

## INSTALLATION . OPERATION . MAINTENANCE

## INSTRUCTIONS

# TYPE SCO-T SOLID STATE SINGLE PHASE OVERCURRENT RELAY

**CAUTION:** It is recommended that the user become acquainted with the information in this instruction leaflet before energizing the equipment. Failure to observe this precaution may result in damage to the equipment.

## **APPLICATION**

The SCO-T relay is a single phase solid state non-directional time over-current device. It is used

to sense current level above the setting and normally is used to trip a circuit breaker to clear faults. A wide range of characteristics permit applications involving coordination with fuses, reclosers, cold load pickup, motor starting, or essentially fixed time applications.

The following describes typical applications of the SCO-T Relay:

RELAY TYPE	CURVE MODULE	TIME CURVE	TYPICAL APPLICATIONS
SCO-2T	A02	Short	<ol> <li>Differential protection where saturation of current transformers is not expected, or where delayed tripping is permissible.</li> <li>Overcurrent protection, phase or ground, where coordination with downstream devices is not involved and 2 to 60 cycle tripping is allowable.</li> </ol>
SCO-5T	A05	Long	Motor locked rotor protection where allowable locked rotor time is approximately between 10 and 70 seconds.
SCO-6T	A06	Definite	Overcurrent protection where coordination with downstream devices is not involved and SCO-2T is too fast. The operating time of this relay does not vary greatly as current level varies.
SCO-7T	A07	Moderately Inverse	1) Overcurrent protection where coordination with other devices is required, and generation varies.
SCO-8T	A08	Inverse	2) Backup protection for relays on other circuits.
SCO-9T	A09	Very Inverse	
SCO-11T	A11	Extremely Inverse	<ol> <li>Motor protection where allowable locked rotor time is less than 10 sec.</li> <li>Overcurrent protection where coordination with fuses and reclosers is involved, or where cold load pickup or transformer inrush are factors.</li> </ol>

All possible contingencies which may arise during installation, operation, or maintenance, and all details and variations of this equipment do not purport to be covered by these instructions. If further information is desired by purchaser regarding his particular installation, operation or maintenance of his equipment, the local Westinghouse Electric Corporation representative should be contacted.

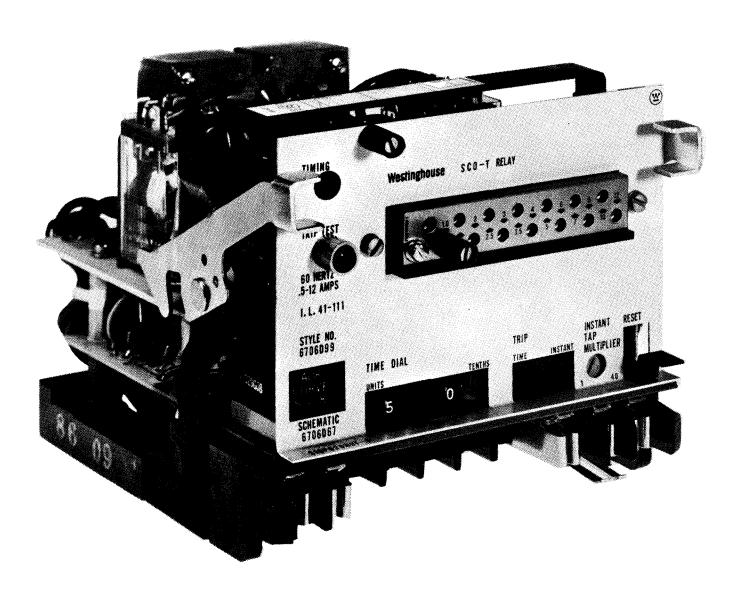


Fig. 1. Type SCO-T Relay-Front Left Side View

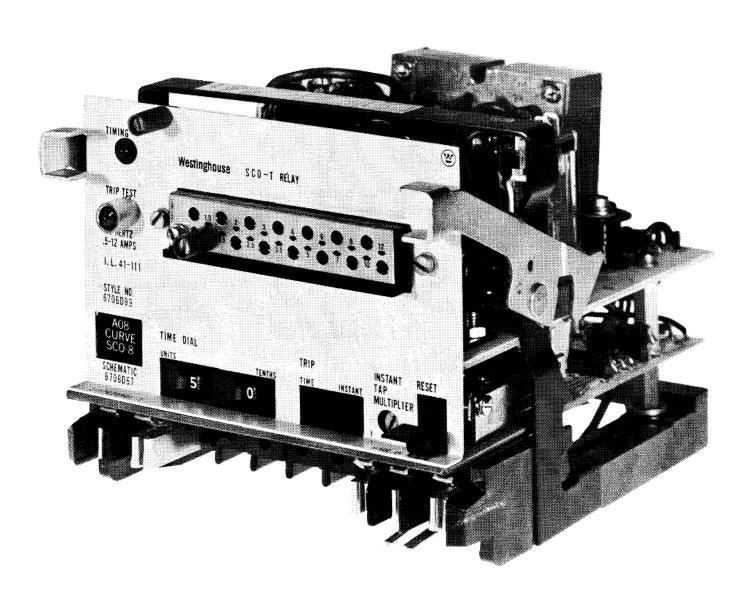


Fig. 2. Type SCO-T Relay-Front Right Side View

The SCO-T relay is equipped with an instantaneous trip feature with separate trip output to provide high speed tripping for high current faults.

Instantaneous trip units can be applied effectively where wide variations in fault currents occur for different fault locations, but have limited applications where wide variations in fault currents occur for a fixed fault location. It responds to total current and must be set to include the effect of dc current and to override the conditions that should be ignored such as transformer inrush, motor locked rotor, and faults outside of the desired trip zone.

Independant contact trip outputs and separate indication are provided for the instantaneous and time delay tirp outputs. No indication occurs unless there is current flow in the trip circuit. Indicator reset is accomplished manually.

The relay is self contained in that the power supply for the solid state logic is derived from the current transformer. There is no continuous drain on the tripping battery.

See SETTINGS Section for further application data.

## CONSTRUCTION

The SCO-T relay is a static relay consisting of 2 printed circuit modules, a time curve plug-in module, and a front panel assembly, packaged in a FT-11 case. For detailed information on the flexitest case, referred to I.L. 41-076.

The photographs in Figures 1 and 2 show the front left and front right view of the SCO-T reay removed from the case.

All of the circuitry suitable for mounting on printed circuit boards is contained on the two modules horizontally mounted on posts behind the front panel. The top module contains the transformer and "front-end" circuitry and the trip output relays for the SCO-T while the bottom module contains the power supply, information sensing, curve shaping, tripping and indication circuitry, as well as the plug-in curve module. Terminals for current input and trip output are located on the rear of the case, and all inputs and outputs pass through the FT switchjaws on the lower front part of the relay, below the front panel. The front panel, in addition to showing all pertinent style and setting information, has the minimum pickup indicator and the trip test switch located on the upper left-hand side.

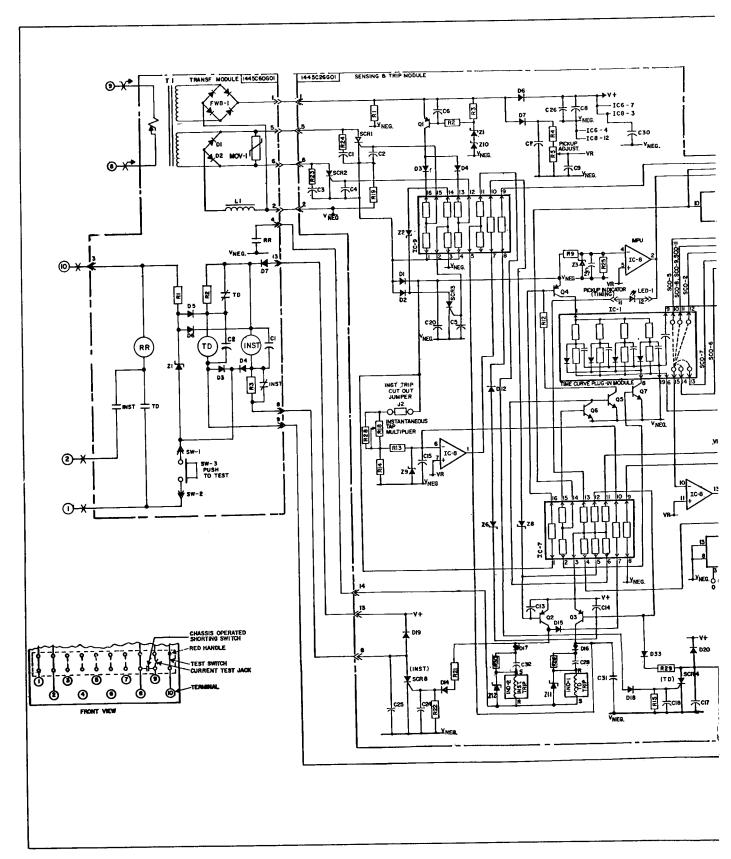


Fig. 3. SCO-T Inte

	1445026	GOI SC	3 1 PHASE							
IC-4 BNARY COUNTER  33  2  4  5   JYNEG.	1445C26 COMPONE C32 C1 C2 C3 C4 C5 C6 C7 C8 C9 C11 C12 C13 C14 C15 C19 C24 C17 C25 C25 C25 C25 C29 C30 S1 S1	CAPACITOR CAPACITOR CAPACITOR CAPACITOR CAPACITOR	DESCRIPTION	STYLE (184.466) 8 79.401 3509.43 3509.	HIS 1913 4H01 1H13 4H01 4H01 4H01 2H01 2H02 2H01 2H02 4H03 4H03 4H03 4H03 4H03 4H01 9H01 9H01 9H01 9H01 9H01 9H01 9H01 9	COMPOI JI J2 J3 R5 R18 R1 R2 R2 R15 R15 R15 R15 R15 R25 R25 R26 R27 R27 R28 R27 R27 R28	JUMPER JUMPER JUMPER JUMPER JUMPER JUMPER JUMPER POT POT POT RESISTOR	3.0K .50	- STOR W 22222222222222222222222222222222222	\$62A478H01 \$62A478H01 \$62A478H01 \$62A478H01 \$62A478H01 \$60A626H05 \$50A626H05 \$512A37H01 \$29A531H43 \$549A531H3 \$629A531H3 \$629A531H80 \$629A531H80 \$629A531H80 \$629A531H80 \$629A531H80 \$629A531H80 \$629A531H80 \$629A531H08 \$629A531H08 \$629A531H08 \$629A531H08 \$629A531H08 \$629A531H08 \$629A531H08 \$629A531H08 \$629A531H08 \$629A531H08 \$629A531H73 \$629A531H73 \$629A531H73 \$629A531H73 \$629A531H73 \$629A531H73 \$629A531H73 \$629A531H73 \$629A531H73
VR CONE SHOT)  ONE SHO	D3 D4 D6 D7 D8 D9 D10 D12 D14 D15 D16 D17 D18 D19 D20 D31 D20 D31 IC2 IC3 IC4 IC5 IC6 IC7 IC8 IC7 IC8	DIBDE	IN 48 18 IN 48 18 IN 48 18 IN 48 18 IN 41 48 IN 48 18 IN 48 22 IN 48 22 IN 48 22 IN 48 22 IN 41 45 IN 41 48 IN	188A34 188A34 188A34 836A92 836A92 836A92 836A92 188A34 188A34 188A34 188A34 188A34 774B93 774B93 774B93 775B06 775B06	2H06 2H06 8H06 8H06 8H06 8H06 8H06 2H11 8H06 2H11 8H06 2H11 2H11 2H11 2H11 2H11 1H14 6H01 1H14 2H01	RESO  01  02  03  04  05  06  07  21  22  23  25  26  28  29  210  SCR-12  SCR-28  SCR-8  ICI	TRANSISTOR  TRANSI	2 202907A 2 202907A 2 202907A 2 202907A 2 205551 2 205551 2 20222A 2 20222A	w 1%	848.4819H48 762.4672H17 762.4672H17 762.4672H17 752.9435H02 752.9435H02 762.4672H15 762.4672H15 18.6472H15 18.6472H16 18.
	1						SWITCH ID-2 INDICATOR	2A21600IG		3509A52H0I 3513A71G0I
V++						Z11 Z12	ZENER ZENER		3.6 V	186 A797H12
1C-3   1C-2   1C-2   1D-2   1C-2   1D-2			C2 C	SCO  APACITOR APACITOR (ODE IODE IODE IODE IODE IODE IODE IODE I	I50.4.H IER VM48	5% 5% 5% 15V	5TYLE  3509A3 3509A3 188A34 18	2HO2 22HO2 2HI1 2HI1 2HI1 2HI1 2HI1 2HI1 2HII 2HII		
			LED L	ARISTOR MOUNTED AMP WITCH	ERZ-CIODH		3509A3 879A77 3510A0	4H02		Sub.10 6706D6

#### PRINTED CIRCUIT MODULES

Following is a description of the printed circuit modules used in the SCO-T relay. Refer to the internal schematic shown in Figure 3. This schematic contains a detailed scheme for understanding of the circuitry and a complete list and description of the components for renewal parts.

For those users not generally acquainted with circuit notation or with device symbols of those components used in the SCO-T drawings, it is recommended that a copy of Westinghouse instruction leaflet I.L. 41-000.1 entitled "Symbols for Solid State Protective Relaying" be consulted.

## TRANSFORMER MODULE

Component Location Figure 5.

The transformer module, mounted at the top of the relay, contains the current transformer for obtaining the line current information and also supplies the power to operate the electronic circuits. A tap block with 14 taps covering the range of 0.5-12 amperes, is contained at the front of the module and extends through the front panel. A full-wave-bridge for the power supply winding and two diodes for the information winding of the transformer are also mounted on this circuit module to minimize wiring between the two modules. The two trip output relays and the reed relay for indicator pickup are also located on this module.

## SENSING & TRIP MODULE

Component location Figure 6.

The sensing and trip module is mounted at the bottom of the relay, beneath the transformer module. It contains the circuitry for power supply voltages V+ and VR, information sensing, curve shaping, tripping and indication. It also contains two decade thumb wheel switches for setting the time-dial, the potentiometer for setting the instantaneous trip, the instantaneous trip cut-out jumper, the reset lever assembly for resetting the time delay and instantaneous trip indicators, and the socket for the plug-in curve module. It also contains the two multi-turn trimpot calibration controls for setting minimum pickup and calibrating the curve.

## TIME CURVE MODULE (IC-1)

The time curve module is a 24 pin plug-in module containing the specific circuitry and components for each particular curve style. There are seven different curve module styles corresponding to the SCO-2, SCO-5, SCO-6, SCO-7, SCO-8, SCO-9 and SCO-11 curves. This module plugs into the 24 pin socket on the sensing-trip module and is visible to the front of the relay through a window in the front panel. There the front label on the module completes the last 3 digits of the style of the relay (printed on the front panel), and also shows which curve the relay is set for i.e. "SCO-2 curve". See Figure 1 front photograph and Figure 6 for exact location. For further information on time curve modules see Plug-in Curve Modules section in Renewal Parts of this instruction leaflet and also I.L. 41-110.2 instruction leaflet for Type SCO Time Curve Plug-in Modules.

## FRONT PANEL

The front panel, which is attached to the two tap block brackets on the transformer module, shows all pertinent style and setting information. It also has the minimum pick-up indicator and the trip test switch mounted on the upper left hand side. See Figure 1 for exact location.

## MINIMUM PICKUP INDICATOR TIMING

The minimum pickup indicator is mounted on the upper left-hand corner of the front panel. It consists of a light-emitting diode which is dimly lit at 99% tap value current and fully energized when current exceeds the minimum tap value. It is visible from the front of the relay which facilitates monitoring and testing. See Figure 1 for exact location.

#### TRIP TEST SWITCH

The trip test switch is mounted on the upper left-hand side of the front panel. It consists of a push-to-test switch protected from accidental activation by a shield guard which requires a definite depression of the switch by some device that fits inside the guard, i.e. pencil, slender rod, etc. See Figure 1 for exact location. The trip test function derives its power from the station battery to pickup both the time delay and instantaneous trip relays simultaneously. Battery positive must be present on terminal 10 and a return path to battery negative must be provided from terminal 1 (through a trip coil with at least .5 amp loading).

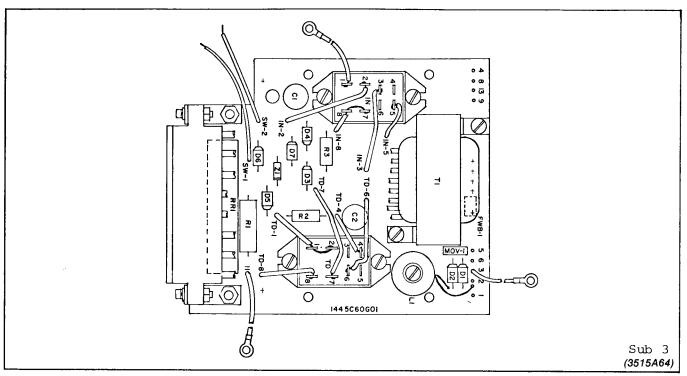


Fig. 5. Transformer Module Component Location Single Phase

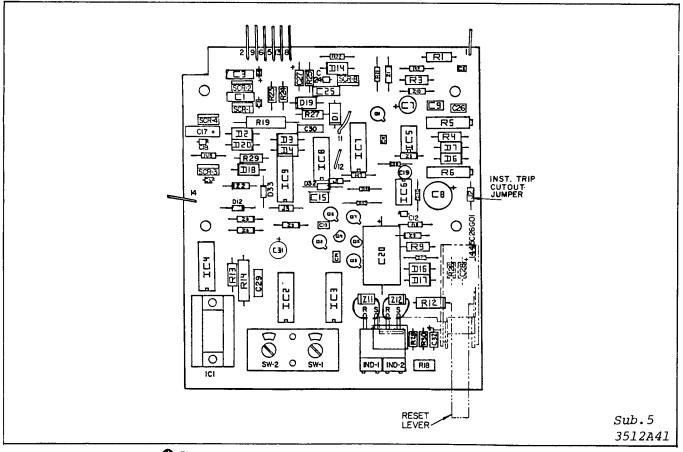


Fig. 6. Sensing-Trip Module Component Location Single Phase

#### THEORY OF OPERATION

The basic operation of the SCO-T relay will be described with the aid of Figure 3 internal schematic 6706D67, and Figure 4 external scheme.

The SCO-T relay derives both its power and its sensing information from a single transformer. The type of transformer used is of the linear current transformer design consisting of a tapped primary winding and two secondary windings. The tapped primary winding allows 14 different pickup current settings from 0.5 to 12 amperes. One of the two secondary windings is a high current power supply winding (low number of turns) and the other one is a low current information winding (high number of turns). The circuit operation is based on the transformer ampere-turns balance principle between the primary and the secondary. Following each zero crossing of the line current, balancing of the primary ampere-turns is first achieved by the high current winding. During this time thyristors SCR-1 and SCR-2 are both off and the power supply regulator circuit is the only load imposed at the transformer's secondary. When the regulator reaches the specified regulated voltage based on zener diodes Z1 and Z10, transistor Q1 generates a signal to turn SCR-1 and SCR-2 on. Since these thyristors form a full wave bridge with diodes D1 and D2 on the transformer module, only the respective forward-biased thyristor will fire. Upon firing, an instant voltage drop is seen at the power supply winding output.

This action forces the diode bridge FWB-1 into a back-biased condition cutting off the power supply winding current flow. Balancing of the primary ampere-turns is, therefore, carried out in the low current, or information winding circuit. From this switching point the next zero crossing, the line current represented in voltage form is obtained across the burden resistor R19. When the line current experiences the next zero-crossing the thyristor is turned off automatically, again allowing the current flow in the power supply winding to charge the regulator circuit. The transformer is designed to allow a large enough current flow in the power supply winding at the pickup level so that the regulated voltage can be established very quickly. Once the regulated supply voltage is obtained, the subsequent replenishment uses only the very initial portion of each half cycle of the current. Therefore, the flux build-up due to the power supply replenishment is very low and the design is capable of providing a linear current information transfer up to 40 times pickup current.

The line current information obtained across burden resistor R19 in voltage form is then utilized using the technique of RC approximation and digital time multiplication for time-current curve sensing. The time current curves generated by this design are closely matched to the ones presently obtained from the electromechanical induction disc type relays. This technique utilizes a short, precision time-constant network for timecurrent curve shaping, and then uses digital counting and decoding techniques to provide time multiplication and precision time dial section. This has an advantage over a straight RC approximation scheme since long delay times are required at low multiples of pickup current. Component leakage and other design factors that make the straight RC network type of timing unattractive and complicated are not considered a problem in this digital approach. Thus, the information across resistor R19 is fed through transistor Q4 to this precision multi-branch RC network housed in the plug-in curve module IC-1. Depending upon the degree of inverseness of the desired time-current curve, the number of RC branches may vary from 2 to 4 branches. Each RC branch contains a first order RC circuit with a time-constant different from other branches. The branches are then combined to give a common weighted output. The weighted RC output is then compared with the reference V<sub>R</sub> by IC-6. This operational amplifier maintains a closed-loop operation through Z5 and D8 before the equivalent voltage of the RC network reaches the reference level V<sub>R</sub>. This reference level is set at the minimum pickup condition through the comparator IC-8 (pin 2 output) and potentiometer R5. Once this VR reference level is exceeded, IC-6 outputs a negative-going signal which triggers the one-shot circuit (IC-5). The one-shot signal, which has a pulse width adjusted to supply the proper definite delay time (poteniometer R6), resets the multi-branch RC network by turning transistor Q4 off, through Q5 and Q6, and by turning Q7 on to discharge the RC capacitors.

The one-shot signal also advances the binary counter circuit IC-4. This counter, which is enabled (logic 0 on pin 11) when the input current is above the minimum pickup level and reset or kept inactive when below minimum pickup level (MPU IC-8 pin 2), counts the negative going signals from the one-shot output. When the correct count is attained, up to 2<sup>12</sup> power or 4096 counts, depending upon which binary output is used per respective curve connection in IC-1, the counter output is inverted by comparator IC-9 (pin 13) and then drives the two timedial decade counter/decorder circuits, IC-3 and IC-2. These two counters, one for tenth timedial positions and one for unit time-dial positions, are connected to a dual decade thumbwheel switch to provide ninety-nine distinct time-dial settings, which means up to 99 count outputs from the binary counter IC-4. Thus, for example, if the  $2^{10}(1024)$  output of IC-4 is used, up to 210X time dial setting (from 1 to 99) actual counts of the RC network takes place before generation of a trip signal. These decade counters, as in the previous case of the binary counter IC-4, are kept inoperative and reset whenever the minimum pickup signal on pin 15 of IC-3 and IC-2 goes to a logic 1, indicating that the input current dropped below pickup level.

Thus, when the set time dial count has elapsed, a positive output occurs from both the decade counters. These are applied through the time dial switches to the cathode ends of D9 and D10, reverse biasing them. This allows the signal present on pin 8 of comparator IC-8 to now become a logic 1 (through R8) generating a trip signal (IC-8 pin 14). Prior to this, the signal on pin 8 of comparator IC-8 was kept at a logic 0 level by the shorting of this input, in accordance with the logic 0 outputs of IC-3 and IC-2, through either or both of diodes D9 and D10.

This trip signal is then applied through IC-9 D12 and Z6 to the base of Q3, turning it on. This, in turn, applies 2 distinct branch signals; one is through IC-9 and D18 to gate thyristor SCR-4, the second is through D16, C28 and R26 to IND-1, the time-delay trip indicator. Thus, with the turn on of SCR-4 the T.D. relay on the top module is energized and a trip output occurs between terminals 1

and 10 of the SCO-T relay. The turn on of the indicator can only occur when the reed relay RR picks up, concurrent with the flow of trip coil current. This happens when the normally open RR contact closes completing the path to, and allowing the indicator current to thereby flow to, power supply negative.

The trip of the breaker will interrupt the current input, and total reset of the relay circuitry occurs within 50 milliseconds plus an additional 15 to 20 milliseconds dropout time of the trip relay. Reset of the indicator is accomplished manually through use of the reset lever actuated from the outside of the case. This lever magnetically flips the indicator back to its reset state.

The instantaneous trip circuitry also derives its information from the voltage across resistor R19. This information is taken from the cathode side of diode D1, through the instantaneous trip cutout link jumper, to the level control and filter circuitry on the input of the instantaneous trip comparator, IC-8 (pin 6). This input is then compared with the minimum pickup reference level V<sub>R</sub> by IC-8. The potentiometer R18 allows a continuous range of setting from 1 to 40 times the minimum pickup tap setting of the relay. Once the V<sub>R</sub> reference level is exceeded, IC-8 (pin 1) outputs a negative-going instantaneous trip signal. This signal is then applied through IC-9 and Z8 to the base of Q2, turning it on. This, in turn, applies 3 distinct branch signals; one is through D15 and IC-7 to immediately seal-in the instantaneous input on IC-8 pin 6, the second is through R21 and D14 to gate thyristor SCR-8, thereby energizing the INST. relay, and the third is through D17 the IND-2, the instantaneous trip indicator. With the energization of the INST. relay a trip output occurs through similar paths as previously described when initiated by the time delay circuit.

Similarly to the time delay trip indicator, turn on of the instantaneous trip indicator can only occur when the reed relay RR turns on, and is concurrent with the flow of trip coil current.

## **CHARACTERISTICS**

## RANGE

The SCO-T has taps covering the range of 0.5 to 12 amperes. The tap values are: 0.5, 1.0, 1.5, 2.0, 2.5, 3.0, 3.5, 4, 5, 6, 7, 8, 10 and 12 amperes.

Pickup accuracy  $\pm 5$  percent of tap value for all taps.

The instantaneous circuit has a range of 1 to 40 times the tap value selection with a continuously adjustable pickup.

## TIME-OVERCURRENT CHARACTERISTICS

The time vs. current characteristics are shown in Figures 7 to 13. These characteristics give

the trip time for the various time dial settings when the indicated multiples of tap value current are applied to the relay. 8 milliseconds T.D. relay pickup time delay must be added to these curves for total operate time of the SCO-T relay.

Timing accuracy  $\pm 10\%$  of the characteristics curve for any combination of time dial setting and tap value. Operating time repeatability  $\pm 2\%$  at 25°C. for any given time dial and tap setting.

**NOTE:** A higher percentage value may occur on the 0.1 time dial position when the SCO-T relay is suddenly energized due to angle of incidence and delay in power supply turn-on.

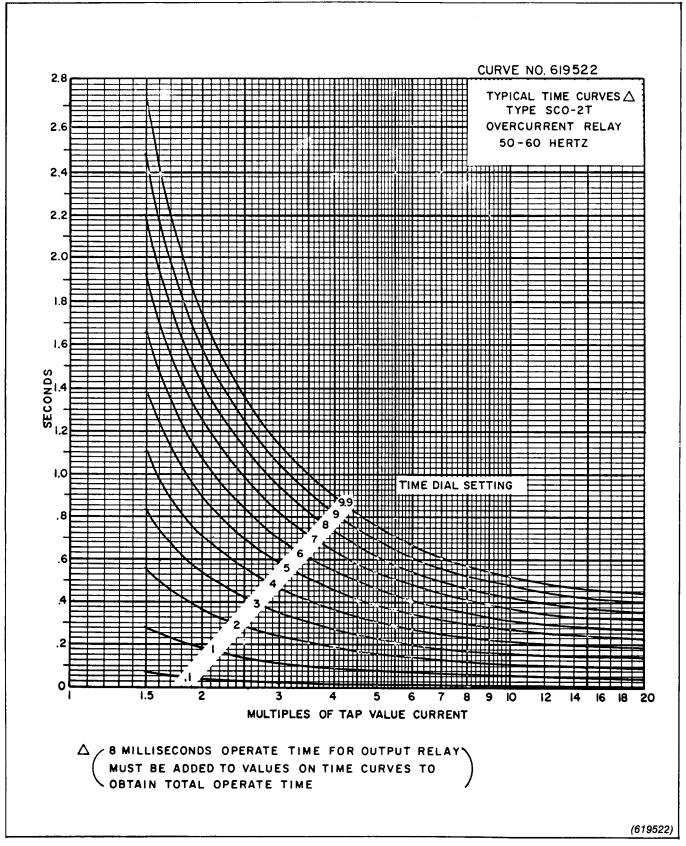


Fig. 7. Typical Time Curves of the Type SCO-2T Relay

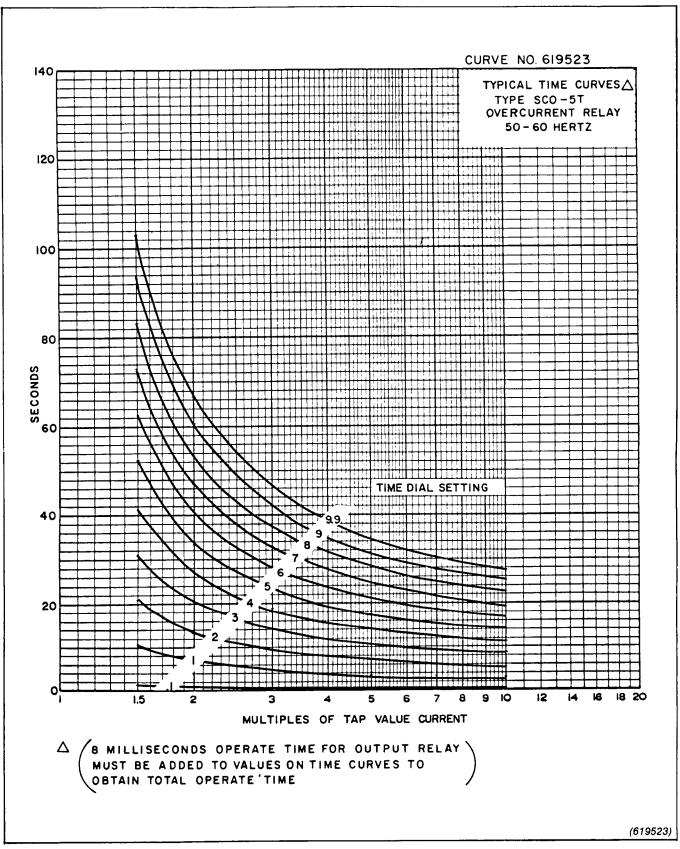


Fig. 8. Typical Time Curves of the Type SCO-5T Relay

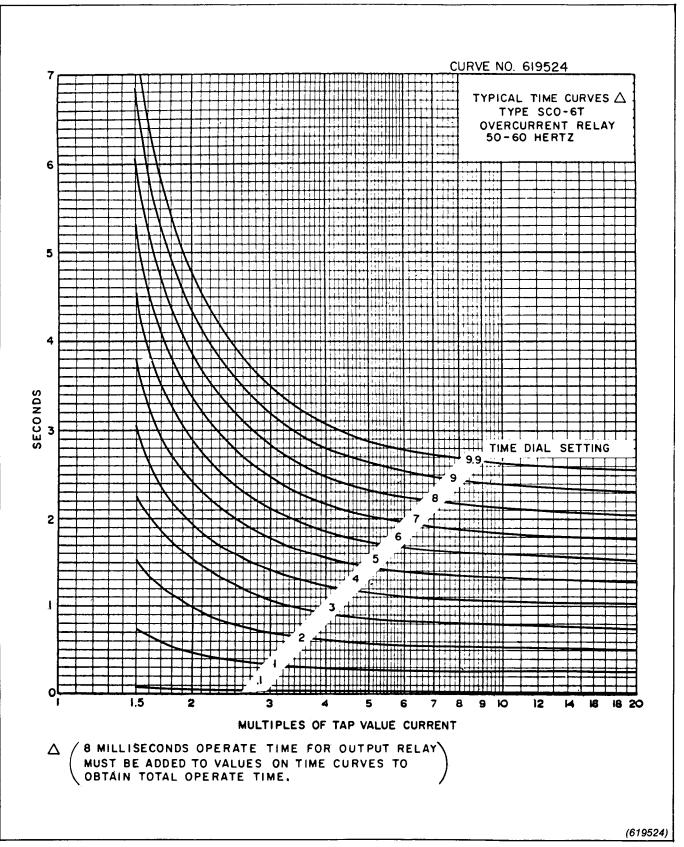


Fig. 9. Typical Time Curves of the Type SCO-6T Relay

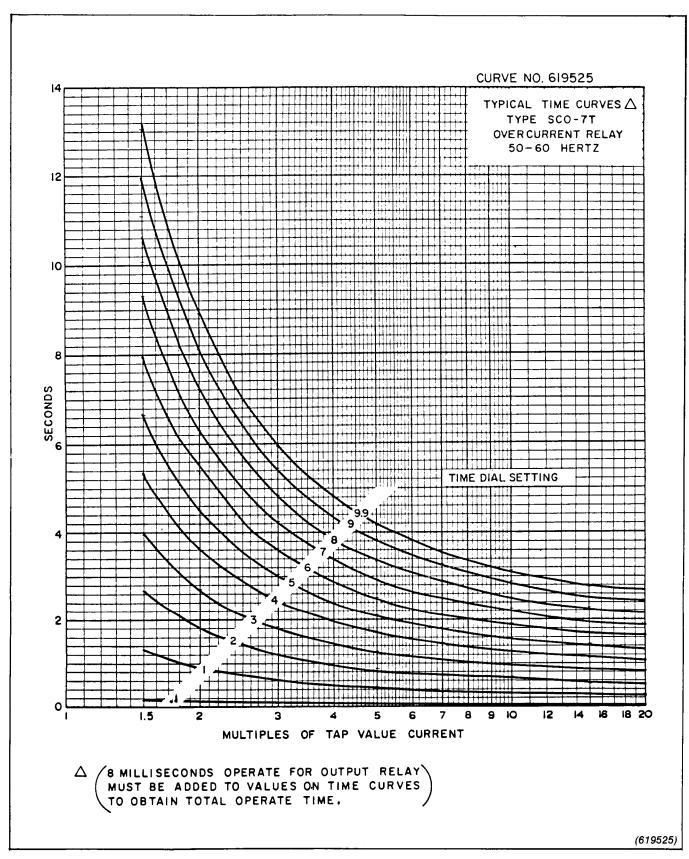


Fig. 10. Typical Time Curves of the Type SCO-7T Relay

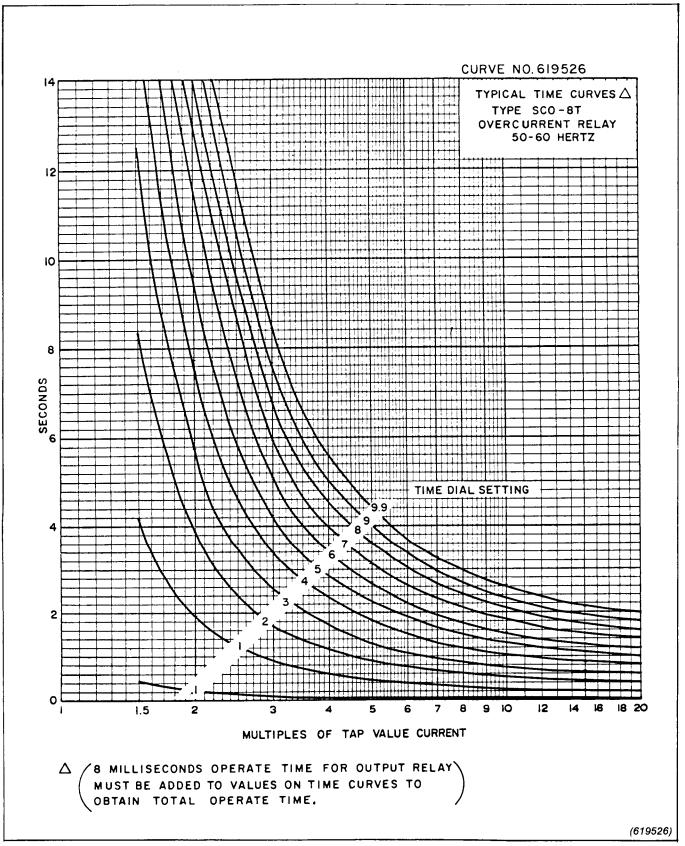


Fig. 11. Typical Time Curves of the Type SCO-8T Relay

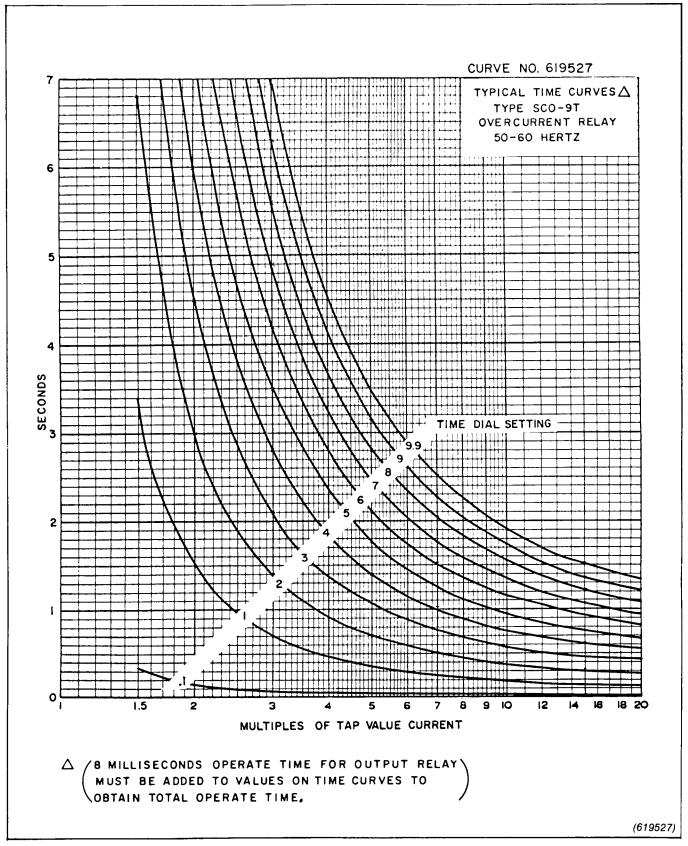


Fig. 12. Typical Time Curves of the Type SCO-9T Relay

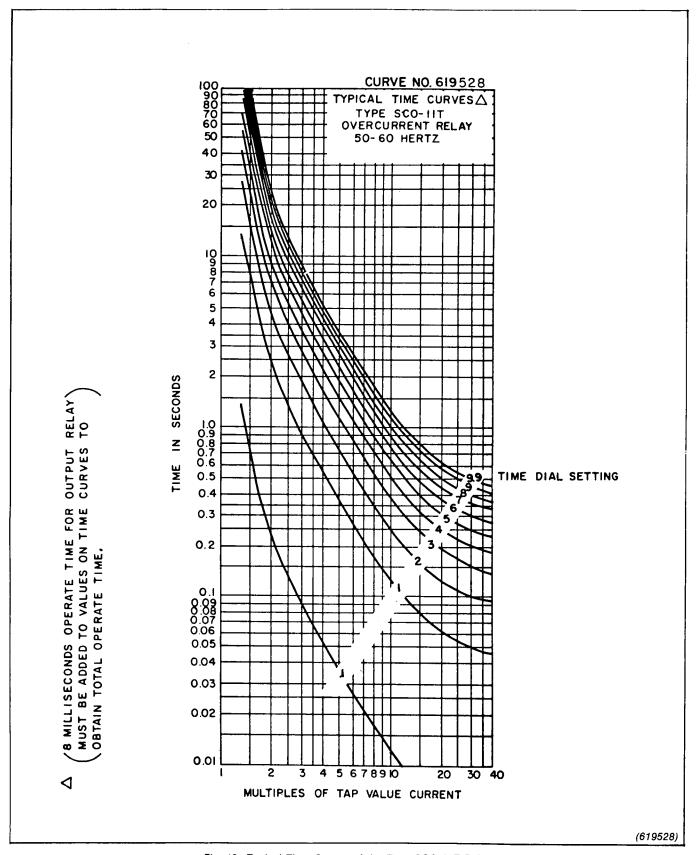


Fig. 13. Typical Time Curves of the Type SCO-11T Relay

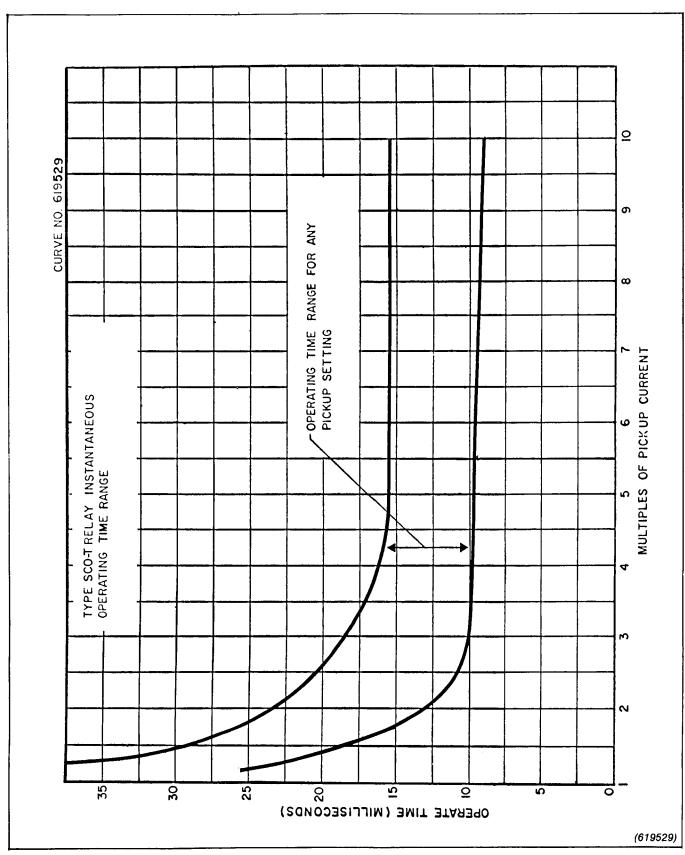


Fig. 14. Typical Time Curves of Type SCO-T Relay Instantaneous

## **INSTANTANEOUS CHARACTERISTICS**

The time vs. current characteristics are shown in Figure 14. These characteristics give the trip time when the indicated multiples of instantaneous pickup current are applied to the relay. 8 milliseconds inst. relay pickup time must be added to this curve for total time of the SCO-T instantaneous.

## TRIP CIRCUIT

The SCO-T relay energizes the breaker trip coil by means of an output contact. This contact will safely carry 30 amperes on a 250 dc system, or less, long enough to trip a circuit breaker (10 cycles). If the trip current requirement exceeds 30 amperes an auxiliary relay should be used and connected so that tripping current is not conducted through the output contact. A 52a contact, or similar contact, should be used to interrupt the trip coil current. Refer to the external scheme Figure 4 for proper trip connections.

## SURGE WITHSTAND CAPABILITY

Withstand SWC test per ANSI Standard C37.90A.

## **DIMENSIONS**

See Figure 20 for outline dimensions.

#### WEIGHT

Single Phase SCO-T Approximately 8 lbs. 6 ozs. (3.8 kilograms).

## **TEMPERATURE RANGE**

-20°C to +55°C chassis ambient (outside the relay case) without departure from the +25°C operating accuracy by more than  $\pm 5$ %.

-30°C to +70°C chassis ambient (outside the the relay case) without failure and with no more than 5% additional timing departure. Continuous current ratings must be derated at temperatures above +55°C.

## **FREQUENCY**

The typical frequency characteristics of the SCO-T relay are shown in Figure 15.

## **HARMONIC RESPONSE**

The typical response of the SCO-T relay to harmonics is shown in Figure 16.

## RESET TIME

The reset time of the SCO-T relay circuitry is less than 50 milliseconds, and the reset of the output relays is approx. 25 milliseconds for a total reset time at 75 milliseconds max.

## **OVERTRAVEL TIME**

The typical overtravel characteristics of the SCO-T relay is shown in Figure 17.

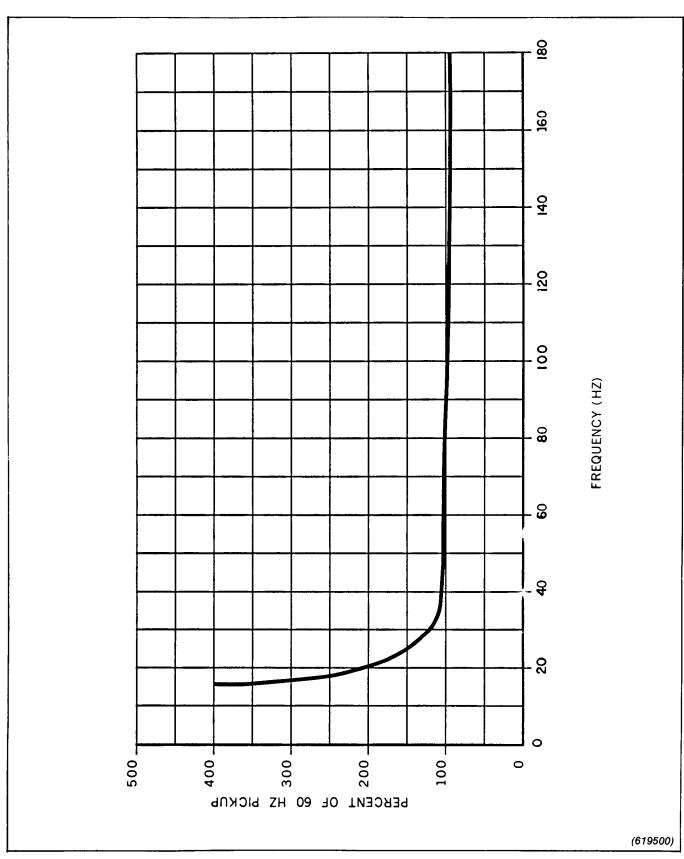


Fig. 15. Typical Frequency Characteristic of the Type SCO-T Relay

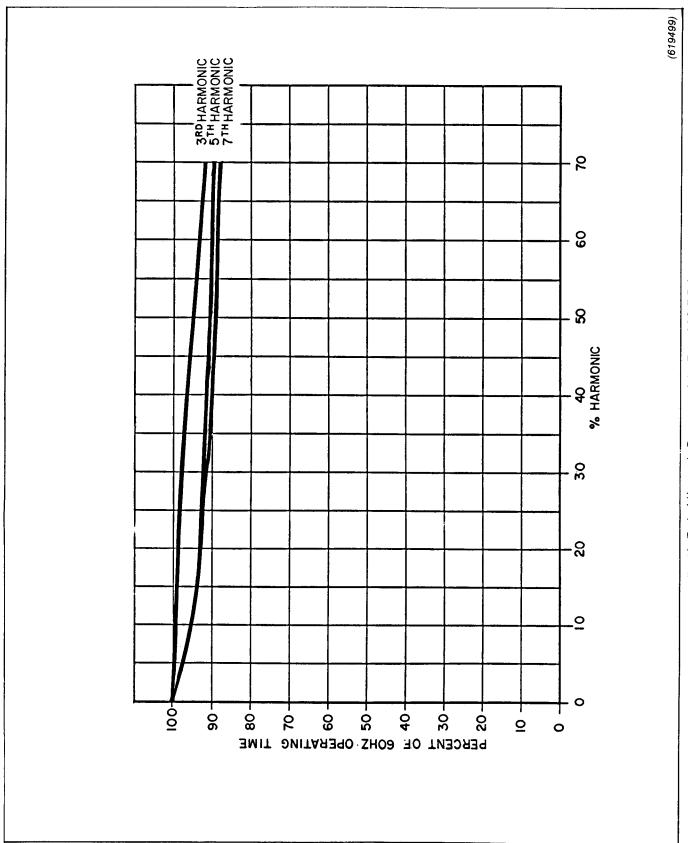
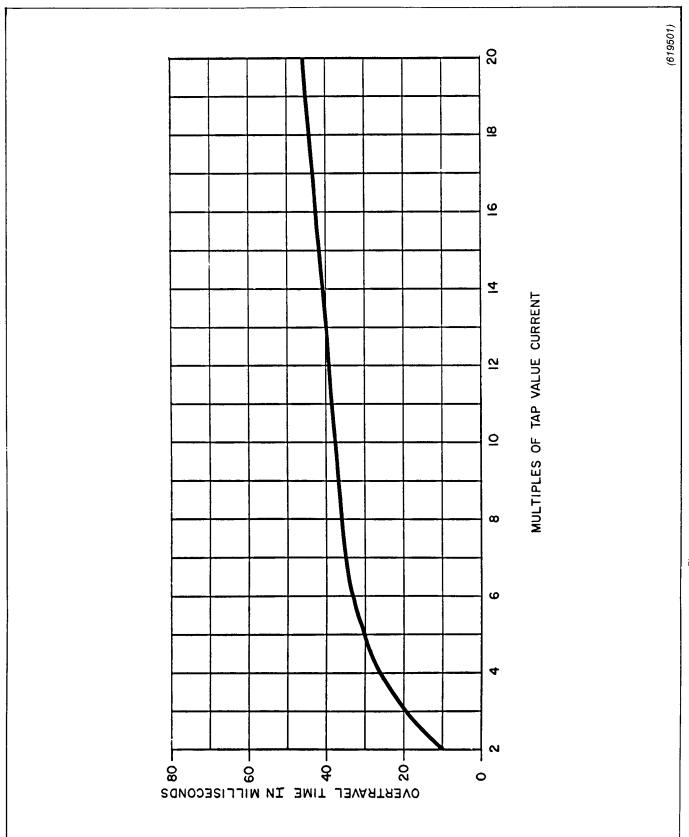


Fig. 16. Typical Harmonic Response of the Type SCO-T Relay





## TABLE I ENERGY REQUIREMENTS (60 HERTZ)<sup>1</sup>

## TYPE SCO-T RELAY WITH INSTANTANEOUS TRIP CIRCUITRY

			BURDENS AT TAP VALUE CURRENT			BURDENS IN OHMS'			
TAP	CON- TINUOUS RATING (AMPERES)	ONE SECOND RATING <sup>2</sup> (AMPERES)	R OHMS	X OHMS	Z OHMS	AT 3 TIMES TAP VALUE CURRENT	AT 10 TIMES TAP VALUE CURRENT	AT 20 TIMES TAP VALUE CURRENT	
0.5	1.6	44	12.4	0	12.4	3.78	2.32	2.08	
1.0	3.3	44	3.0	0	3.0	0.96	0.62	0.58	
1.5	4.9	185	1.29	0	1.29	0.41	0.27	0.26	
2.0	6.5	185	0.73	0	0.73	0.25	0.17	0.17	
2.5	8.1	185	0.48	0	0.48	0.17	0.12	0.12	
3.0	9.8	185	0.32	0	0.32	0.12	0.09	0.08	
3.5	11.4	185	0.25	0	0.25	0.09	0.06	0.06	
4.0	13.0	185	0.19	0	0.19	0.07	0.05	0.05	
5.0	16.3	460	0.13	0	0.13	0.05	0.04	0.04	
6.0	19.5	460	0.09	0	0.09	0.04	0.03	0.03	
7.0	22.8	460	0.08	0	0.08	0.04	0.03	0.03	
8.0	25.0	460	0.06	0	0.06	0.03	0.03	0.03	
10	29.0	460	0.05	0	0.05	£.03	0.03	0.03	
12	29.0	460	0.04	0	0.04	მ.02	0.02	0.02	

<sup>&</sup>lt;sup>1</sup>Burdens are approximately 10% lower at 50 hertz.

<sup>&</sup>lt;sup>2</sup>Thermal capacities for short times other than 1 second may be c: conated on the basis of time being inversely proportional to the square of the current (i.e.  $K = I^2t$ )

## **SETTINGS**

## **TIME DELAY**

The overcurrent time delay settings can be defined either by tap setting and time dial setting or by tap setting and a specific time of operation at some current multiple of the tap setting (e.g. 4 tap setting, 2.6 time dial setting or 4 tap setting, 0.6 seconds at 6 times tap value current).

The connector screw on the terminal plate of the tap block makes connections to various turns on the input current transformer. By placing this screw in the various terminal plate holes, the tap desired can be set and the relay will respond to multiples of tap value currents in accordance with the various typical time-current curves.

## CAUTION

Since the tap block connector screw carries operating current, be sure that the screw is turned tight. In order to avoid opening the current transformer circuits when changing taps under load, connect the spare connector screw in the desired tap position before removing the other tap screw from the original tap position.

The time dial should be set to the desired setting on the two decade time dial thumbwheel switches on the front panel in accordance with the various typical time-current curves.

The time delay must be set to overide the normal conditions to which the relay can be subjected, such as motor starting current, cold load pickup, emergency circuit load and transformer inrush.

## 1. Differential protection

For small transformers and less important buses the SCO-T differential scheme can be used. A pickup setting above maximum load of any circuit connected to the bus, and a time delay setting for maximum fault current in excess of three times the primary circuit de time constant, will generally prove to be suitable.

## 2. Motor protection

For locked rotor protection, the pickup of the SCO-T is typically set at one half locked rotor

current, and the time delay is set to allow the motor to start without exceeding the allowable locked rotor time for the particular motor.

## 3. Circuit protection

A pickup setting of two times maximum circuit loading is typical for the phase relay. The circuit load may reach 5 times normal when reenergized after a long time. It may not drop below 2 times normal for approximately 7 seconds. The relay should not trip for this condition. This is the cold load pickup phenomenon and varies widely with the type of load

Devices farther away from the source than the SCO-T and located between the SCO-T and a fault should be allowed to clear the fault. For all currents seen by both devices, the SCO-T curve should be approximately 0.3 seconds above the total clearing time of the remote device. Where consideration to ct performance, fault current variation and relay accuracy a coordinating time equal to or less than 0.2 second plus breaker clearing time may be used. Ground relay pickup must be above the maximum residual load unbalance, including the effect of switching single phase laterals. A pickup setting corresponding to 0.4 of maximum phase load current is typical. The time curve must be above that of all devices farther away from the source than the SCO-T. This includes fuses and recloses even though they may respond to phase current only. 0.3 second coordinating time is adequate. Lower coordinating times may be used as described above.

Similar SCO characteristics curve shapes at a given system voltage level can generally be more efficiently co-ordinated than dissimilar curve shapes.

## **INSTANTANEOUS TRIP**

The instantaneous circuit should be set to the desired setting on the instantaneous tap multiplier potentiometer on the front panel (see CALIBRATION section). This section is in multiples of tap setting (e.g. with a tap setting of 4 amps. and an instantaneous multiple setting at 20 times, the instantaneous pickup setting will be 80 amps). The relay will respond to currents above this setting per typical time curve Figure 14.

The instantaneous unit is responsive to total current including dc component, and an allowance must be made in the setting to avoid overtripping. Normally a setting of 1.25 times the maximum symmetrical current for which the unit should not trip will provide an adequate margin to prevent undesired tripping due to dc offset.

If an instantaneous trip is not desired in a style relay where it is included, it can be removed from service by cutting out the instantaneous trip cutout jumper J2 located on the right side of the circuit module.

#### INSTALLATION

The relays should be mounted on switchboard panels or their equivalent in a location free from dirt, moisture, excessive vibration, corrosive fumes and heat. The maximum temperature outside the relay case should not exceed +55°C for normal operation (See CHARACTERISTICS for temperature range specifications).

Mount the relay vertically by means of the four mounting holes on the flanges for semi-flush mounting or by means of the rear stud or studs for projection mounting. Either a mounting stud or the mounting screws may be utilized for grounding the relay. External toothed washers are provided for use in the locations shown on the outline and drilling plan to facilitate making a good electrical connection between the relay case, its mounting screws or studs, and the relay panel. Ground wires are affixed to the mounting screws or studs as required for poorly grounded or insulating panels. Other electrical connections may be made directly to the terminals by means of screws for steel panel mounting or the terminal studs furnished with the relay for thick panel mounting. The terminal studs may be easily removed or inserted by locking two nuts on the stud and then turning the proper nut with a wrench. See Figure 20 for Outline and Drilling Plan. For detailed FT case information refer to I.L. 41-076.

#### ADJUSTMENTS AND MAINTENANCE

The proper adjustments to insure correct operation of this realy have been made at the factory. Upon receipt of the relay, no customer adjustments other than those covered under "SETTINGS" should be required.

## **ACCEPTANCE CHECK**

It is recommended that an acceptance check be applied to the SCO-T relay to verify that the circuits are functioning properly. The SCO-T test diagram shown in Figure 18 aids in test of the relay. Proper energization of the relay is also shown in this figure.

## A. Minimum Trip Current

Set the time dial at 0.1, the tap block at 1 amp. and the instantaneous trip potentiometer at maximum setting (40X). Apply current to the relay, starting with a current below the set pickup, and very gradually increase the current applied to 5% below pickup value. The relay should not trip (See characteristic curves for approximate timing). Increase current 5% above pickup value and the relay should trip. The timing indicator (light emitting diode) begins to light in a dim manner at approximately 1% below the pickup point and attains full brightness at the actual minimum pickup level (tap block setting). This same procedure may be used to check the minimum trip current at other tap block settings.

If a more accurate check is desired, an oscilloscope may be used to view the minimum pickup signal. This signal is present on terminal 12 of the sensing-trip module, and is also easily accessible on the top lead of the TIMING light emitting diode by pulling back the insulated sleeving and attaching the scope probe to this point. The current where this signal becomes a solid logic 0 (complete absence of any positive pulses) is the actual minimum pickup point.

## **B.** Time Curve

The time curve calibration points for the various types of relays are shown in Table II. With the time dial set to the indicated position, apply the currents specified by Table II (e.g. for the SCO-8T, 2 and 20 times tap value current) and measure the operating time of the relay. The operating times should equal those of Table II plus or minus 10%.

## C. Instantaneous Trip

High multiples of current may be involved in the following test, therefore, caution should be taken not to exceed the thermal limits specified under CHARACTERISTICS. Starting with the instantaneous trip potentiometer set at minimum, a procedure of raising the potentiometer and applying the desired pickup current should be tried until the instantaneous unit does not operate with the desired current applied (time delay trip may operate). The instantaneous unit setting should then be "backed down and tried" until it does operate with the desired current applied (instantaneous trip indicator operates). The instantaneous will then respond to currents above this setting per the typical time curve Figure 14. If testing the instantaneous trip at higher multiples of pickup where the instantaneous and time delay curves may overlap, the time dial setting should be

raised to the 9.9 setting to give maximum time delay time.

## D. Trip Indication

The time trip indicator should operate (orange) on time curve trip and be resettable (black) with the reset lever. The instantaneous trip indicator should operate (orange) on instantaneous trip and be resettable (black) with the reset lever.

## E. Test Trip Switch

The trip test switch, when pushed, should trip the breaker. (Note: No indication occurs on this trip). Note that connection through terminal (1) to Battery Negative through a trip coil must be provided for the trip test to operate.

At completion of the acceptance test return all settings to desired position.

**TABLE II** 

		LOW CUR	RENT TESTS	HIGH CURRENT TESTS			
RELAY TYPE	TIME DIAL POSITION	CURRENT APPLIED TIMES TAP VALUE	OPERATING TIME IN SECONDS	CURRENT APPLIED TIMES TAP VALUE	OPERATING TIME IN SECONDS		
SCO-2T	5.0	2X	.888	20X	.222		
SCO-5T	5.0	2X	33.5	10X	14.0		
SCO-6T	5.0	2X	2.42	20X	1.28		
SCO-7T	5.0	2X	4.50	20X	1.36		
SCO-8T	5.0	2X	9.66	20X	1.00		
SCO-9T	5.0	2X	7.50	20X	.675		
SCO-11T	5.0	2X	10.5	20X	.310		

(Note: 8 milliseconds pickup time for the T.D. relay must be added to the above operate times for total operate time of the SCO-T relay).

## **ROUTINE MAINTENANCE**

All relays should be inspected periodically and all settings and times of operation should be checked at least once every year or at such other intervals as may be indicated by experience to be suitable to the particular application.

## **CALIBRATION**

The proper adjustments to insure correct operation of the relay have been made at the factory and should not be disturbed after receipt by the customer. However, recalibration may be required if the adjustments or any components have

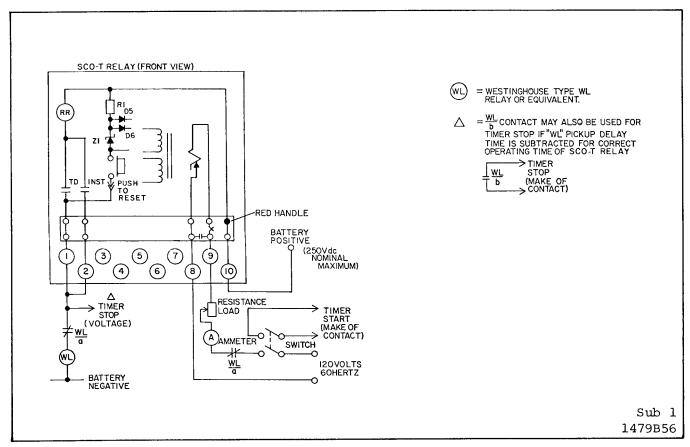


Fig. 18. Diagram of Test Connections for Type SCO-T Relay

been changed or SCO-T curve plug-in modules interchanged. This procedure should not be used until it is apparent that the relay is not in proper working order (See "Acceptance Check"). The SCO-T test diagram shown in Figure 18 aids in test of the relay. Proper energization of the relay is also shown in this figure.

## A. Minimum Trip Curve

Set the time dial at 0.1 setting, the tap block at a 1 amp. setting, and the instantaneous trip potentiometer at maximum setting (40X). Apply minimum current (1 amp.) to the relay (terminals 8 and 9). Adjust multi-turn trimpot R5 so that the relay will trip at tap value +1% and not trip at tap value -1%. Counterclockwise rotation of trimpot R5 increases the pickup point, (increases  $V_R$ ) and clockwise rotation of trimpot R5 decreases it. See Figure 2, front photograph, and Figure 6, module component location, for exact location of trimpot R5.

Note that the TIMING indicator (light emitting diode) begins to light in a dim manner at approximately 1% below the pickup and attains full brightness at the actual minimum pickup level.

An oscilloscope may be used to view the minimum pickup signal. This signal is present on terminal 12 of the sensing and trip module, and is also easily accessible on the top lead of the TIMING light emitting diode by pulling back the insulated sleeving and attaching the scope probe to this point. The current where this signal becomes solid logic 0 (complete absence of any positive pulses) is the actual minimum pickup point. This method is recommended for type SCO-5T and SCO-11T relays which have appreciable trip delays at pickup value.

#### **B.** Time Curve

Set the tap block at a 1 amp. setting, and set the instantaneous trip at maximum or above 20 times setting so it will not interfere with the time curve trip.

The time curve calibration points for the various types of relays are shown in Table II. Apply current per Table II for 10X or 20X pickup and adjust multi-turn trimpot R6 for the appropriate operating time ±2%. Clockwise rotation of trimpot R6 increases the trip time and counterclockwise rotation decreases it. See Figure 2, front photograph, and Figure 6, module component location, for exact location of trimpot R6. Apply current per Table II for 2X pickup and check for appropriate operating time  $\pm 7\%$ . Caution should be taken at these higher multiples of current not to exceed the thermal limits of the relay specified under CHARACTERISTICS. A contact to interrupt the input current upon trip of the relay is recommended in testing the SCO-T relay.

Note: Trimmer capacitor C19 has been factory set for correct operation of IC-6 and should not be readjusted. However, if IC-6 is ever replaced, capacitor C19 and trimpot R6 must both be adjusted with a SCO-11 curve module plugged in the relay to obtain correct compensation for IC-6 and correct SCO-11 curve 20X timing value.

## C. Instantaneous Trip

High multiples of current may be involved in the following test, therefore, caution should be taken not to exceed the thermal limits specified under CHARACTERISTICS. Starting with the instantaneous trip potentiometer R18 set at minimum, (fully counterclockwise) a procedure of raising the potentiometer and applying the desired pickup current should be tried until the instantaneous unit does not operate with the desired current applied (Time delay trip may operate). The

instantaneous unit setting should then be "backed down and tried" until it does operate with the desired current applied. (Instantaneous trip indicator operates). The instantaneous unit will then respond to currents above this setting per the typical time curve Figure 14. If testing the instantaneous trip at higher multiples of pickup where the instantaneous and time delay curves may overlap, the time dial setting should be raised to the 9.9 setting to give a maximum time delay time.

No other calibration is necessary other than desired changes in settings.

## TROUBLE SHOOTING

The components in the SCO-T relay are operated well within their ratings and normally will give long and trouble free service. However, if a relay has given indication of trouble in service or during routine checks, then using the internal schematic Figure 3, component location Figures 5 and 6, and the theory of operation the faulty component, connection, or circuit can be identified.

Voltage levels for "0" and "1" logic states in the theory of operation are:

Logic "0" is equivalent to less than 1 Vdc positive.

Logic "1" is equivalent to 5 to 11 Vdc positive.

For those users not generally acquainted with circuit notation or with device symbols of those components used in the SCO-T drawings, it is recommended that a copy of Westinghouse Instruction Leaflet I.L. 41-000.1 entitled, "Symbols for Solid State Protective Relaying" be consulted.

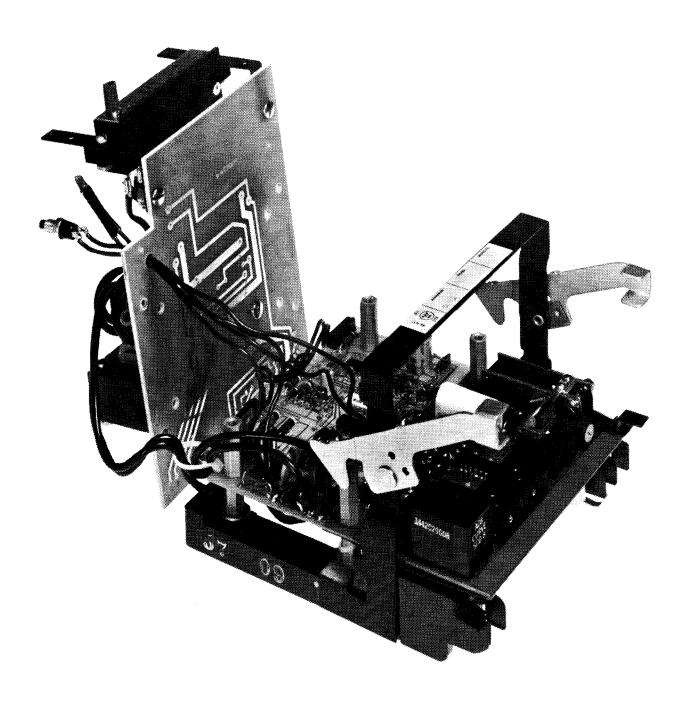


Fig. 19. Disassembly of Type SCO-T Relay

The SCO-T relay can easily be disassembled to gain accessibility to all components for ease in trouble shooting. The following procedure should be followed to mechanically detach and slide back the top transformer module when accessibility to components on the bottom module is desired (reference Figure 19):

- 1. Remove the two nameplate screws.
- 2. Remove both the tap block screw and spare tap screw.
- 3. Slide back rear retaining ring on TIMING light emitting diode snap bushing (onto wires), and push light emitting diode back through panel.
- 4. Unscrew shield guard from trip test switch (counterclockwise rotation). Front panel is now free to remove.
- 5. Remove the four screws holding the top module to posts.
- 6. Slip the wire tie, which holds the leads in the rear, up over the left rear post.
- 7. Slide the top module backwards for accessibility to components on bottom module.

Reassembly of the relay is accomplished by reassembling everything disassembled in steps 1 through 7 above in reverse order (7 through 1). Reposition intermodule connecting lead wires in rear of relay back to original routing.

## **RENEWAL PARTS**

Repair work can be done most satisfactorily at the factory. However, interchangeable parts can be furnished to the customers who are equipped for doing repair work. Internal Schematic Figure 3 contains a complete list and description of the components for renewal parts. When ordering parts, always give complete nameplate data and appropriate Westinghouse style numbers.

## **PLUG-IN CURVE MODULES (IC-1)**

Plug-in curve modules are available to change the particular style and time-overcurrent characteristic curve of the relay. The time curve module is a 24 pin plug-in module containing the specific circuitry and components for each particular curve style. There are seven different curve module styles corresponding to the SCO-2, SCO-5, SCO-6, SCO-7, SCO-8, SCO-9 and SCO-11 curves. This module plugs into the 24 pin socket on the sensing-trip module and is visible to the front of the relay through a window in the front panel. There the front label on the module completes the last three digits of the style of the relay (printed on the front panel), and also shows which curve the relay is set for i.e. "SCO-2 curve". Thus, changing this module automatically changes the style of the relay.

When changing plug-in curve modules, the relay should be recalibrated for minimum pickup and time curve specifications per the Calibration Section of this instruction leaflet.

The following are the style numbers of the plug-in curve modules available:

Relay Type	Curve Module	Time Curve	Curve Module Plug-In Style
SCO-2T	A02	Short	1442C29G02
SCO-5T	A05	Long	1442C29G05
SCO-6T	A06	Definite	1442C29G06
SCO-7T	A07	Moderately Inverse	1442C29G07
SCO-8T	A08	Inverse	1442C29G08
SCO-9T	A09	Very Inverse	1442C29G09
SCO-11T	A11	Extremely Inverse	1442C29G11

Consult Type SCO Time Curve Plug-in Modules Instruction Leaflet I.L. 41-110.2 for further information on SCO-T plug-in curve modules.

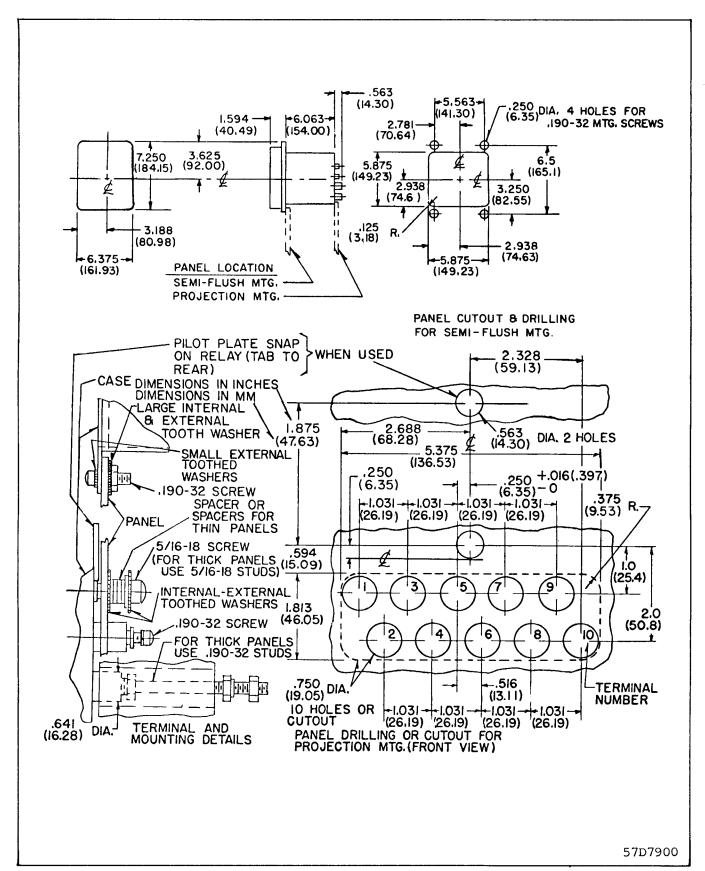


Fig. 20. Outline and Drilling Plan for Type SCO-T Relay Single Phase in FT-11 Case

## WESTINGHOUSE ELECTRIC CORPORATION RELAY-INSTRUMENT DIVISION NEWARK, N. J.

to sense current level above the setting and nor-

mally is used to trip a circuit breaker to clear

faults. A wide range of characteristics permit

applications involving coordination with fuses,

reclosers, cold load pickup, motor starting, or es-

The following describes typical applications of

sentially fixed time applications.



## OPERATION . MAINTENANCE INSTALLATION .

# INSTRUCTIONS

## TYPE SCO-T SOLID STATE SINGLE PHASE **OVERCURRENT RELAY**

CAUTION: It is recommended that the user become acquainted with the information in this instruction leaflet before energizing the equipment. Failure to observe this precaution may result in damage to the equipment.

## **APPLICATION**

The SCO-T relay is a single phase solid state non-directional time over-current device. It is used

The SCO-T rel	lay is a single le over-current	t device. It is used	the SCO-T Relay:
RELAY TYPE SCO-2T	CURVE MODULE A02	TIME CURVE Short	TYPICAL APPLICATIONS  1) Differential protection where saturation of current transformers is not expected, or where delayed tripping is permissible.  2) Overcurrent protection, phase or ground, where coordination with downstream devices is not involved and 2 to 60 cycle tripping is allowable.
SCO-5T	A05	Long	Motor locked rotor protection where allowable locked rotor time is approximately between 10 and 70 seconds.
SCO-6T	A06	Definite	Overcurrent protection where coordination with downstream devices is not involved and SCO-2T is too fast. The operating time of this relay does not vary greatly as current level varies.
SCO-7T	A07	Moderately Inverse	1) Overcurrent protection where coordination with other devices is required, and generation varies.
SCO-8T	A08	Inverse	2) Backup protection for relays on other circuits.
SCO-9T	A09	Very Inverse	- Houghla looked rotor
SCO-11T	A11	Extremely Inverse	<ol> <li>Motor protection where allowable locked rotor time is less than 10 sec.</li> <li>Overcurrent protection where coordination with fuses and reclosers is involved, or where cold load pickup or transformer inrush are factors.</li> </ol>

All possible contingencies which may arise during installation, operation, or maintenance, and all details and variations of this equipment do not purport to be covered by these instructions. If further information is desired by purchaser regarding his particular installation, operation or maintenance of his equipment, the local Westinghouse Electric Corporation representative should be contacted.

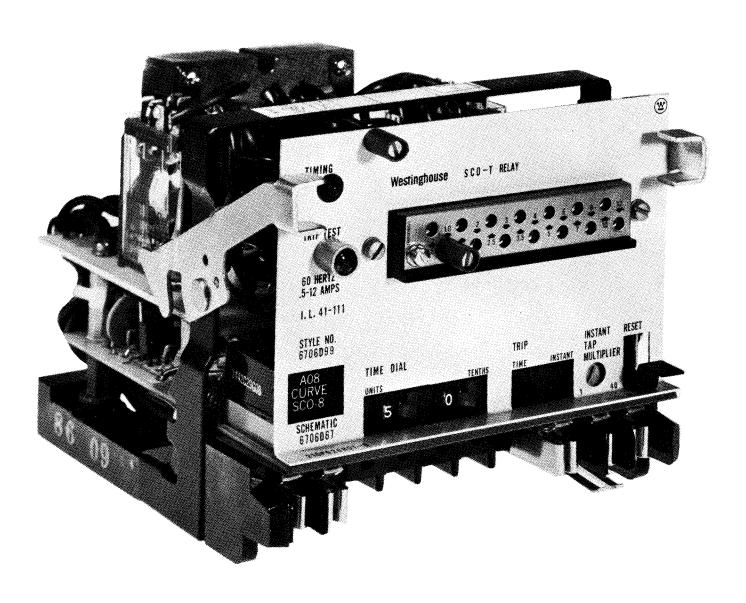


Fig. 1. Type SCO-T Relay-Front Left Side View

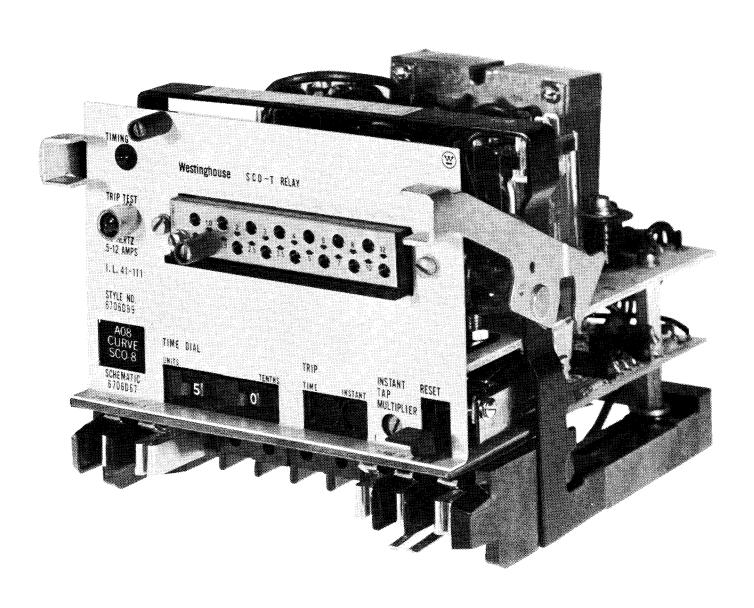


Fig. 2. Type SCO-T Relay-Front Right Side View

The SCO-T relay is equipped with an instantaneous trip feature with separate trip output to provide high speed tripping for high current faults.

Instantaneous trip units can be applied effectively where wide variations in fault currents occur for different fault locations, but have limited applications where wide variations in fault currents occur for a fixed fault location. It responds to total current and must be set to include the effect of dc current and to override the conditions that should be ignored such as transformer inrush, motor locked rotor, and faults outside of the desired trip zone.

Independent contact trip outputs and separate indication are provided for the instantaneous and time delay tirp outputs. No indication occurs unless there is current flow in the trip circuit. Indicator reset is accomplished manually.

The relay is self contained in that the power supply for the solid state logic is derived from the current transformer. There is no continuous drain on the tripping battery.

See SETTINGS Section for further application data.

## CONSTRUCTION

The SCO-T relay is a static relay consisting of 2 printed circuit modules, a time curve plug-in module, and a front panel assembly, packaged in a FT-11 case. For detailed information on the flexitest case, referred to I.L. 41-076.

The photographs in Figures 1 and 2 show the front left and front right view of the SCO-T reay removed from the case.

All of the circuitry suitable for mounting on printed circuit boards is contained on the two modules horizontally mounted on posts behind the front panel. The top module contains the transformer and "front-end" circuitry and the trip output relays for the SCO-T while the bottom module contains the power supply, information sensing, curve shaping, tripping and indication circuitry, as well as the plug-in curve module. Terminals for current input and trip output are located on the rear of the case, and all inputs and outputs pass through the FT switchjaws on the lower front part of the relay, below the front panel. The front panel, in addition to showing all pertinent style and setting information, has the minimum pickup indicator and the trip test switch located on the upper left-hand side.

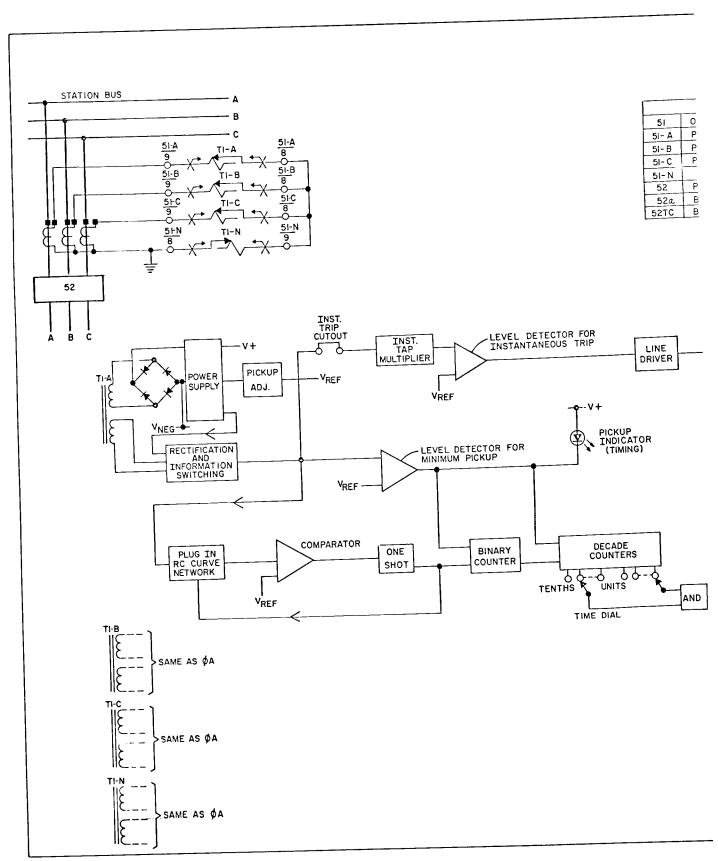
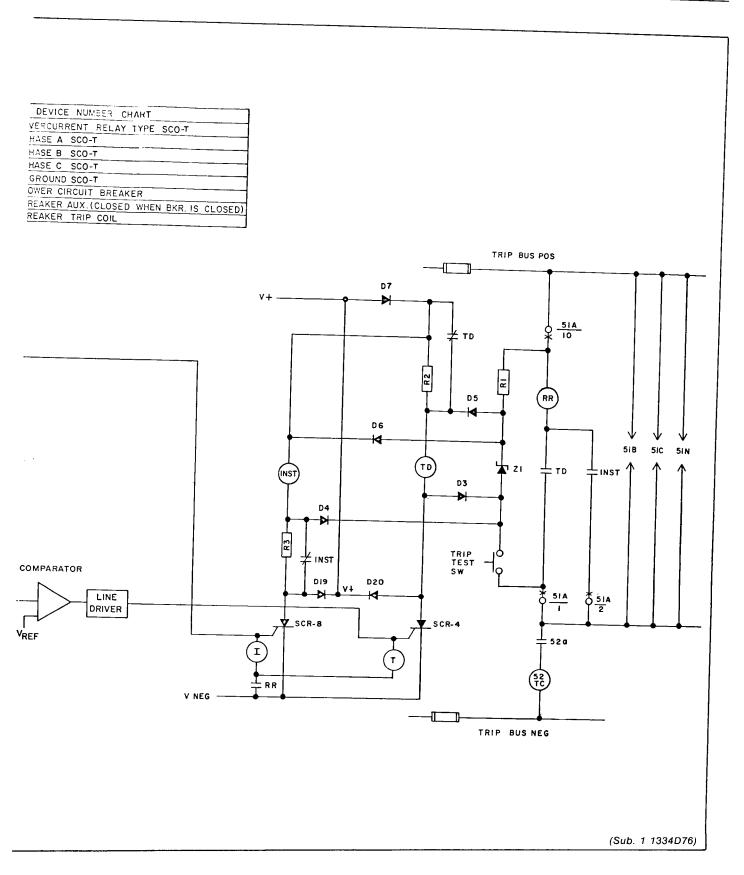


Fig. 4. SCO-T E



ternal Schematic

# PRINTED CIRCUIT MODULES

Following is a description of the printed circuit modules used in the SCO-T relay. Refer to the internal schematic shown in Figure 3. This schematic contains a detailed scheme for understanding of the circuitry and a complete list and description of the components for renewal parts.

For those users not generally acquainted with circuit notation or with device symbols of those components used in the SCO-T drawings, it is recommended that a copy of Westinghouse instruction leaflet I.L. 41-000.1 entitled "Symbols for Solid State Protective Relaying" be consulted.

# TRANSFORMER MODULE

Component Location Figure 5.

The transformer module, mounted at the top of the relay, contains the current transformer for obtaining the line current information and also supplies the power to operate the electronic circuits. A tap block with 14 taps covering the range of 0.5-12 amperes, is contained at the front of the module and extends through the front panel. A full-wave-bridge for the power supply winding and two diodes for the information winding of the transformer are also mounted on this circuit module to minimize wiring between the two modules. The two trip output relays and the reed relay for indicator pickup are also located on this module.

# SENSING & TRIP MODULE

Component location Figure 6.

The sensing and trip module is mounted at the bottom of the relay, beneath the transformer module. It contains the circuitry for power supply voltages V+ and VR, information sensing, curve shaping, tripping and indication. It also contains two decade thumb wheel switches for setting the time-dial, the potentiometer for setting the instantaneous trip, the instantaneous trip cut-out jumper, the reset lever assembly for resetting the time delay and instantaneous trip indicators, and the socket for the plug-in curve module. It also contains the two multi-turn trimpot calibration controls for setting minimum pickup and calibrating the curve.

# TIME CURVE MODULE (IC-1)

The time curve module is a 24 pin plug-in module containing the specific circuitry and components for each particular curve style. There are seven different curve module styles corresponding to the SCO-2, SCO-5, SCO-6, SCO-7, SCO-8, SCO-9 and SCO-11 curves. This module plugs into the 24 pin socket on the sensing-trip module and is visible to the front of the relay through a window in the front panel. There the front label on the module completes the last 3 digits of the style of the relay (printed on the front panel), and also shows which curve the relay is set for i.e. "SCO-2 curve". See Figure 1 front photograph and Figure 6 for exact location. For further information on time curve modules see Plug-in Curve Modules section in Renewal Parts of this instruction leaflet and also I.L. 41-110.2 instruction leaflet for Type SCO Time Curve Plug-in Modules.

# FRONT PANEL

The front panel, which is attached to the two tap block brackets on the transformer module, shows all pertinent style and setting information. It also has the minimum pick-up indicator and the trip test switch mounted on the upper left hand side. See Figure 1 for exact location.

# MINIMUM PICKUP INDICATOR TIMING

The minimum pickup indicator is mounted on the upper left-hand corner of the front panel. It consists of a light-emitting diode which is dimly lit at 99% tap value current and fully energized when current exceeds the minimum tap value. It is visible from the front of the relay which facilitates monitoring and testing. See Figure 1 for exact location.

# TRIP TEST SWITCH

The trip test switch is mounted on the upper left-hand side of the front panel. It consists of a push-to-test switch protected from accidental activation by a shield guard which requires a definite depression of the switch by some device that fits inside the guard, i.e. pencil, slender rod, etc. See Figure 1 for exact location. The trip test function derives its power from the station battery to pickup both the time delay and instantaneous trip relays simultaneously. Battery positive must be present on terminal 10 and a return path to battery negative must be provided from terminal 1 (through a trip coil with at least .5 amp loading).

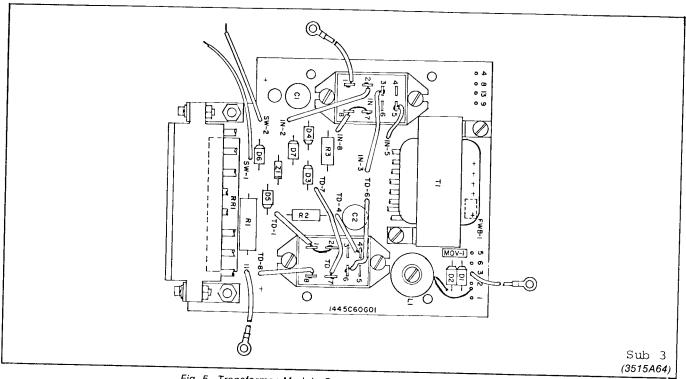


Fig. 5. Transformer Module Component Location Single Phase

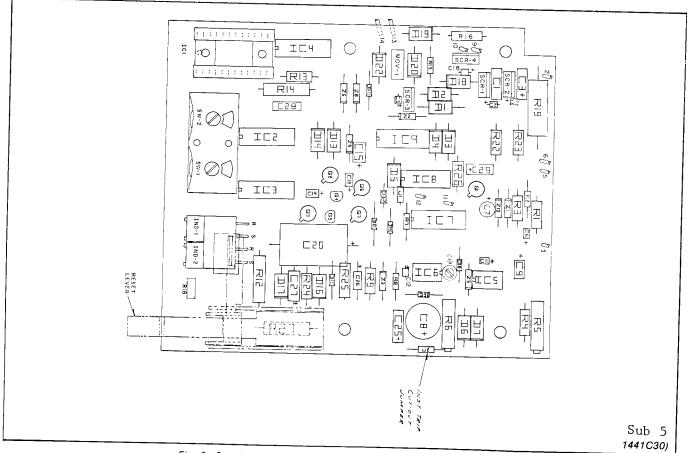


Fig. 6. Sensing-Trip Module Component Location Single Phase

# THEORY OF OPERATION

The basic operation of the SCO-T relay will be described with the aid of Figure 3 internal schematic 6706D67, and Figure 4 external scheme.

The SCO-T relay derives both its power and its sensing information from a single transformer. The type of transformer used is of the linear current transformer design consisting of a tapped primary winding and two secondary windings. The tapped primary winding allows 14 different pickup current settings from 0.5 to 12 amperes. One of the two secondary windings is a high current power supply winding (low number of turns) and the other one is a low current information winding (high number of turns). The circuit operation is based on the transformer ampere-turns balance principle between the primary and the secondary. Following each zero crossing of the line current, balancing of the primary ampere-turns is first achieved by the high current winding. During this time thyristors SCR-1 and SCR-2 are both off and the power supply regulator circuit is the only load imposed at the transformer's secondary. When the regulator reaches the specified regulated voltage based on zener diodes Z1 and Z10, transistor Q1 generates a signal to turn SCR-1 and SCR-2 on. Since these thyristors form a full wave bridge with diodes D1 and D2 on the transformer module, only the respective forward-biased thyristor will fire. Upon firing, an instant voltage drop is seen at the power supply winding output.

This action forces the diode bridge FWB-1 into a back-biased condition cutting off the power supply winding current flow. Balancing of the primary ampere-turns is, therefore, carried out in the low current, or information winding circuit. From this switching point the next zero crossing, the line current represented in voltage form is obtained across the burden resistor R19. When the line current experiences the next zero-crossing the thyristor is turned off automatically, again allowing the current flow in the power supply winding to charge the regulator circuit. The transformer is designed to allow a large enough current flow in the power supply winding at the pickup level so that the regulated voltage can be established very quickly. Once the regulated supply voltage is obtained, the subsequent replenishment uses only the very initial portion of each half cycle of the current. Therefore, the flux build-up due to the power supply replenishment is very low and the design is capable of providing a linear current information transfer up to 40 times pickup current.

The line current information obtained across burden resistor R19 in voltage form is then utilized using the technique of RC approximation and digital time multiplication for time-current curve sensing. The time current curves generated by this design are closely matched to the ones presently obtained from the electromechanical induction disc type relays. This technique utilizes a short, precision time-constant network for timecurrent curve shaping, and then uses digital counting and decoding techniques to provide time multiplication and precision time dial section. This has an advantage over a straight RC approximation scheme since long delay times are required at low multiples of pickup current. Component leakage and other design factors that make the straight RC network type of timing unattractive and complicated are not considered a problem in this digital approach. Thus, the information across resistor R19 is fed through transistor Q4 to this precision multi-branch RC network housed in the plug-in curve module IC-1. Depending upon the degree of inverseness of the desired time-current curve, the number of RC branches may vary from 2 to 4 branches. Each RC branch contains a first order RC circuit with a time-constant different from other branches. The branches are then combined to give a common weighted output. The weighted RC output is then compared with the reference VR by IC-6. This operational amplifier maintains a closed-loop operation through Z5 and D8 before the equivalent voltage of the RC network reaches the reference level V<sub>R</sub>. This reference level is set at the minimum pickup condition through the comparator IC-8 (pin 2 output) and potentiometer R5. Once this VR reference level is exceeded, IC-6 outputs a negative-going signal which triggers the one-shot circuit (IC-5). The one-shot signal, which has a pulse width adjusted to supply the proper definite delay time (poteniometer R6), resets the multi-branch RC network by turning transistor Q4 off, through Q5 and Q6, and by turning Q7 on to discharge the RC capacitors.

The one-shot signal also advances the binary counter circuit IC-4. This counter, which is enabled (logic 0 on pin 11) when the input current is above the minimum pickup level and reset or kept inactive when below minimum pickup level (MPU IC-8 pin 2), counts the negative going signals from the one-shot output. When the correct count is attained, up to 2<sup>12</sup> power or 4096 counts, depending upon which binary output is used per respective curve connection in IC-1, the counter output is inverted by comparator IC-9 (pin 13) and then drives the two timedial decade counter/decorder circuits, IC-3 and IC-2. These two counters, one for tenth timedial positions and one for unit time-dial positions, are connected to a dual decade thumbwheel switch to provide ninety-nine distinct time-dial settings, which means up to 99 count outputs from the binary counter IC-4. Thus, for example, if the 2<sup>10</sup>(1024) output of IC-4 is used, up to 210X time dial setting (from 1 to 99) actual counts of the RC network takes place before generation of a trip signal. These decade counters, as in the previous case of the binary counter IC-4, are kept inoperative and reset whenever the minimum pickup signal on pin 15 of IC-3 and IC-2 goes to a logic 1, indicating that the input current dropped below pickup level.

Thus, when the set time dial count has elapsed, a positive output occurs from both the decade counters. These are applied through the time dial switches to the cathode ends of D9 and D10, reverse biasing them. This allows the signal present on pin 8 of comparator IC-8 to now become a logic 1 (through R8) generating a trip signal (IC-8 pin 14). Prior to this, the signal on pin 8 of comparator IC-8 was kept at a logic 0 level by the shorting of this input, in accordance with the logic 0 outputs of IC-3 and IC-2, through either or both of diodes D9 and D10.

This trip signal is then applied through IC-9 D12 and Z6 to the base of Q3, turning it on. This, in turn, applies 2 distinct branch signals; one is through IC-9 and D18 to gate thyristor SCR-4, the second is through D16, C28 and R26 to IND-1, the time-delay trip indicator. Thus, with the turn on of SCR-4 the T.D. relay on the top module is energized and a trip output occurs between terminals 1

and 10 of the SCO-T relay. The turn on of the indicator can only occur when the reed relay RR picks up, concurrent with the flow of trip coil current. This happens when the normally open RR contact closes completing the path to, and allowing the indicator current to thereby flow to, power supply negative.

The trip of the breaker will interrupt the current input, and total reset of the relay circuitry occurs within 50 milliseconds plus an additional 15 to 20 milliseconds dropout time of the trip relay. Reset of the indicator is accomplished manually through use of the reset lever actuated from the outside of the case. This lever magnetically flips the indicator back to its reset state.

The instantaneous trip circuitry also derives its information from the voltage across resistor R19. This information is taken from the cathode side of diode D1, through the instantaneous trip cutout link jumper, to the level control and filter circuitry on the input of the instantaneous trip comparator, IC-8 (pin 6). This input is then compared with the minimum pickup reference level V<sub>R</sub> by IC-8. The potentiometer R18 allows a continuous range of setting from 1 to 40 times the minimum pickup tap setting of the relay. Once the V<sub>R</sub> reference level is exceeded, IC-8 (pin 1) outputs a negative-going instantaneous trip signal. This signal is then applied through IC-9 and Z8 to the base of Q2, turning it on. This, in turn, applies 3 distinct branch signals; one is through D15 and IC-7 to immediately seal-in the instantaneous input on IC-8 pin 6, the second is through R21 and D14 to gate thyristor SCR-8, thereby energizing the INST. relay, and the third is through D17 the IND-2, the instantaneous trip indicator. With the energization of the INST. relay a trip output occurs through similar paths as previously described when initiated by the time delay circuit.

Similarly to the time delay trip indicator, turn on of the instantaneous trip indicator can only occur when the reed relay RR turns on, and is concurrent with the flow of trip coil current.

# CHARACTERISTICS

#### RANGE

The SCO-T has taps covering the range of 0.5 to 12 amperes. The tap values are: 0.5, 1.0, 1.5, 2.0, 2.5, 3.0, 3.5, 4, 5, 6, 7, 8, 10 and 12 amperes.

Pickup accuracy  $\pm 5$  percent of tap value for all taps.

The instantaneous circuit has a range of 1 to 40 times the tap value selection with a continuously adjustable pickup.

# TIME-OVERCURRENT CHARACTERISTICS

The time vs. current characteristics are shown in Figures 7 to 13. These characteristics give

the trip time for the various time dial settings when the indicated multiples of tap value current are applied to the relay. 8 milliseconds T.D. relay pickup time delay must be added to these curves for total operate time of the SCO-T relay.

Timing accuracy  $\pm 10\%$  of the characteristics curve for any combination of time dial setting and tap value. Operating time repeatability  $\pm 2\%$  at 25°C. for any given time dial and tap setting.

**NOTE:** A higher percentage value may occur on the 0.1 time dial position when the SCO-T relay is suddenly energized due to angle of incidence and delay in power supply turn-on.

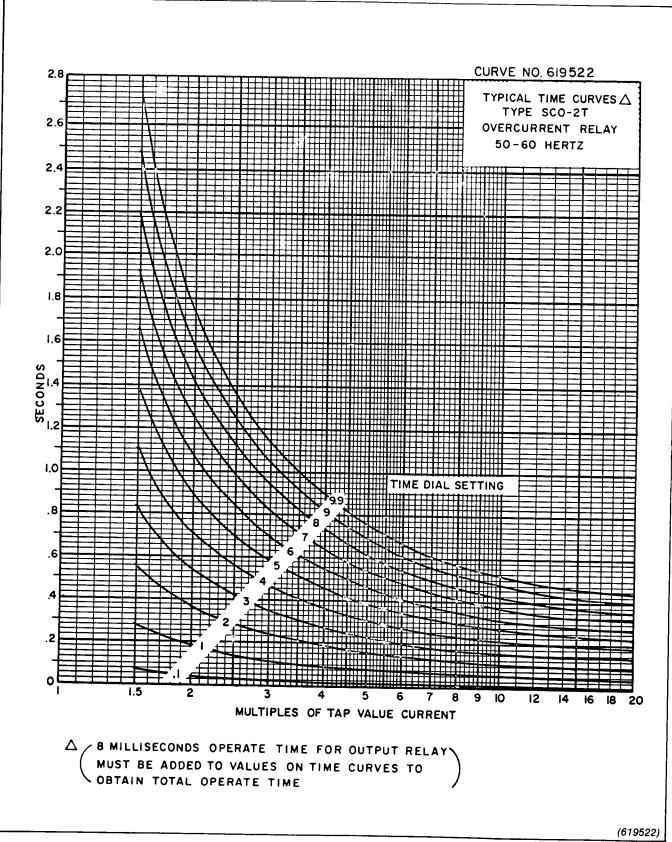


Fig. 7. Typical Time Curves of the Type SCO-2T Relay

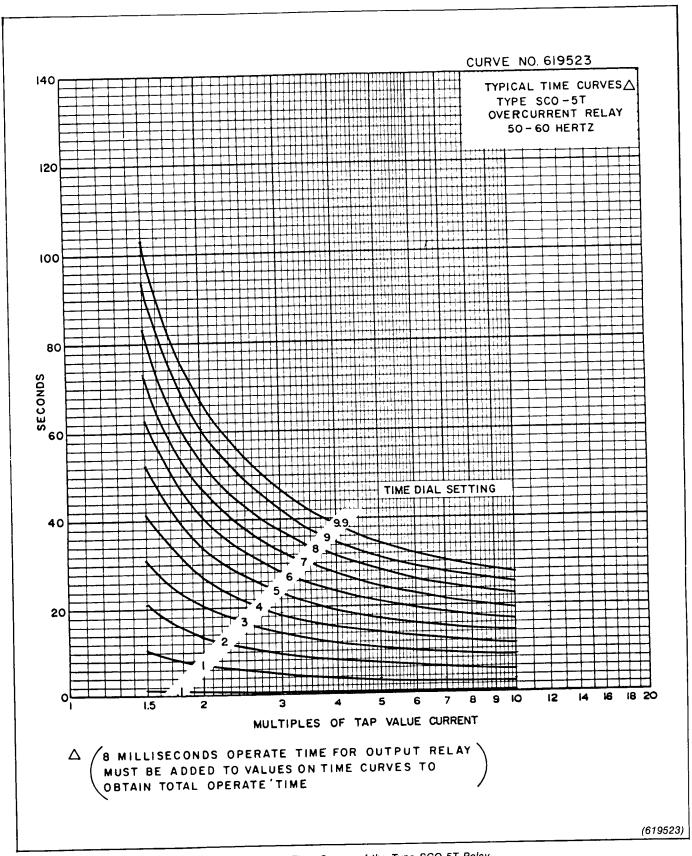


Fig. 8. Typical Time Curves of the Type SCO-5T Relay

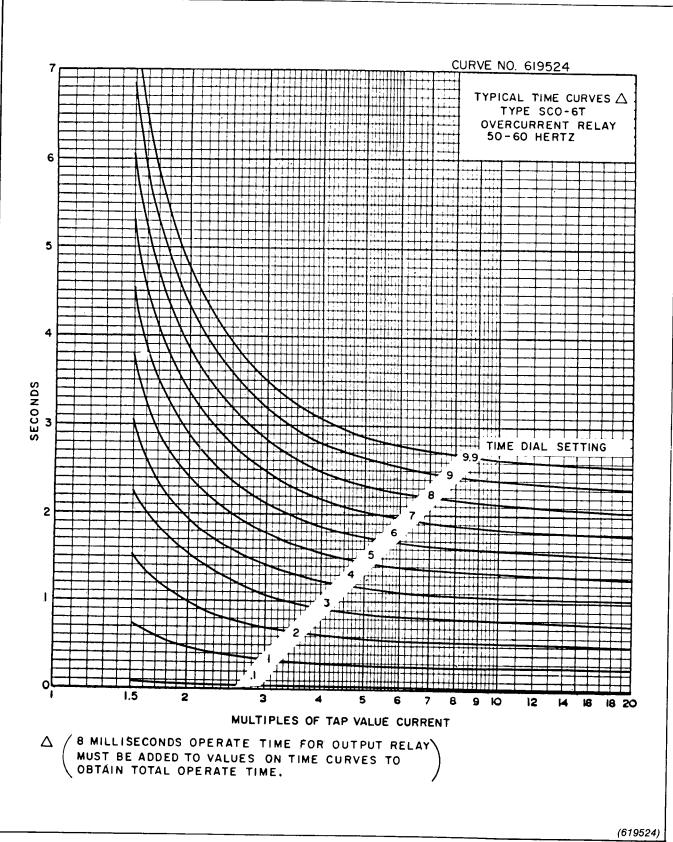


Fig. 9. Typical Time Curves of the Type SCO-6T Relay

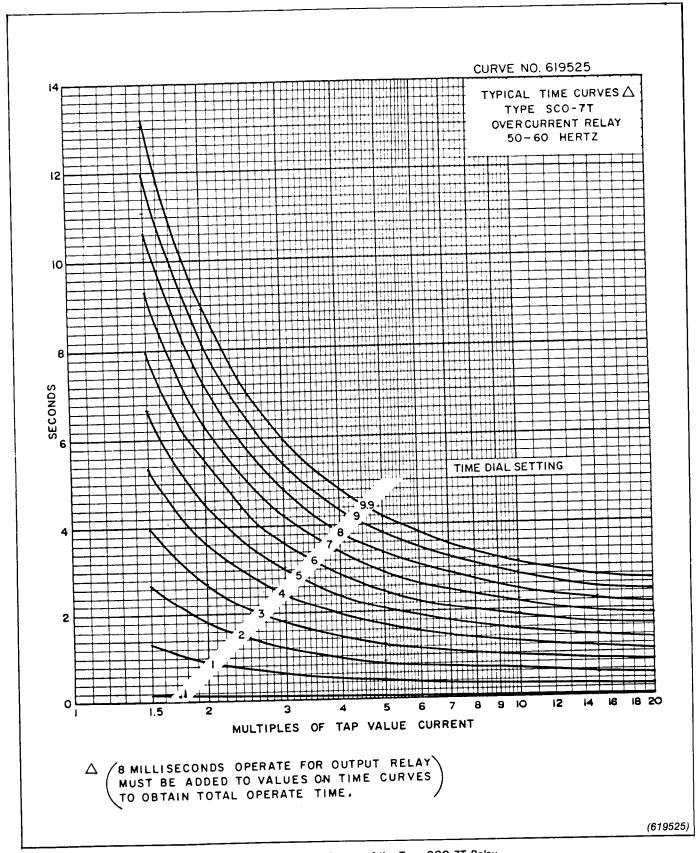


Fig. 10. Typical Time Curves of the Type SCO-7T Relay

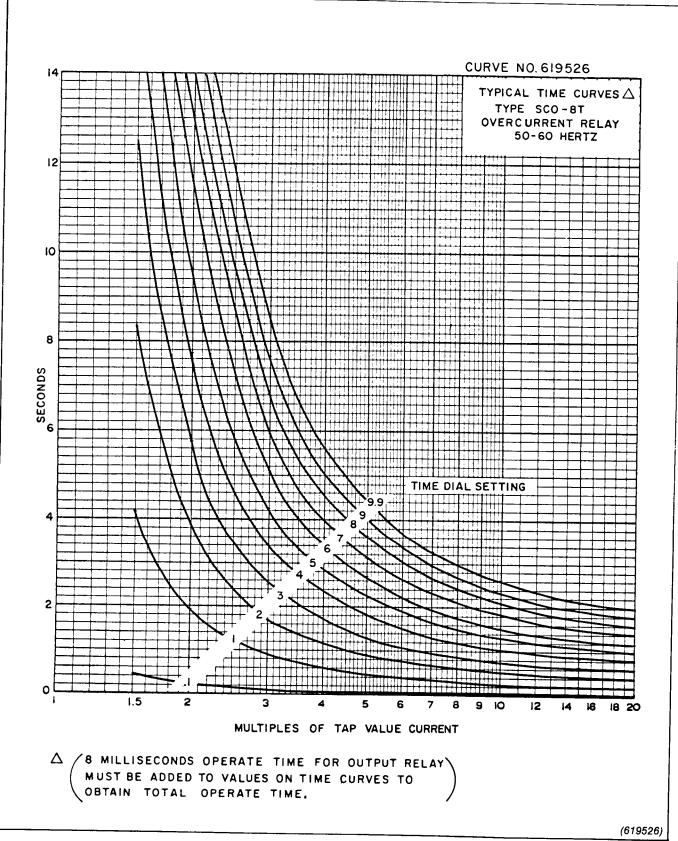


Fig. 11. Typical Time Curves of the Type SCO-8T Relay

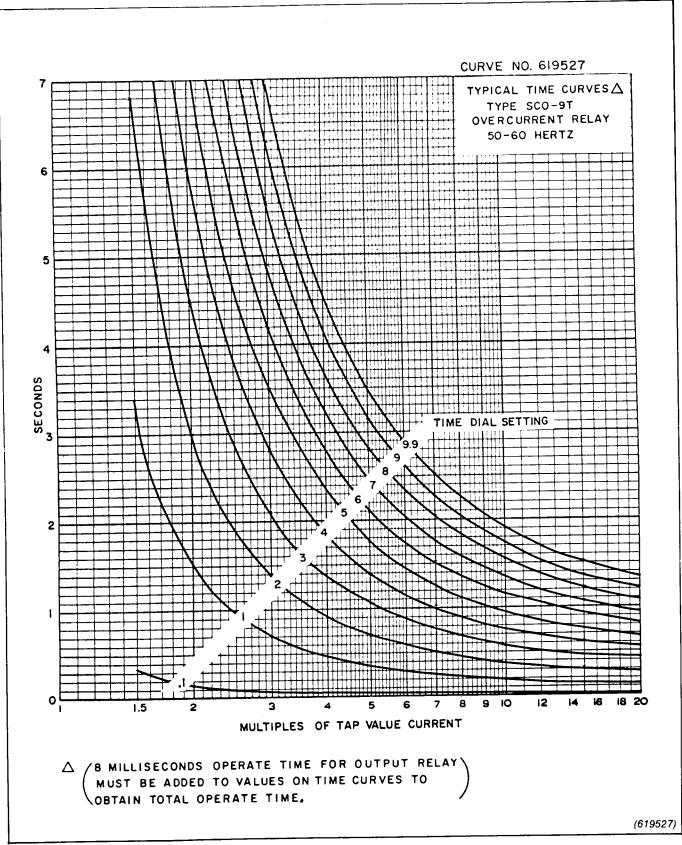


Fig. 12. Typical Time Curves of the Type SCO-9T Relay

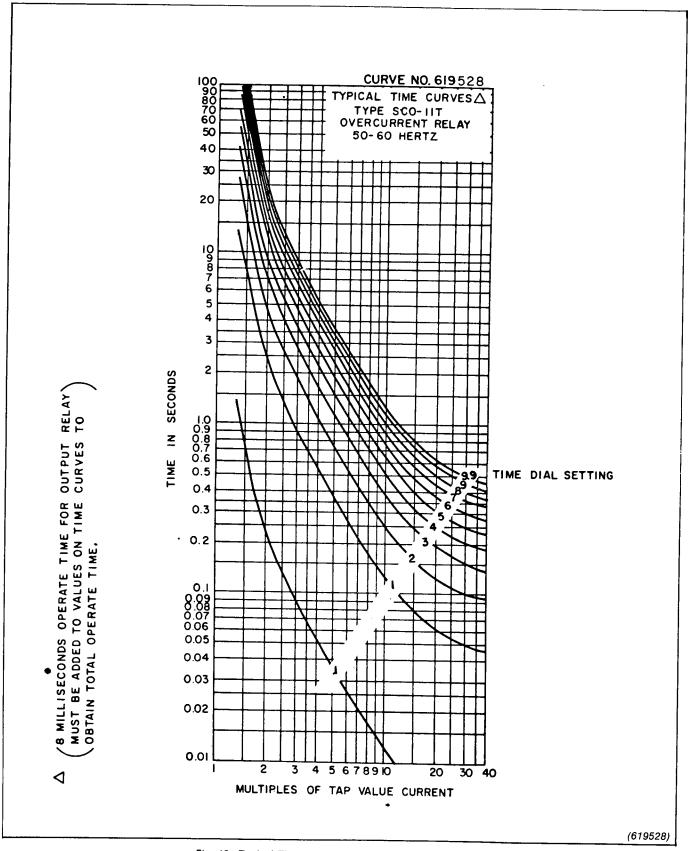


Fig. 13. Typical Time Curves of the Type SCO-11T Relay

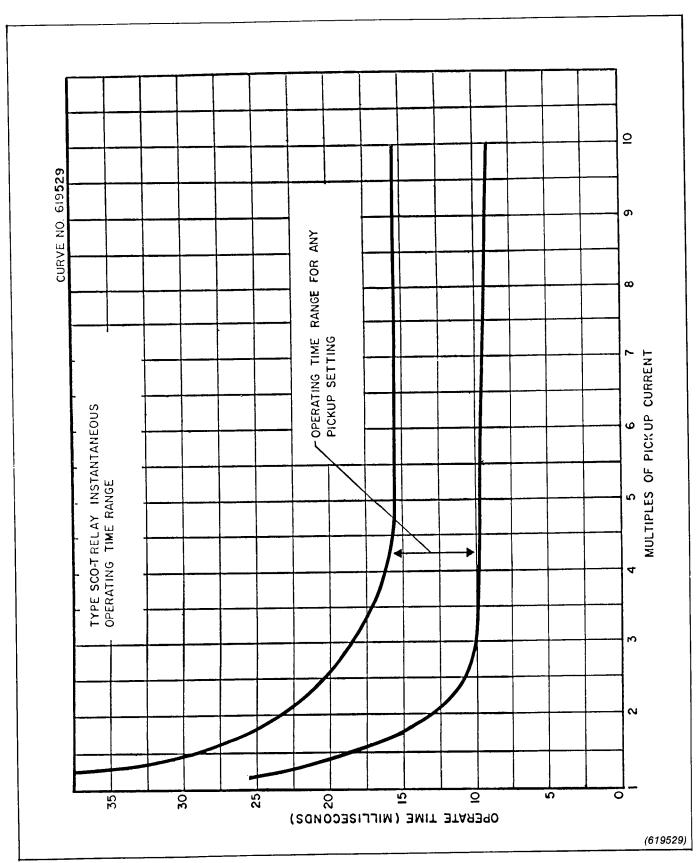


Fig. 14. Typical Time Curves of Type SCO-T Relay Instantaneous

# INSTANTANEOUS CHARACTERISTICS

The time vs. current characteristics are shown in Figure 14. These characteristics give the trip time when the indicated multiples of instantaneous pickup current are applied to the relay. 8 milliseconds inst. relay pickup time must be added to this curve for total time of the SCO-T instantaneous.

#### TRIP CIRCUIT

The SCO-T relay energizes the breaker trip coil by means of an output contact. This contact will safely carry 30 amperes on a 250 dc system, or less, long enough to trip a circuit breaker (10 cycles). If the trip current requirement exceeds 30 amperes an auxiliary relay should be used and connected so that tripping current is not conducted through the output contact. A 52a contact, or similar contact, should be used to interrupt the trip coil current. Refer to the external scheme Figure 4 for proper trip connections.

### SURGE WITHSTAND CAPABILITY

Withstand SWC test per ANSI Standard C37.90A.

#### **DIMENSIONS**

See Figure 20 for outline dimensions.

### WEIGHT

Single Phase SCO-T Approximately 8 lbs. 6 ozs. (3.8 kilograms).

## **TEMPERATURE RANGE**

-20°C to +55°C chassis ambient (outside the relay case) without departure from the +25°C operating accuracy by more than  $\pm 5$ %.

-30°C to +70°C chassis ambient (outside the the relay case) without failure and with no more than 5% additional timing departure. Continuous current ratings must be derated at temperatures above +55°C.

#### **FREQUENCY**

The typical frequency characteristics of the SCO-T relay are shown in Figure 15.

#### HARMONIC RESPONSE

The typical response of the SCO-T relay to harmonics is shown in Figure 16.

### **RESET TIME**

The reset time of the SCO-T relay circuitry is less than 50 milliseconds, and the reset of the output relays is approx. 25 milliseconds for a total reset time at 75 milliseconds max

### **OVERTRAVEL TIME**

The typical overtravel characteristics of the SCO-T relay is shown in Figure 17.

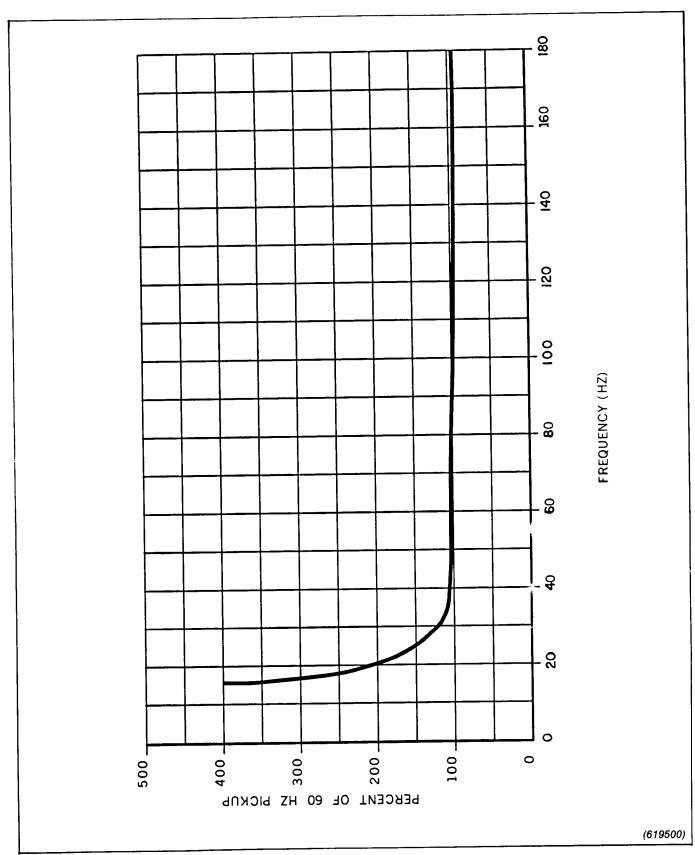


Fig. 15. Typical Frequency Characteristic of the Type SCO-T Relay

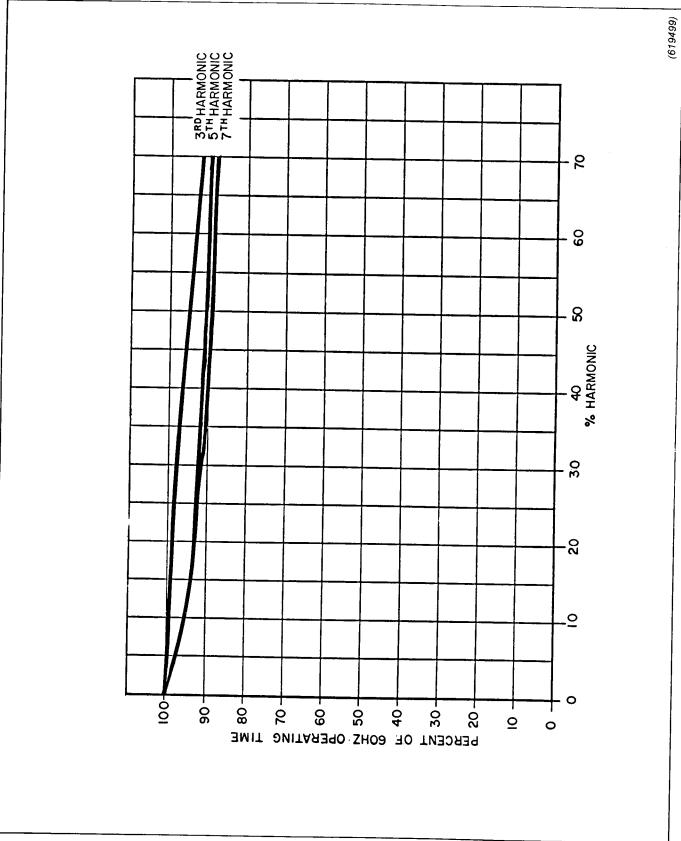
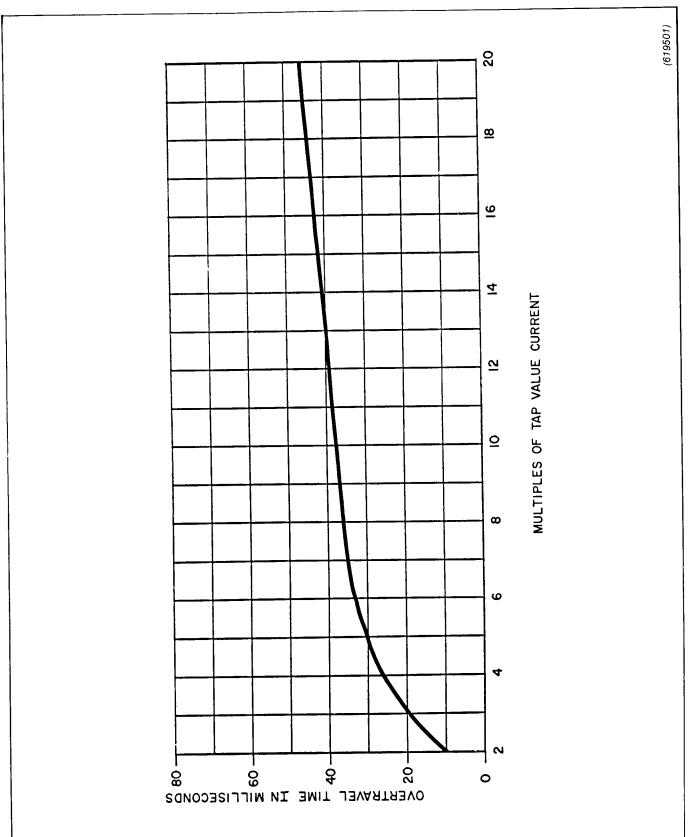


Fig. 16. Typical Harmonic Response of the Type SCO-T Relay





# TABLE I ENERGY REQUIREMENTS (60 HERTZ)<sup>1</sup>

# TYPE SCO-T RELAY WITH INSTANTANEOUS TRIP CIRCUITRY

			BURDENS AT TAP VALUE CURRENT			BURDENS IN OHMS <sup>1</sup>		
ТАР	CON- TINUOUS RATING (AMPERES)	ONE SECOND RATING <sup>2</sup> (AMPERES)	R OHMS	X OHMS	Z OHMS	AT 3 TIMES TAP VALUE CURRENT	AT 10 TIMES TAP VALUE CURRENT	AT 20 TIMES TAP VALUE CURRENT
0.5	1.6	44	12.4	0	12.4	3.78	2.32	2.08
1.0	3.3	44	3.0	0	3.0	0.96	0.62	0.58
1.5	4.9	185	1.29	0	1.29	0.41	0.27	0.26
2.0	6.5	185	0.73	0	0.73	0.25	0.17	0.17
2.5	8.1	185	0.48	0	0.48	0.17	0.12	0.12
3.0	9.8	185	0.32	0	0.32	0.12	0.09	0.08
3.5	11.4	185	0.25	0	0.25	0.09	0.06	0.06
4.0	13.0	185	0.19	0	0.19	0.07	0.05	0.05
5.0	16.3	460	0.13	0	0.13	0.05	0.04	0.04
6.0	19.5	460	0.09	0	0.09	0.04	0.03	0.03
7.0	22.8	460	0.08	0	0.08	0.04	0.03	0.03
8.0	25.0	460	0.06	0	0.06	0.03	0.03	0.03
10	29.0	460	0.05	0	0.05	0.03	0.03	0.03
12	29.0	460	0.04	0	0.04	0.02	0.02	0.02

<sup>&</sup>lt;sup>1</sup>Burdens are approximately 10% lower at 50 hertz.

<sup>&</sup>lt;sup>2</sup>Thermal capacities for short times other than 1 second may be calculated on the basis of time being inversely proportional to the square of the current (i.e.  $K = I^2t$ )

### **SETTINGS**

#### TIME DELAY

The overcurrent time delay settings can be defined either by tap setting and time dial setting or by tap setting and a specific time of operation at some current multiple of the tap setting (e.g. 4 tap setting, 2.6 time dial setting or 4 tap setting, 0.6 seconds at 6 times tap value current).

The connector screw on the terminal plate of the tap block makes connections to various turns on the input current transformer. By placing this screw in the various terminal plate holes, the tap desired can be set and the relay will respond to multiples of tap value currents in accordance with the various typical time-current curves.

#### CAUTION

Since the tap block connector screw carries operating current, be sure that the screw is turned tight. In order to avoid opening the current transformer circuits when changing taps under load, connect the spare connector screw in the desired tap position before removing the other tap screw from the original tap position.

The time dial should be set to the desired setting on the two decade time dial thumbwheel switches on the front panel in accordance with the various typical time-current curves.

The time delay must be set to overide the normal conditions to which the relay can be subjected, such as motor starting current, cold load pickup, emergency circuit load and transformer inrush.

# 1. Differential protection

For small transformers and less important buses the SCO-T differential scheme can be used. A pickup setting above maximum load of any circuit connected to the bus, and a time delay setting for maximum fault current in excess of three times the primary circuit dc time constant, will generally prove to be suitable.

# 2. Motor protection

For locked rotor protection, the pickup of the SCO-T is typically set at one half locked rotor

current, and the time delay is set to allow the motor to start without exceeding the allowable locked rotor time for the particular motor.

# 3. Circuit protection

A pickup setting of two times maximum circuit loading is typical for the phase relay. The circuit load may reach 5 times normal when reenergized after a long time. It may not drop below 2 times normal for approximately 7 seconds. The relay should not trip for this condition. This is the cold load pickup phenomenon and varies widely with the type of load.

Devices farther away from the source than the SCO-T and located between the SCO-T and a fault should be allowed to clear the fault. For all currents seen by both devices, the SCO-T curve should be approximately 0.3 seconds above the total clearing time of the remote device. Where consideration to ct performance, fault current variation and relay accuracy a coordinating time equal to or less than 0.2 second plus breaker clearing time may be used. Ground relay pickup must be above the maximum residual load unbalance, including the effect of switching single phase laterals. A pickup setting corresponding to 0.4 of maximum phase load current is typical. The time curve must be above that of all devices farther away from the source than the SCO-T. This includes fuses and recloses even though they may respond to phase current only. 0.3 second coordinating time is adequate. Lower coordinating times may be used as described above.

Similar SCO characteristics curve shapes at a given system voltage level can generally be more efficiently co-ordinated than dissimilar curve shapes.

# **INSTANTANEOUS TRIP**

The instantaneous circuit should be set to the desired setting on the instantaneous tap multiplier potentiometer on the front panel (see CALIBRATION section). This section is in multiples of tap setting (e.g. with a tap setting of 4 amps. and an instantaneous multiple setting at 20 times, the instantaneous pickup setting will be 80 amps). The relay will respond to currents above this setting per typical time curve Figure 14.

The instantaneous unit is responsive to total current including dc component, and an allowance must be made in the setting to avoid overtripping. Normally a setting of 1.25 times the maximum symmetrical current for which the unit should not trip will provide an adequate margin to prevent undesired tripping due to dc offset.

If an instantaneous trip is not desired in a style relay where it is included, it can be removed from service by cutting out the instantaneous trip cutout jumper located on the right side of the circuit module.

### **INSTALLATION**

The relays should be mounted on switchboard panels or their equivalent in a location free from dirt, moisture, excessive vibration, corrosive fumes and heat. The maximum temperature outside the relay case should not exceed +55°C for normal operation (See CHARACTERISTICS for temperature range specifications).

Mount the relay vertically by means of the four mounting holes on the flanges for semi-flush mounting or by means of the rear stud or studs for projection mounting. Either a mounting stud or the mounting screws may be utilized for grounding the relay. External toothed washers are provided for use in the locations shown on the outline and drilling plan to facilitate making a good electrical connection between the relay case, its mounting screws or studs, and the relay panel. Ground wires are affixed to the mounting screws or studs as required for poorly grounded or insulating panels. Other electrical connections may be made directly to the terminals by means of screws for steel panel mounting or the terminal studs furnished with the relay for thick panel mounting. The terminal studs may be easily removed or inserted by locking two nuts on the stud and then turning the proper nut with a wrench. See Figure 20 for Outline and Drilling Plan. For detailed FT case information refer to I.L. 41-076.

# **ADJUSTMENTS AND MAINTENANCE**

The proper adjustments to insure correct operation of this realy have been made at the factory. Upon receipt of the relay, no customer ad-

justments other than those covered under "SETTINGS" should be required.

### **ACCEPTANCE CHECK**

It is recommended that an acceptance check be applied to the SCO-T relay to verify that the circuits are functioning properly. The SCO-T test diagram shown in Figure 18 aids in test of the relay. Proper energization of the relay is also shown in this figure.

# A. Minimum Trip Current

Set the time dial at 0.1, the tap block at 1 amp. and the instantaneous trip potentiometer at maximum setting (40X). Apply current to the relay, starting with a current below the set pickup, and very gradually increase the current applied to 5% below pickup value. The relay should not trip (See characteristic curves for approximate timing). Increase current 5% above pickup value and the relay should trip. The timing indicator (light emitting diode) begins to light in a dim manner at approximately 1% below the pickup point and attains full brightness at the actual minimum pickup level (tap block setting). This same procedure may be used to check the minimum trip current at other tap block settings.

If a more accurate check is desired, an oscilloscope may be used to view the minimum pickup signal. This signal is present on terminal 12 of the sensing-trip module, and is also easily accessible on the top lead of the TIMING light emitting diode by pulling back the insulated sleeving and attaching the scope probe to this point. The current where this signal becomes a solid logic 0 (complete absence of any positive pulses) is the actual minimum pickup point.

### B. Time Curve

The time curve calibration points for the various types of relays are shown in Table II. With the time dial set to the indicated position, apply the currents specified by Table II (e.g. for the SCO-8T, 2 and 20 times tap value current) and measure the operating time of the relay. The operating times should equal those of Table II plus or minus 10%.

# C. Instantaneous Trip

High multiples of current may be involved in the following test, therefore, caution should be taken not to exceed the thermal limits specified under CHARACTERISTICS. Starting with the instantaneous trip potentiometer set at minimum, a procedure of raising the potentiometer and applying the desired pickup current should be tried until the instantaneous unit does not operate with the desired current applied (time delay trip may operate). The instantaneous unit setting should then be "backed down and tried" until it does operate with the desired current applied (instantaneous trip indicator operates). The instantaneous will then respond to currents above this setting per the typical time curve Figure 14. If testing the instantaneous trip at higher multiples of pickup where the instantaneous and time delay curves may overlap, the time dial setting should be

raised to the 9.9 setting to give maximum time delay time.

# D. Trip Indication

The time trip indicator should operate (orange) on time curve trip and be resettable (black) with the reset lever. The instantaneous trip indicator should operate (orange) on instantaneous trip and be resettable (black) with the reset lever.

# E. Test Trip Switch

The trip test switch, when pushed, should trip the breaker. (Note: No indication occurs on this trip). Note that connection through terminal (1) to Battery Negative through a trip coil must be provided for the trip test to operate.

At completion of the acceptance test return all settings to desired position.

TABLE !!

	TIME DIAL POSITION	LOW CURF	RENT TESTS	HIGH CURRENT TESTS			
RELAY TYPE		CURRENT APPLIED TIMES TAP VALUE	OPERATING TIME IN SECONDS	CURRENT APPLIED TIMES TAP VALUE	OPERATING TIME IN SECONDS		
SCO-2T	5.0	2X	.888	20X	.222		
SCO-5T	5.0	2X	33.5	10X	14.0		
SCO-6T	5.0	2X	2.42	20X	1.28		
SCO-7T	5.0	2X	4.50	20X	1.36		
SCO-8T	5.0	2X	9.66	20X	1.00		
SCO-9T	5.0	2X	7.50	20X	.675		
SCO-11T	5.0	2X	10.5	20X	.310		

(Note: 8 milliseconds pickup time for the T.D. relay must be added to the above operate times for total operate time of the SCO-T relay).

# **ROUTINE MAINTENANCE**

All relays should be inspected periodically and all settings and times of operation should be checked at least once every year or at such other intervals as may be indicated by experience to be suitable to the particular application.

#### **CALIBRATION**

The proper adjustments to insure correct operation of the relay have been made at the factory and should not be disturbed after receipt by the customer. However, recalibration may be required if the adjustments or any components have

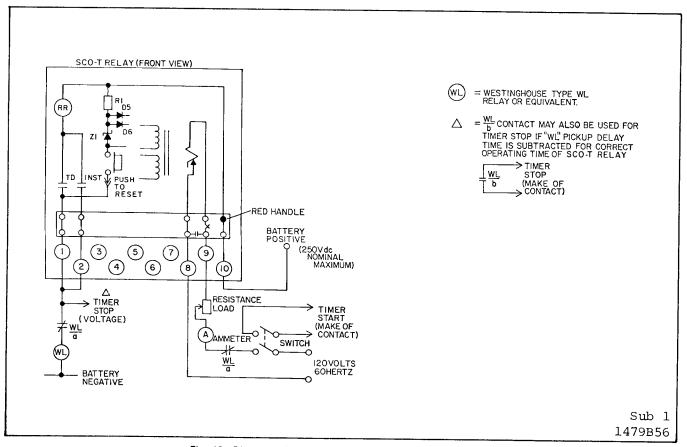


Fig. 18. Diagram of Test Connections for Type SCO-T Relay

been changed or SCO-T curve plug-in modules interchanged. This procedure should not be used until it is apparent that the relay is not in proper working order (See "Acceptance Check"). The SCO-T test diagram shown in Figure 18 aids in test of the relay. Proper energization of the relay is also shown in this figure.

#### A. Minimum Trip Curve

Set the time dial at 0.1 setting, the tap block at a 1 amp. setting, and the instantaneous trip potentiometer at maximum setting (40X). Apply minimum current (1 amp.) to the relay (terminals 8 and 9). Adjust multi-turn trimpot R5 so that the relay will trip at tap value +1% and not trip at tap value -1%. Counterclockwise rotation of trimpot R5 increases the pickup point, (increases VR) and clockwise rotation of trimpot R5 decreases it. See Figure 2, front photograph, and Figure 6, module component location, for exact location of trimpot R5.

Note that the TIMING indicator (light emitting diode) begins to light in a dim manner at approximately 1% below the pickup and attains full brightness at the actual minimum pickup level.

An oscilloscope may be used to view the minimum pickup signal. This signal is present on terminal 12 of the sensing and trip module, and is also easily accessible on the top lead of the TIMING light emitting diode by pulling back the insulated sleeving and attaching the scope probe to this point. The current where this signal becomes solid logic 0 (complete absence of any positive pulses) is the actual minimum pickup point. This method is recommended for type SCO-5T and SCO-11T relays which have appreciable trip delays at pickup value.

#### B. Time Curve

Set the tap block at a 1 amp. setting, and set the instantaneous trip at maximum or above 20 times setting so it will not interfere with the time curve trip.

The time curve calibration points for the various types of relays are shown in Table II. Apply current per Table II for 10X or 20X pickup and adjust multi-turn trimpot R6 for the appropriate operating time ±2%. Clockwise rotation of trimpot R6 increases the trip time and counterclockwise rotation decreases it. See Figure 2, front photograph, and Figure 6, module component location, for exact location of trimpot R6. Apply current per Table II for 2X pickup and check for appropriate operating time  $\pm 7\%$ . Caution should be taken at these higher multiples of current not to exceed the thermal limits of the relay specified under CHARACTERISTICS. A contact to interrupt the input current upon trip of the relay is recommended in testing the SCO-T relay.

Note: Trimmer capacitor C19 has been factory set for correct operation of IC-6 and should not be readjusted. However, if IC-6 is ever replaced, capacitor C19 and trimpot R6 must both be adjusted with a SCO-11 curve module plugged in the relay to obtain correct compensation for IC-6 and correct SCO-11 curve 20X timing value.

# C. Instantaneous Trip

High multiples of current may be involved in the following test, therefore, caution should be taken not to exceed the thermal limits specified under CHARACTERISTICS. Starting with the instantaneous trip potentiometer R18 set at minimum, (fully counterclockwise) a procedure of raising the potentiometer and applying the desired pickup current should be tried until the instantaneous unit does not operate with the desired current applied (Time delay trip may operate). The

instantaneous unit setting shoulld then be "backed down and tried" until it does operate with the desired current applied. (Instantaneous trip indicator operates). The instantaneous unit will then respond to currents above this setting per the typical time curve Figure 14. If testing the instantaneous trip at higher multiples of pickup where the instantaneous and time delay curves may overlap, the time dial setting should be raised to the 9.9 setting to give a maximum time delay time.

No other calibration is necessary other than desired changes in settings.

# TROUBLE SHOOTING

The components in the SCO-T relay are operated well within their ratings and normally will give long and trouble free service. However, if a relay has given indication of trouble in service or during routine checks, then using the internal schematic Figure 3, component location Figures 5 and 6, and the theory of operation the faulty component, connection, or circuit can be identified.

Voltage levels for "0" and "1" logic states in the theory of operation are:

Logic "0" is equivalent to less than 1 Vdc positive.

Logic "1" is equivalent to 5 to 11 Vdc positive.

For those users not generally acquainted with circuit notation or with device symbols of those components used in the SCO-T drawings, it is recommended that a copy of Westinghouse Instruction Leaflet I.L. 41-000.1 entitled, "Symbols for Solid State Protective Relaying" be consulted.

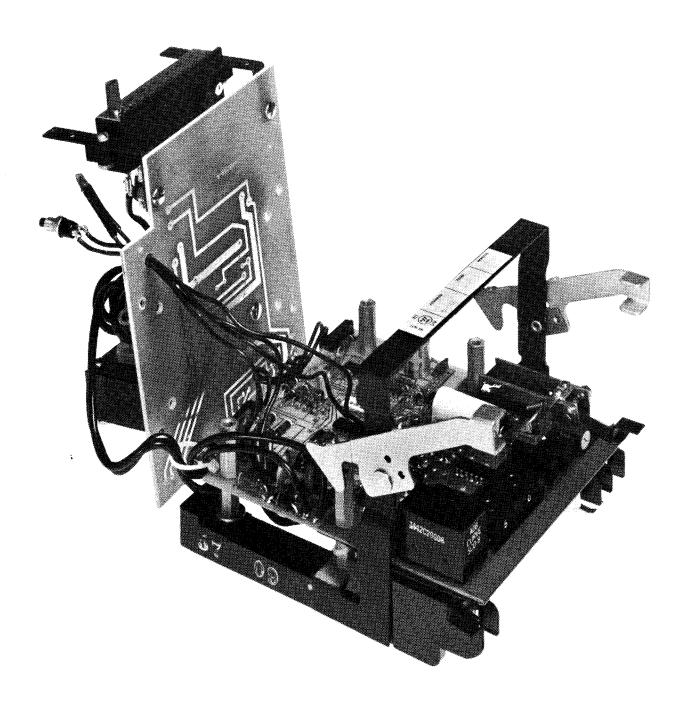


Fig. 19. Disassembly of Type SCO-T Relay

The SCO-T relay can easily be disassembled to gain accessibility to all components for ease in trouble shooting. The following procedure should be followed to mechanically detach and slide back the top transformer module when accessibility to components on the bottom module is desired (reference Figure 19):

- 1. Remove the two nameplate screws.
- 2. Remove both the tap block screw and spare tap screw.
- 3. Slide back rear retaining ring on TIMING light emitting diode snap bushing (onto wires), and push light emitting diode back through panel.
- 4. Unscrew shield guard from trip test switch (counterclockwise rotation). Front panel is now free to remove.
- 5. Remove the four screws holding the top module to posts.
- 6. Slip the wire tie, which holds the leads in the rear, up over the left rear post.
- 7. Slide the top module backwards for accessibility to components on bottom module.

Reassembly of the relay is accomplished by reassembling everything disassembled in steps 1 through 7 above in reverse order (7 through 1). Reposition intermodule connecting lead wires in rear of relay back to original routing.

#### RENEWAL PARTS

Repair work can be done most satisfactorily at the factory. However, interchangeable parts can be furnished to the customers who are equipped for doing repair work. Internal Schematic Figure 3 contains a complete list and description of the components for renewal parts. When ordering parts, always give complete nameplate data and appropriate Westinghouse style numbers.

# PLUG-IN CURVE MODULES (IC-1)

Plug-in curve modules are available to change the particular style and time-overcurrent characteristic curve of the relay. The time curve module is a 24 pin plug-in module containing the specific circuitry and components for each particular curve style. There are seven different curve module styles corresponding to the SCO-2, SCO-5, SCO-6, SCO-7, SCO-8, SCO-9 and SCO-11 curves. This module plugs into the 24 pin socket on the sensing-trip module and is visible to the front of the relay through a window in the front panel. There the front label on the module completes the last three digits of the style of the relay (printed on the front panel), and also shows which curve the relay is set for i.e. "SCO-2 curve". Thus, changing this module automatically changes the style of the relay.

When changing plug-in curve modules, the relay should be recalibrated for minimum pickup and time curve specifications per the Calibration Section of this instruction leaflet.

The following are the style numbers of the plug-in curve modules available:

Relay Type	Curve Module	Time Curve	Curve Module Plug-In Style
SCO-2T	A02	Short	1442C29G02
SCO-5T	A05	Long	1442C29G05
SCO-6T	A06	Definite	1442C29G06
SCO-7T	<b>A</b> 07	Moderately Inverse	1442C29G07
SCO-8T	A08	Inverse	1442C29G08
SCO-9T	A09	Very Inverse	1442C29G09
SCO-11T	<b>A</b> 11	Extremely Inverse	1442C29G11

Consult Type SCO Time Curve Plug-in Modules Instruction Leaflet I.L. 41-110.2 for further information on SCO-T plug-in curve modules.

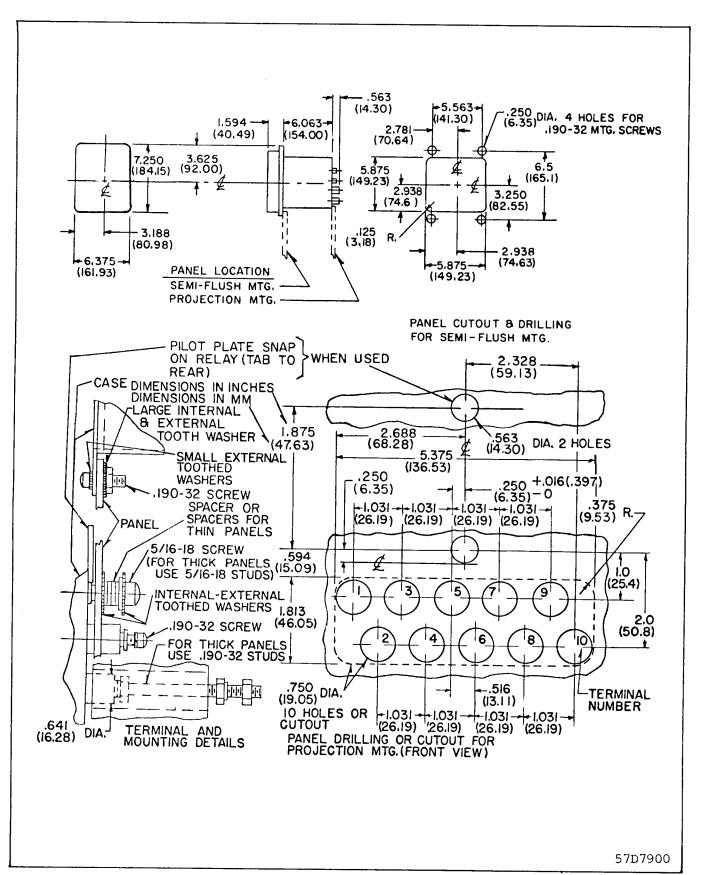
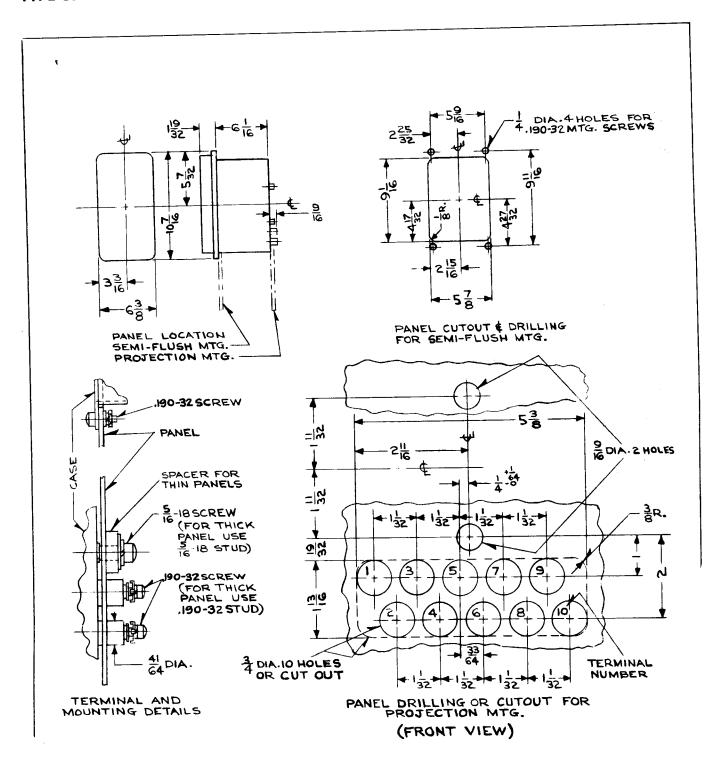


Fig. 20. Outline and Drilling Plan for Type SCO-T Relay Single Phase in FT-11 Case

# WESTINGHOUSE ELECTRIC CORPORATION RELAY-INSTRUMENT DIVISION NEWARK, N. J.



line and Drilling Plan for the Type CO Multi-range Contact Making Ammeter in the Type FT21 se.



# INSTALLATION . OPERATION . MAINTENANCE

# TYPE CO MULTI-RANGE CONTACT MAKING AMMETER

CAUTION Before putting relays into service, remove all blocking inserted for the purpose of securing the parts during shipment. Make sure that all moving parts operate freely. Inspect the contacts to see that they are clean and close properly, and operate the relay to check the settings and electrical connections.

# APPLICATION

These relays are used to initiate switching or control operations when the line current rises above a preset value, or falls below a preset value. Thus the relay is a contact making ammeter with high and low current settings.

# CONSTRUCTION AND OPERATION

The relay consists of a current operated induction disc unit, a tap adjuster to change the relay operating range, and adjustable front and back contacts to set the upper and lower tripping limits. There is no torque compensator, operation indicator, or contactor switch.

The operating unit is an induction-disc type element operating on overcurrent. The induction disc is a thin four-inch diameter conducting disc mounted on a vertical shaft. The shaft is supported on the lower end by a steel ball bearing riding between concave sapphire jewel surfaces, and on the upper end by a stainless steel pin.

The moving contact is a small silver rod hemispherically shaped at either end to form a double throw arrangement. It is fastened on the end of a conducting arm. The other end of this arm is clamped to an insulating tube on the disc shaft. The electrical connection is made from the moving contact thru the arm and a spiral spring. One end of the spring is fastened to the arm, and the other to a slotted spring adjuster disc which in turn fastens to the moulded insulation block mounted on the unit.

The front and back stationary contact assemblies are both adjustable. Each mounts on a lever which can be set anywhere about the periphery of a calibrated scale. The moulded brackets, upon which the stationary contact leaf springs are mounted, are each secured to their respective lever arms by two screws. These screws may be loosened and the moulded contact supports pivoted to the positions required for correct tracking of both contact assemblies on the calibrated scale.

The moving disc is rotated by an electro-magnet in the rear and damped by a permanent magnet in the front. The operating torque is obtained by the circuit arrangement shown in Fig. 1. The main pole coil of the relay acts as a transformer and induces a voltage in a secondary coil. Current from this secondary coil flows through the upper pole coils and thus produces torque in the disc by the reaction between the fluxes of the upper and lower poles. When the current rises above the preset value the moving contact closes to the right (front view). When the current falls below a preset value the moving contact closes to the left (front view).

#### CHARACTERISTICS

The type CO multi-range contact making ammeter has adjustable high and low current contacts that can be set around an  $180^{\circ}$  arc which is calibrated from 80% to 105% in 5% steps. It is possible to move the adjustable contacts to their extreme positions corresponding to approximately 75% and 110%. These values represent the tripping position of the moving contacts when that percent of tap current is applied to the relay. The tap plate is marked in amperes as follows: 2.0, 2.5, 3.0, 3.5, 4.0, 5.0 and 6.0.

The moving contacts will assume a position corresponding to the current thru the relay and the relay setting and will stay in that position until the current changes. If the current changes either

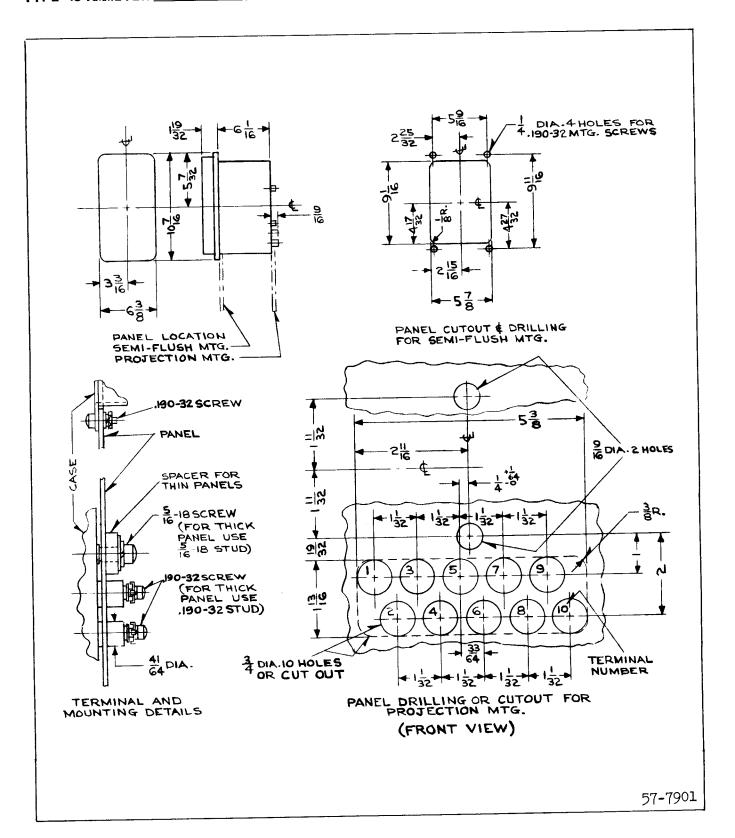


Fig. 3. Outline and Drilling Plan for the Type CO Multi-range Contact Making Ammeter in the Type FT21 Case.

# WESTINGHOUSE ELECTRIC CORPORATION METER DIVISION • NEWARK, N.J.



# INSTALLATION • OPERATION • MAINTENANCE INSTALLATION • OPERATION • MAINTENANCE

# TYPE CO MULTI-RANGE CONTACT MAKING AMMETER

CAUTION Before putting relays into service, remove all blocking inserted for the purpose of securing the parts during shipment. Make sure that all moving parts operate freely. Inspect the contacts to see that they are clean and close properly, and operate the relay to check the settings and electrical connections.

### **APPLICATION**

These relays are used to initiate switching or control operations when the line current rises above a preset value, or falls below a preset value. Thus the relay is a contact making ammeter with high and low current settings.

## CONSTRUCTION AND OPERATION

The relay consists of a current operated induction disc unit, a tap adjuster to change the relay operating range, and adjustable front and back contacts to set the upper and lower tripping limits. There is no torque compensator, operation indicator, or contactor switch.

The operating unit is an induction-disc type element operating on overcurrent. The induction disc is a thin four-inch diameter conducting disc mounted on a vertical shaft. The shaft is supported on the lower end by a steel ball bearing riding between concave sapphire jewel surfaces, and on the upper end by a stainless steel pin.

The moving contact is a small silver rod hemispherically shaped at either end to form a double throw arrangement. It is fastened on the end of a conducting arm. The other end of this arm is clamped to an insulating tube on the disc shaft. The electrical connection is made from the moving contact thru the arm and a spiral spring. One end of the spring is fastened to the arm, and the other to a slotted spring adjuster disc which in turn fastens to the moulded insulation block mounted on the unit.

The front and back stationary contact assemblies are both adjustable. Each mounts on a lever which can be set anywhere about the periphery of a calibrated scale. The moulded brackets, upon which the stationary contact leaf springs are mounted, are each secured to their respective lever arms by two screws. These screws may be loosened and the moulded contact supports pivoted to the positions required for correct tracking of both contact assemblies on the calibrated scale.

The moving disc is rotated by an electro-magnet in the rear and damped by a permanent magnet in the front. The operating torque is obtained by the circuit arrangement shown in Fig. 1. The main pole coil of the relay acts as a transformer and induces a voltage in a secondary coil. Current from this secondary coil flows through the upper pole coils and thus produces torque in the disc by the reaction between the fluxes of the upper and lower poles. When the current rises above the preset value the moving contact closes to the right (front view). When the current falls below a preset value the moving contact closes to the left (front view).

#### CHARACTERISTICS

The type CO multi-range contact making ammeter has adjustable high and low current contacts that can be set around an  $180^{\circ}$  arc which is calibrated from 80% to 105% in 5% steps. It is possible to move the adjustable contacts to their extreme positions corresponding to approximately 75% and 110%. These values represent the tripping position of the moving contacts when that percent of tap current is applied to the relay. The tap plate is marked in amperes as follows: 2.0, 2.5, 3.0, 3.5, 4.0, 5.0 and 6.0.

The moving contacts will assume a position corresponding to the current thru the relay and the relay setting and will stay in that position until the current changes. If the current changes either

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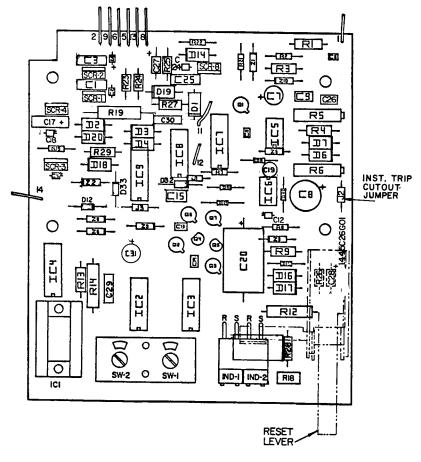
# INSTALLATION . OPERATION . MAINTENANCE

# INSTRUCTIONS

# TYPE SCO-T SOLID STATE SINGLE PHASE OVERCURRENT RELAY

This sheet notes changes which should be made in instruction leaflet I.L. 41-111 dated July 1978.

Figure 6, page 10, is in error. The correct figure and drawing number is shown below:



Sub. 4 3512A41

Fig. 6. Sensing Trip Module Component Location Single Phase.

All possible contingencies which may arise during installation, operation, or maintenance, and all details and variations of this equipment do not purport to be covered by these instructions. If further information is desired by purchaser regarding his particular installation, operation or maintenance of his equipment, the local Westinghouse Electric Corporation representative should be contacted.

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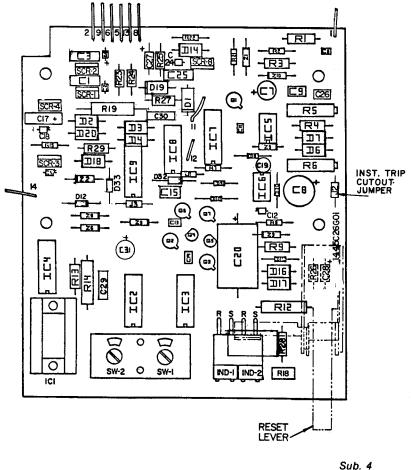
# INSTALLATION . OPERATION . MAINTENANCE

# INSTRUCTIONS

# TYPE SCO-T SOLID STATE SINGLE PHASE OVERCURRENT RELAY

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Fig. 6. Sensing Trip Module Component Location Single Phase.

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