60 Hertz ▲	0 to 40 °C Ambient		
460 Volt	Maximum Full Load Current	Variable and Constant Torque Applications 150% Current for 60 Seconds		
Horsepowert	Amperes†	Туре	Price*	
15 20 30 40 50 60 75 100 125 150	21 28 34 40 53 65 77 98 126 156 188	CT-015 CT-020 CT-020 CT-030 CT-040 CT-050 CT-050 CT-075 CT-100 ■VT-125 ■VT-150	\$17,430. 20,084. 21,960. 23,790. 26,352. 27,816. 30,012. 37,371. 44,447. 45,741.	

Select controller based on motor horsepower and full load current.
A motor starter is not recommended or required. Refer to Use of Contactors section of Application Data.

For 230V application Data.
For 230V applications consult factory.
Variable torque applications only. Rated 110% for 60 seconds.

ADDITIONS AND MODIFICATIONS

Item	Description		Price	Item	Description	Price
1	Power CIRCUIT MODIFICATIONS: Power Bus (Per Controller) 600 Amp 1000 Amp 1200 Amp 1600 Amp	HP 0 60V 15 - 30 40 - 60 75 - 150 15 - 30 40 - 60 75 - 150 15 - 30 40 - 60 75 - 150 15 - 30 40 - 60 75 - 150	\$ 360. 541. Consult Factory 561. 842. Consult Factory 629. 943. Consult Factory 763. 1141. Consult Factory	3 4 5 6	Bypass and isolation contactors to permit emergency full speed operation. HP @ 460V 15 - 25 30 - 50 60 - 100 125 - 150 CONTROL CIRCUIT MODIFICATIONS Push Button or Selector Switch Pilot Light (specify color) Remote operator station instead of cabinet mounted devices	2336. 3004. 4801. 7471. 92. 48. Consult Factory
2	Ground Bus 300 Amp 600 Amp	$\begin{array}{rrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrrr$	143. 214. Consult Factory 285. 427. Consult Factory	7 8 9 10	METERING Elapsed Time Indicator Ammeter with CT Voltmeter Test meter to aid troubleshooting	233. 540. 270. 960.

OMEGAPAK ADJUSTABLE FREQUENCY CONTROLLER APPLICATION DATA

When applying adjustable frequency controllers, the following items must be considered — as described below and in the following pages.

Maximum and Minimum Speed Motor Selection Type of Load Efficiency Power Factor Speed Regulation

Controller Ventilation, Heat Loss, Ambient Temperature Use of Contactors

MAXIMUM SPEED AND MINIMUM SPEED

The standard controller can produce an output frequency of from 6 Hz to 60 Hz. This corresponds to a motor speed range of 10% to 100% of rated speed. Many applications do not require the motor to operate below 10% speed; consequently, the controller has been designed to allow the motor to operate down to 10% speed (6 Hz) but is adjustable up to 40% speed (24 Hz). Although maximum operating frequency is normally 60 Hz and is factory set at that point, the maximum operating frequency is adjustable from 30 Hz to 63 Hz (50% to 105% rated speed).

Some special applications require the motor to operate at 150% rated or as much as 200% rated speed. The controller can be modified to operate within these extended motor speeds but the motor manufacturer must be consulted to verify that the motor will not be damaged and can withstand speeds above its 100% rating.

MOTOR SELECTION

Motors used with the controller will normally be industry standard NEMA Design B squirrel cage induction motors; however, in some cases where very precise speed regulation is required, synchronous motors may be required. When selecting a motor for use with an adjustable frequency controller or applying a controller with an existing motor, the effects of reduced speed operation on the motor must be considered. The cooling air flow through or over the motor is a function of the speed at which internal or external fans are turning. As a result, the motor will run hotter at reduced speed unless its loading is reduced (see Type of Loads). Also, additional heating will occur when the motor runs at reduced speeds, because the motor input power will contain some harmonics. In general, most open dripproof and totally enclosed fan cooled (TEFC) motors will tolerate operation from 50% to 100% rated speed without difficulty (see Types of Loads). A 1.15 motor service factor is recommended.

TYPES OF LOADS

Motor loads generally fall into three categories: variable torque, constant torque and constant horsepower. In general, application of adjustable speed controllers to motors driving variable torque loads is relatively simple. Motor heating is not normally a problem, as the torque requirements are less as the speed is reduced. Constant torque and constant horsepower loads are more difficult. The motor manufacturer should be consulted before applying adjustable speed controllers to motors driving these type loads. Forced ventilation may be recommended and the minimum and/or maximum speed may be limited.

EFFICIENCY

The controller controls the synchronous speed of an ac induction motor and does not cause slip loss power to be produced when the motor operates at less than rated speed. The controller efficiency remains high, approximately 94%, while the motor efficiency varies according to the motor size, operating speed, and loadingt Generally, larger motors have higher efficiencies and motor efficiency drops as the load becomes less.



The displacement power factor of the standard controller remains essentially constant at .95 lagging regardless of motor speed, motor load, or motor power factor.

SPEED REGULATION

AC motors are considered constant speed machines; however, this is not entirely true. The motor speed will deviate with loading. As load increases, motor speed will decrease slightly due to increased slip (the difference between the stator rotating field speed and rotor speed). The controller includes a feature called slip compensation which will correct for speed variations due to load changes. Speed regulation with slip compensation is $\pm 1\%$ of full speed. If better regulation is required it will be necessary to use a synchronous motor.

CONTROLLER VENTILATION, HEAT LOSS, AMBIENT TEMPERATURE

The standard controller is equipped with fans to circulate air through the enclosure. A slight amount of heat, approximately 152 BTU per hour per horsepower, will be dissipated into the control room. Normal control room ventilation will usually keep the ambient temperature within the required 0° to 40° C range. If temperatures below 0° C are expected, space heaters should be added to the controller. If temperatures higher than 40° C are expected, additional cooling will be required or the controller must be derated.

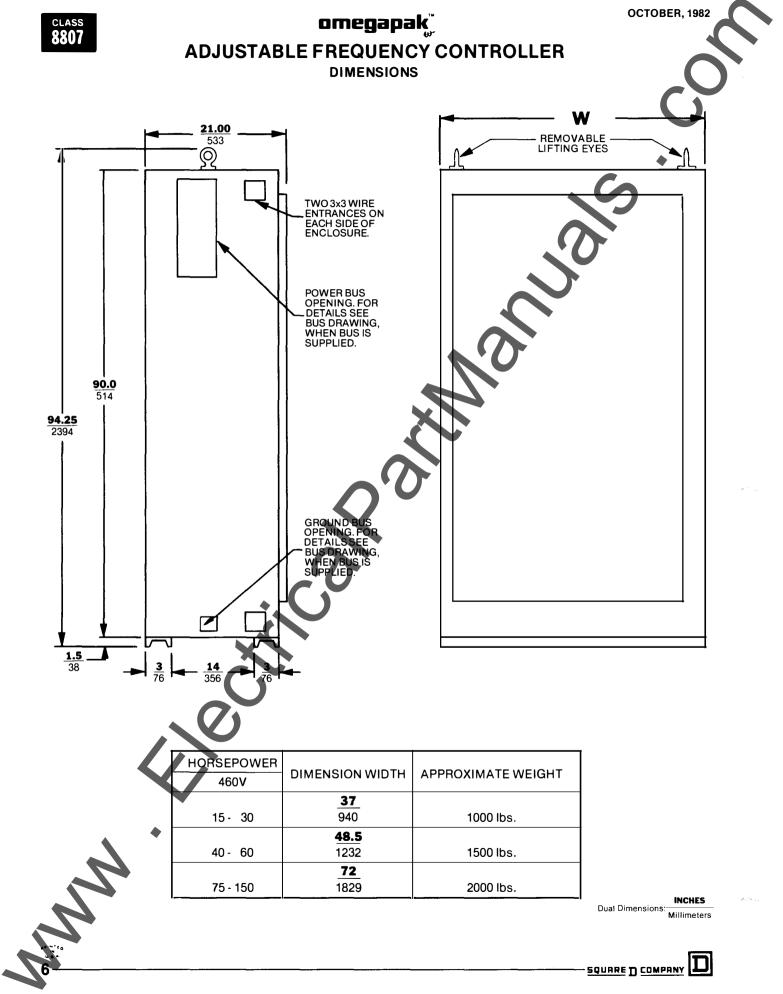
BYPASS AND ISOLATION CONTACTORS

The standard controller does not include the provision for emergency full speed operation. If this feature is desired, bypass and isolation contactors will be required. The isolation contactor isolates the controller from the line, while the bypass contactor applies 60 Hertz line power to the motor. Care should be taken to ensure that the isolation contactor does not open while the controller is operating. A contactor should not be used between the ac supply line and the controller 460 volt input.

CURRENT LIMIT

The OMEGAPAK controller employs a current regulator circuit that limits the inrush current during starting and acceleration. This feature when properly utilized can often result in lower KVA ratings on stand-by emergency power equipment. The controller current limit is adjustable between 50% and 150% of motor nameplate full load current; which can be field adjusted by a potentiometer on the main control board.

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OMEGAPAK ADJUSTABLE FREQUENCY CONTROLLER GENERAL SPECIFICATIONS

1.0 GENERAL

An adjustable speed control system shall be supplied to control the speed of a standard ac squirrel cage induction motor by controlling the frequency applied to the motor driving the load. A separate adjustable speed controller shall be supplied for each motor. Failure of an adjustable speed controller shall not prevent other system loads, which normally operate as adjustable speed loads, from operating in an adjustable speed manner. The adjustable speed control system shall be designed to operate from a manual speed control potentiometer or accept an automatic speed reference signal.

2.0 ADJUSTABLE CONTROLLERS

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The adjustable speed controls shall be Square D Company, OMEGAPAKTM adjustable frequency controller to control the speed of a _____ HP, 460 volt squirrel cage motor from ____% to full rated speed. The controller shall be of the adjustable frequency type and shall be fully rated to control the motor under all speed and load conditions. The controller shall not cause system displacement power factor to be less than .95 at any speed.

The adjustable frequency controller shall accept 460 volt, 3 phase, 50/60 Hertz input power, convert it to dc, and regulate the current to a thyristor inverter, and clamp the output voltage to a level which will not degrade the insulation of a standard squirrel cage induction motor.

The adjustable frequency controller shall be inherent electronic short circuit protected in that a short circuit placed on the inverter output terminals shall not damage the controller or cause a protective fuse to blow. The controller shall be equipped with adjustable current limit, individually adjustable acceleration and deceleration rates, and adjustable minimum and maximum speeds. Speed regulation shall be $\pm 1\%$ of full speed without the use of a tachometer. A door mounted speed indicating meter shall be supplied.

The controller shall be equipped with a main disconnect switch interlocked with the controller door. A Hand-Off-Automatic selector switch and manual speed control shall be provided. The controller shall also accept an input signal of 0-10 vdc or 4-20 ma dc as an automatic speed control signal when the controller is in the automatic mode.

Electronic circuitry shall include diagnostic light emitting diodes (LED's) which monitor circuit operation.

The controller shall be housed in a NEMA Type 1, free-standing enclosure and shall be designed to operate in an ambient temperature range of 0 °C to 40 °C.

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