



# INSTALLATION • OPERATION • MAINTENANCE INSTRUCTIONS

## TYPE HRZ DIRECTIONAL OVERCURRENT IMPEDANCE RELAY

**CAUTION** Before putting protective relays into service, remove all blocking which may have been inserted for the purpose of securing the parts during shipment, make sure that all moving parts operate freely, inspect the contacts to see that they are clean and close properly, and operate the relay to check the settings and electrical connections.

### APPLICATION

The Type HRZ relay is a combination of the instantaneous impedance and directional elements of the Type HZ relay and the overcurrent element of the Type CO relay. This relay is used for high speed clearing of phase faults on transmission systems. It gives instantaneous protection over 80 to 90% of the protected section, and time delay overcurrent protection over the remaining 20 to 10% of the protected section, and the adjacent section.

### CONSTRUCTION AND OPERATION

The Type HRZ relay contains an instantaneous impedance (HZ) element, an overcurrent (CO) element, a directional element, auxiliary contactor switches and operation indicators all mounted in a single case. The construction and operation of each of these elements is as follows.

#### Instantaneous Impedance (HZ) Element

This element is similar to the first impedance element of the Type HZ relay. It consists of a balanced beam pivoted at the center (Figure 3) and pulled downward by a current coil on the forward end to close the relay contacts. This pull is opposed by two voltage coils acting on the other end of the

beam. The fluxes set up by these two potential coils are shifted out of phase with respect to each other so that a balance between current and voltage fluxes can be held within desirable limits for all phase angles.

A tap screw on the front of the element permits changing the number of turns on the current coil, and a core screw on the bottom of the element changes an air gap in the magnetic path. These two adjustments make it possible to set the impedance element so that it will operate instantaneously, for all faults occurring within 80 to 90% of the protected line section. For a fault at the balance point of the element (determined by setting) the pull of the voltage coil, which measures the IZ drop from the fault to the relay, will just equal the pull of the current coil, which receives the fault current, I. If the fault occurs inside the balance point, the IZ voltage pull will be less than the I current pull and the beam will trip closing its contacts. Conversely, if the fault occurs outside the relay balance point, the IZ voltage pull will be greater than the I current pull and the beam will not trip.

A rectangular silver contact is flexibly fastened on the forward end of the beam. As the beam trips, the contact bridges two silver stationary hemispherical contacts mounted on the free end of a short leaf spring. A small set screw determines the position of the leaf spring and provides means for adjusting the contact gap and follow.

#### Overcurrent Element

This element is an induction-disc type element operating on overcurrent. The induction disc is a thin four-inch diameter, aluminum

## TYPE HRZ RELAY

### SETTINGS

The type HRZ relay requires two separate settings: one for the instantaneous HZ element and the other for the CO element. Each will be considered below:

The following nomenclature is used for the discussion of the HZ settings:

Z = the line-to-neutral ohmic impedance. The impedance for 80 to 90% of the protected line section.

$R_c$  = the current transformer ratio.

$R_v$  = the potential transformer ratio.

T = the instantaneous HZ element current tap.

S = the instantaneous HZ element current core screw.

#### Instantaneous (HZ) Element Settings

This element is set to give instantaneous protection over approximately 90% of the protected line section. Since the impedance of the voltage coil is the same at all times, the balance point of the element is adjusted by changing the pull on the current coil. This is done by taps (T) on the current coil winding and by the core screw (S) which varies the magnetic air gap for the current flux.

The most satisfactory method of arriving at the tap settings is by the use of the following equations:

Instantaneous Element Receiving Delta Current:

$$TS = \frac{10 Z R_c}{R_v} \quad (1)$$

Instantaneous Element Receiving Star Current:

$$TS = \frac{17.3 Z R_c}{R_v} \quad (2)$$

The nomenclature is as defined above. The tap, T, is obtained by dividing the TS product by S to give an available tap number. When changing taps, the extra tap screw should be screwed in the desired tap before moving the existing tap screw to prevent open circuiting the current transformers.

The numbers on the core screw appear in ascending order as the core screw is screwed

into the core. In some cases, a question of doubt may arise whether the scale setting is correct, or is out by one full turn of the core screw. In such a case, the point may be verified by turning the core screw all the way in. Then back out the core screw until the highest scale marking and then continuing to back it off until the desired value appears exactly under the end of the pointer. Sufficiently accurate setting can be made by interpolating between the marked points when necessary.

The above formulas are based on the relay being used on a 60° line and are correct for lines of that angle. For lines other than 60° a slight error is introduced which may be as much as 8% and 6% on 40° and 80° lines respectively. However, the formula relay setting can be corrected for lines other than 60° by using the curve of Figure 5.

The formula settings are sufficiently accurate for most installations, where it is desired to set the balance point more accurately the tap and scale values may be checked by applying to the relay the voltage, current and phase angle conditions which will be impressed on it for a fault at the desired balance point. A slight change in the scale value from that calculated may be required so that the relay will just trip for the simulated fault at the balance point.

As an example, the instantaneous element is to be set for 90% of the line section AB which is 6 ohms long. The current transformer ratio is 200/5 star-connected with the star-delta auxiliary current transformer supplying delta current to the instantaneous element coils. The potential transformer ratio is 1000/1.

Using equation (1)

$$TS = \frac{10 \times .90 \times 6 \times 40}{1000} = 2.16$$

Set tap 2 on the .02 to 2.0 ohm relay and core screw = 1.08.

NOTE: The relay should not be required to operate when the drop from the relay to the fault for minimum fault is less than 5 relay volts.

Settings for the CO Element

There are two settings-namely the current value at which the relay closes its contacts and the time required to close them.

For sectionalizing transmission systems the current and time setting must be determined by calculation, due consideration being given to the time required for circuit breakers to open so that the proper selective action can be obtained throughout the system.

Current Setting

The connector screw on the terminal plate above the time scale makes connections to various turns on the operating coil. By placing this screw in the various holes, the relay will just close contacts at the corresponding current, 4-5-6-8-10-12 or 15 amperes, or as marked on the terminal plate.

The tripping value of the relay on any tap may be altered by changing the initial tension of the spiral spring. This can be accomplished by turning the spring adjuster by means of a screw driver inserted in one of the notches of the plate to which the outside convolution of the spring is fastened. An adjustment of tripping current approximately 15 percent above or below any tap value, can be secured.

Time Lever Setting

The index or time lever limits the motion of the disc and thus varies the time of operation. The latter decreases with lower lever settings as shown in the typical time curves.

**CAUTION**

Be sure that the connector screws are turned up tight so as to make a good contact, for the operating current passes through it. Since the overload and the impedance element current coils are connected directly in the current transformer circuits the latter should be short-circuited before changing the connector screw. This can be done conveniently by inserting the extra connector screw, in the new tap and removing the old screw from its original setting.

**ADJUSTMENTS AND MAINTENANCE**

The proper adjustments to insure correct operation of this relay have been made at the factory and should not be disturbed after receipt by the customer. If the adjustments have been changed, the relay taken apart for repairs, or if it is desired to check the adjustments at regular maintenance periods, the instructions below should be followed.

All contacts should be periodically cleaned with a fine file S#1002110 file is recommended for this purpose. The use of abrasive material for cleaning contacts is not recommended, because of the danger of embedding small particles in the face of the soft silver and thus impairing the contact.

Instantaneous Impedance (HZ) Element

Refer to Figure 3. For the 60 cycle relays adjust the stop screw on the rear of the beam to give a clearance of .025 inch between the rear of the beam and the voltage iron circuit. This may be checked with a feeler gauge. With the beam in the reset position, i.e., back against the stop, adjust the gap between the adjustable iron and the beam to .009 inch. Care should be taken in this adjustment to keep the gap the same on both sides. Also, with the beam in the same position, adjust the gap between the front end of the beam and the stop in the upper core screw to .020 inch.

The beam should be balanced as follows. Connect the relay as shown in the test diagram, Figure 11. With any tap and scale setting, check the impedance measured by the relay with 35 volts potential restraint. Apply 5 volts restraint and adjust the balance weight on the beam until the beam just trips with 1/7 of the current required to trip with 35 volts restraint. Make certain that the stop on the voltage side is absolutely clean, otherwise the impedance at which the beam trips may be affected, particularly at the low voltages. The stop can be easily cleaned by drawing a piece of clean white paper between the beam and the stop while the beam is firmly pressed down.

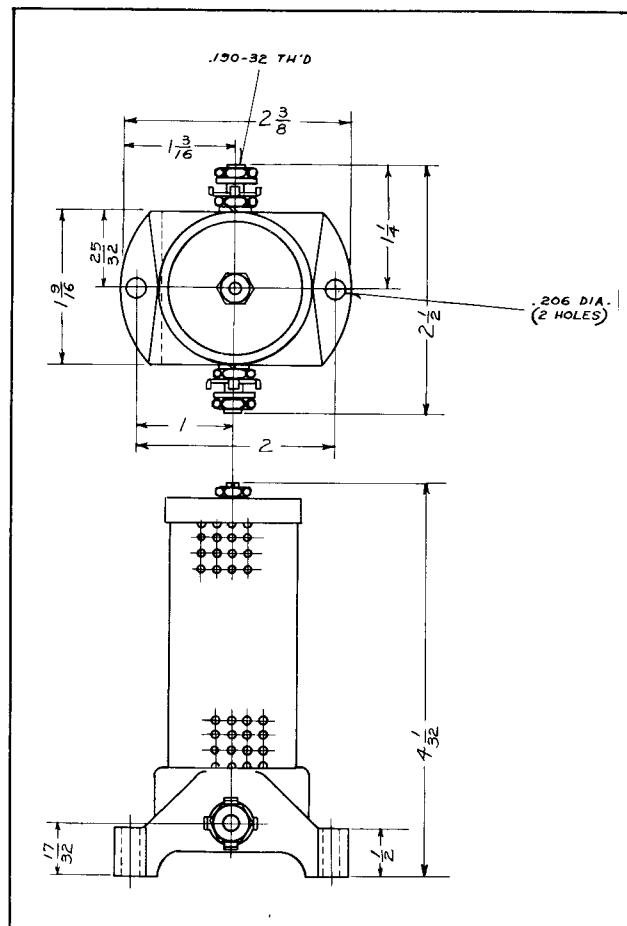


Fig. 13—Outline and Drilling Plan for the External Control Circuit Resistor for the 250 volt d.c. relays. For Reference Only.

## Auxiliary Contactor Switch

### (Directional Control Circuit)

The adjustments are the same as for the seal-in contactor switch except that the contact separation should be  $\frac{3}{64}$  inch. The switch should pick-up at not more than 80 volts d.c. Apply 140 volts d.c. to the circuit and see that the contacts drop out when the coil is shorted by the left-hand directional contacts. For the 250 volt d.c. relays the pick-up should be 165 volts and the contacts should drop-out when the directional element contacts short-circuit the coil with 250 to 280 volts applied to the circuit. Energize the directional element with 50 volts and 10 amperes in phase suddenly applied. The contactor switch must operate the first time the directional contacts close without flut-tering or bouncing of the contacts.

## Operation Indicator

Adjust the indicator to operate at 1.0 ampere d.c. gradually applied. Test for sticking after 30 amperes d.c. is passed through the coil.

## RENEWAL PARTS

Repair work can be done most satisfactorily at the factory. However, interchangeable parts can be furnished to the customers who are equipped for doing repair work. When ordering parts, always give the complete nameplate data.

## ENERGY REQUIREMENTS

The burdens of the various circuits of the 60 cycle relay are as follows:

## TYPE HRZ RELAY

## DEFINITE MINIMUM TIME CO ELEMENT AT 60 CYCLES

Ampere Range	Tap	V.A. at 5 Amperes	V.A. at Tap Current	Power Factor	Continuous Rating (Amperes)	One Second Rating (Amperes)
2/6	2	108	17	60° lag	4	140
	2.5	68	17	60° lag	5	140
	3	47	17	60° lag	5	140
	3.5	35	17	60° lag	6	140
	4	26	17	60° lag	7	140
	5	17	17	60° lag	8	140
	6	12	17	60° lag	10	140
	4	26	17	60° lag	8	250
4/15	5	17	17	60° lag	8	250
	6	12	17	60° lag	9	250
	8	6.5	17	60° lag	10	250
	10	4.5	17	60° lag	12	250
	12	3	17	60° lag	13	250
	15	2	17	60° lag	15	250

## INVERSE TIME CO ELEMENT AT 60 CYCLES

Ampere Range	Tap	V.A. at 5 Amperes	V.A. at Tap Current	Power Factor	Continuous Rating (Amperes)	One Second Rating (Amperes)
0.5/2.5	0.5	200	2	66° lag	2	70
	0.6	140	2	66° lag	2	70
	0.8	78	2	66° lag	2	70
	1.0	50	2	66° lag	3	70
	1.5	22	2	66° lag	3	70
	2.0	12.5	2	66° lag	4	70
	2.5	8	2	66° lag	5	70
2/6	2	12.4	2	66.4° lag	8	250
	2.5	8	2	66.4° lag	8	250
	3	5.6	2	66.4° lag	8	250
	3.5	4.1	2	66.4° lag	8	250
	4	3.1	2	66.4° lag	9	250
	5	2	2	66.4° lag	9	250
	6	1.3	2	66.4° lag	10	250
4/15	4	3.1	2	66.4° lag	16	250
	5	2	2	66.4° lag	16	250
	6	1.4	2	66.4° lag	16	250
	8	0.8	2	66.4° lag	17	250
	10	0.5	2	66.4° lag	18	250
	12	0.3	2	66.4° lag	19	250
	15	0.2	2	66.4° lag	20	250

## VERY INVERSE TIME CO ELEMENT AT 60 CYCLES

Ampere Range	Tap	V.A. at 5 Amperes	V.A. at Tap Current	Power Factor	Continuous Rating (Amperes)	One Second Rating (Amperes)
0.5/2.5	0.5	125	1.25	66.4° lag	2	100
	0.6	87	1.25	66.4° lag	2	100
	0.8	49	1.25	66.4° lag	2	100
	1.0	31	1.25	66.4° lag	3	100
	1.5	14	1.25	66.4° lag	3	100
	2.0	8	1.25	66.4° lag	4	100
	2.5	5	1.25	66.4° lag	5	100
2/6	2	8	1.25	66.4° lag	8	250
	2.5	5	1.25	66.4° lag	8	250
	3	3.5	1.25	66.4° lag	8	250
	3.5	2.5	1.25	66.4° lag	8	250
	4	1.9	1.25	66.4° lag	9	250
	5	1.25	1.25	66.4° lag	9	250
	6	0.9	1.25	66.4° lag	10	250







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**METER DIVISION** . **NEWARK, N.J.**

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#### Overcurrent Element

This element is an induction-disc type element operating on overcurrent. The induction disc is a thin four-inch diameter, aluminum

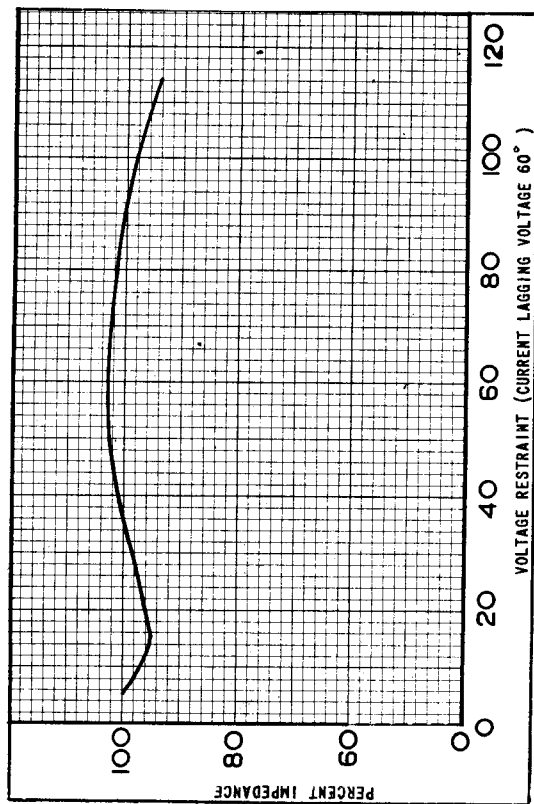


Fig. 4 - Typical Impedance Curve for the Instantaneous (HZ) Element.

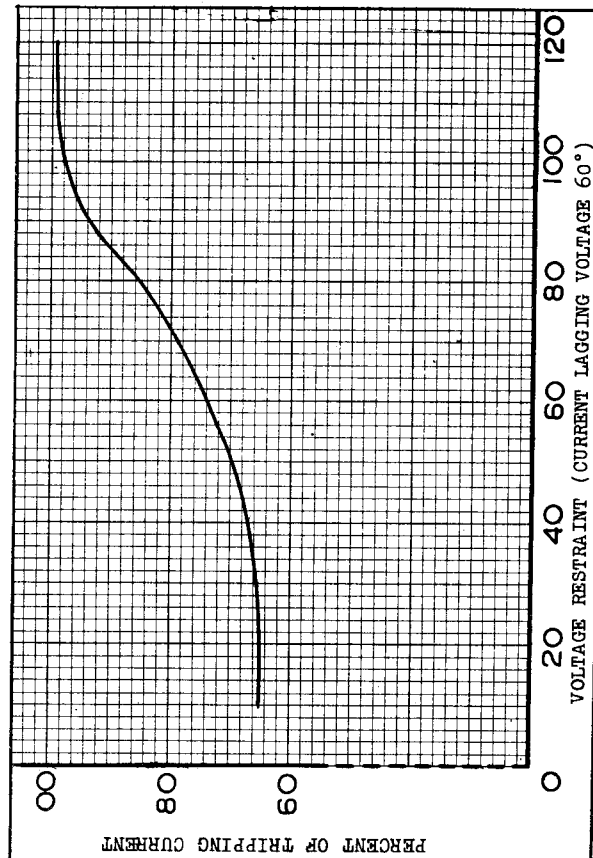


Fig. 6 - Typical Reset Curve for the Instantaneous (HZ) Element.

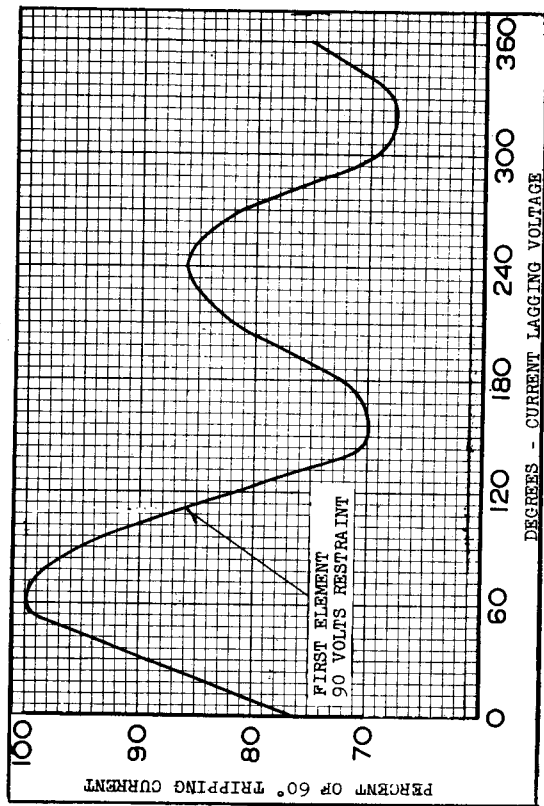


Fig. 5 - Typical Phase Angle Curve of the Instantaneous (HZ) Element.

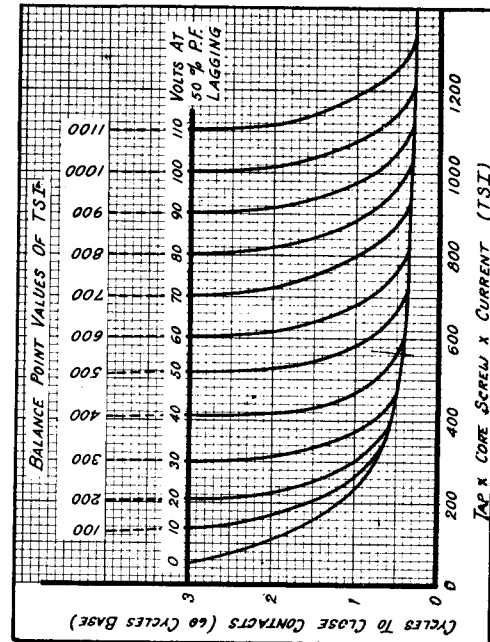


Fig. 7 - Typical Time of Operation Curves for the Instantaneous (HZ) Element.

## TYPE HRZ RELAY

The type CO inverse, very inverse (low energy) element is available in the following current ranges.

0.5, 0.6, 0.8, 1.0, 1.5, 2.0, 2.5  
2, 2.5, 3, 3.5, 4, 5, 6  
4, 5, 6, 8, 10, 12, 15

The tap value is the minimum current required to just close the relay contacts. In addition to the taps, the initial position of the moving contact is adjustable around a semicircular lever scale calibrated in 11 divisions.

The characteristics of the various varieties of type CO element usually supplied are as shown on Figure 8, 9 and 10.

### INSTALLATION

The relays should be mounted on switchboard panels or their equivalent in a location free from dirt, moisture, excessive vibration and heat. Mount the relay vertically by means of the two mounting studs for the standard cases and the type FT projection case or by means of the four mounting holes on the flange for the semi-flush type FT case. Either of the studs or the mounting screws may be utilized for grounding the relay. The electrical connections may be made direct to the terminals by means of screws for steel panel mounting or to terminals studs furnished with the relay for ebony-asbestos or slate panel mounting. The terminal studs may be easily removed or inserted by locking two nuts on the studs and then turning the proper nut with a wrench.

The recommended connections of relay are shown in Fig. 12. The 60° connection is used on the directional element, that is at unity power factor the current thru the directional element coil should lead the polarizing voltage by 60° as shown in the vector diagram. The star-delta auxiliary current transformer is the same as used with the type HZ relay and is described in I.L. 41-535.

### RELAYS IN TYPE FT CASE

The type FT cases are dust-proof enclosures combining relay elements and knife-blade test

switches in the same case. This combination provides a compact flexible assembly easy to maintain, inspect, test and adjust. There are three main units of the type FT case: the case, cover and chassis. The case is an all welded steel housing containing the hinge half of the knife-blade test switches and the terminals for external connections. The cover is a drawn steel frame with a clear window which fits over the front of the case with the switches closed. The chassis is a frame that supports the relay elements and the contact jaw half of the test switches. This slides in and out of the case. The electrical connections between the base and chassis are completed through the closed knife-blades.

#### Removing Chassis

To remove the chassis, first remove the cover by unscrewing the captive nuts at the corners. There are two cover nuts on the S size case and four on the L and M size cases. This exposes the relay elements and all the test switches for inspection and testing. The next step is to open the red handle test switches first before any of the black handle switches or the cam action latches. This opens the trip circuit to prevent accidental trip out. Then open all the remaining switches. The order of opening the remaining switches is not important. In opening the test switches they should be moved all the way back against the stops. With all the switches fully opened, grasp the two cam action latch arms and pull outward. This releases the chassis from the case. Using the latch arms as handles, pull the chassis out of the case. The chassis can be set on a test bench in a normal upright position as well as on its top, back or sides for easy inspection, maintenance and test.

After removing the chassis a duplicate chassis may be inserted in the case or the blade portion of the switches can be closed and the cover put in place without the chassis. The chassis operated shorting switch located behind the current test switch prevents open circuiting the current transformers when the current type test switches are closed.

# TYPE HRZ RELAY

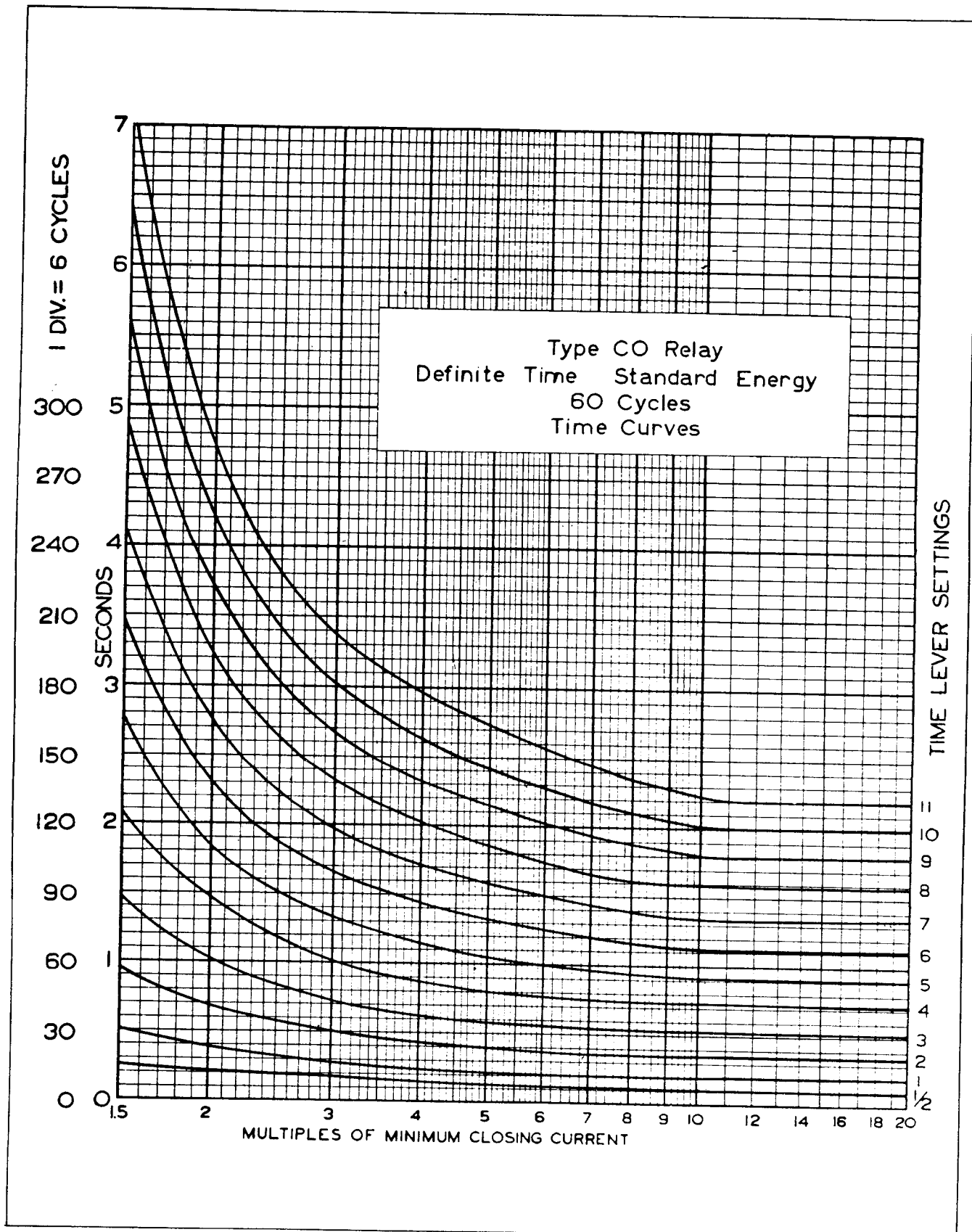


Fig. 8—Typical 60 Cycle Time Curves of the Overcurrent Element of the Definite Minimum Time type HRZ Relay.

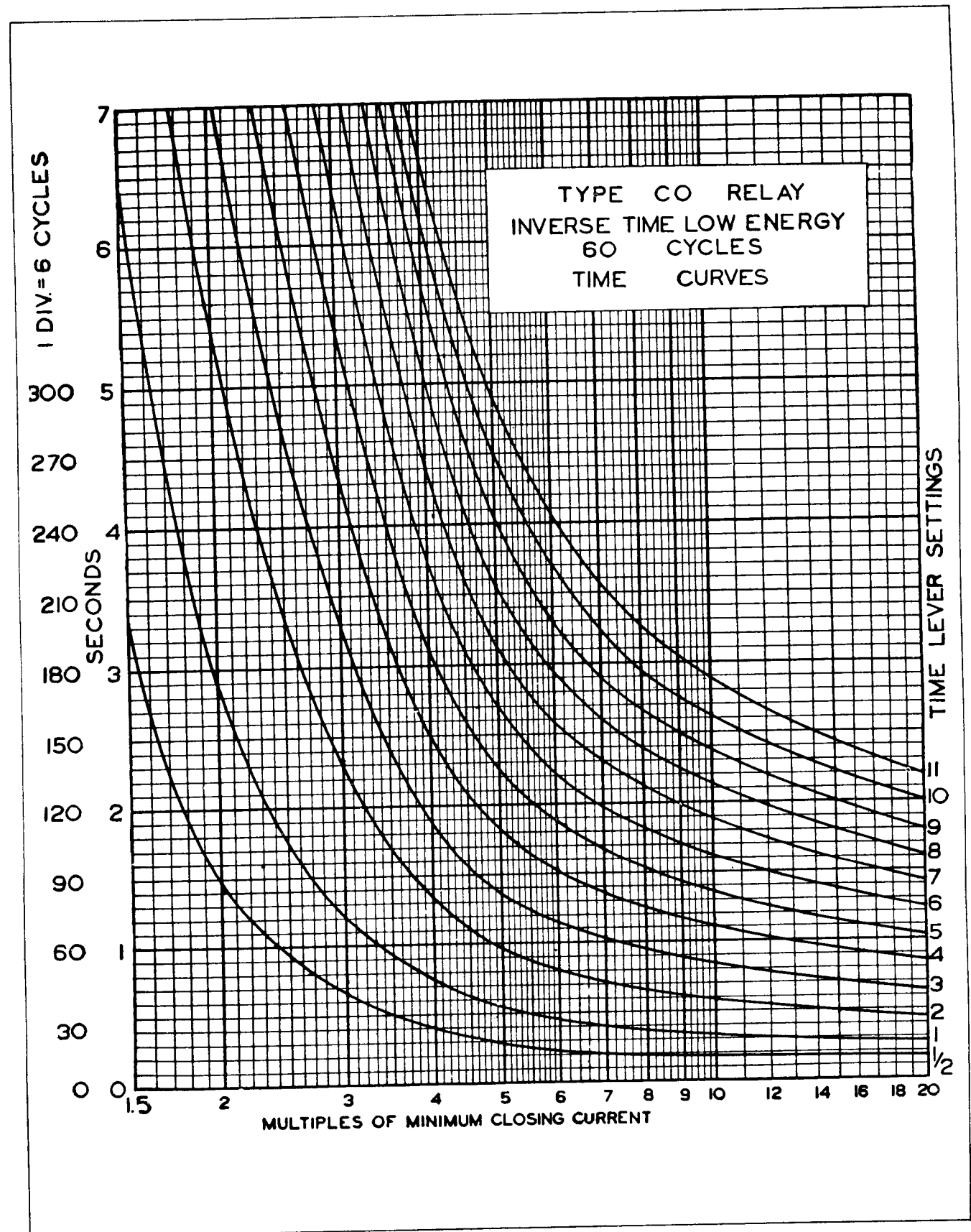


Fig. 9—Typical 60 Cycle Time Curves of the Overcurrent Element of the Inverse Time (Low Energy) type HRZ Relay.

# TYPE HRZ RELAY

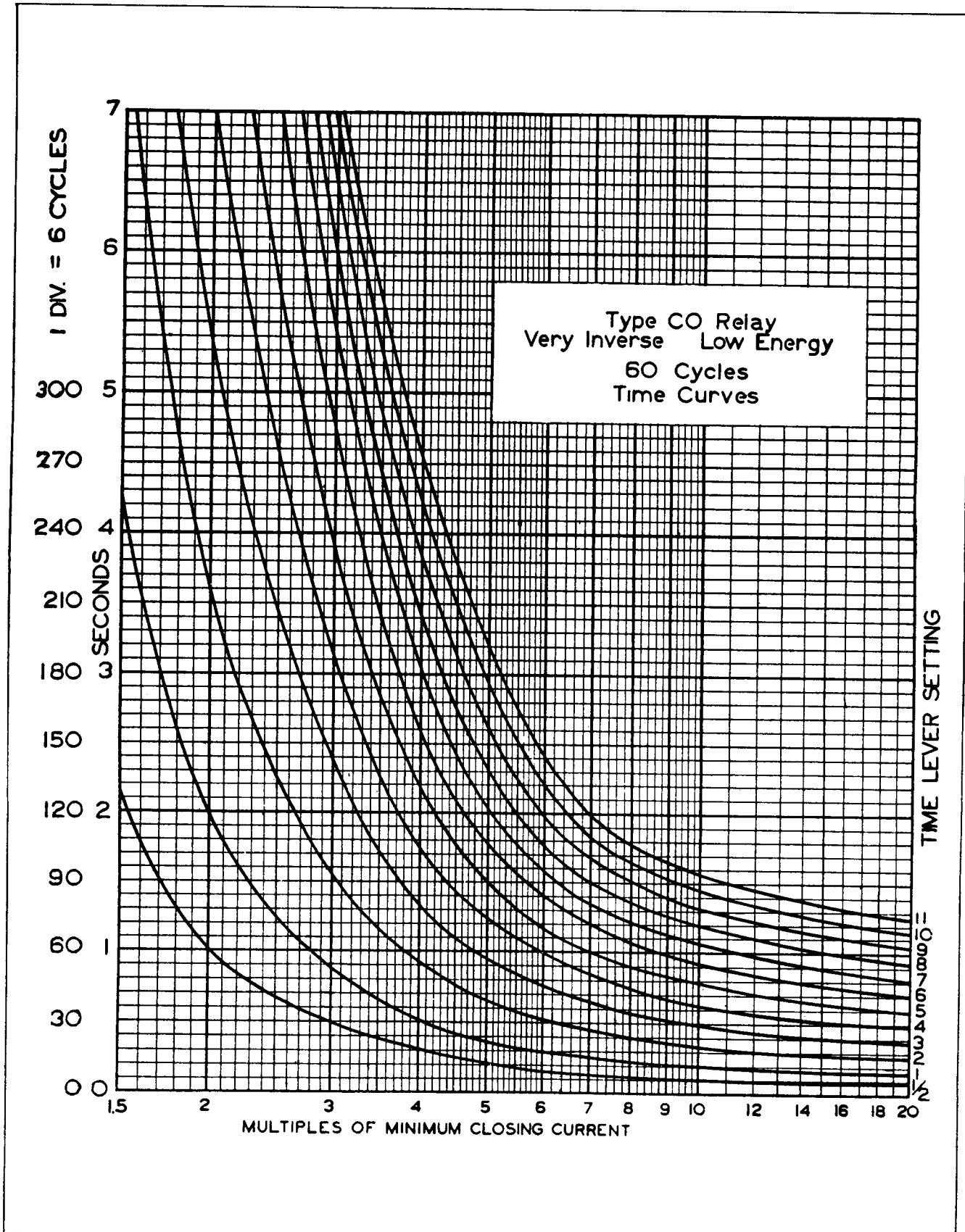


Fig. 10—Typical 60 Cycle Time Curves of the Overcurrent Element of the Very Inverse Time (Low Energy) type HRZ Relay.

## TYPE HRZ RELAY

When the chassis is to be put back in the case, the above procedure is to be followed in the reversed order. The elongated red handle switch should not be closed until after the chassis has been latched in place and all of the black handle switches closed.

### Electrical Circuits

Each terminal in the base connects thru a test switch to the relay elements in the chassis as shown on the internal schematic diagrams. The relay terminal is identified by numbers marked on both the inside and outside of the base. The test switch positions are identified by letters marked on the top and bottom surface of the moulded blocks. These letters can be seen when the chassis is removed from the case.

The potential and control circuits thru the relay are disconnected from the external circuit by opening the associated test switches. Opening the current test switch short-circuits the current transformer secondary and disconnects one side of the relay coil but leaves the other side of the coil connected to the external circuit thru the current test jack jaws. This circuit can be isolated by inserting the current test plug (without external connections), by inserting the ten circuit test plug, or by inserting a piece of insulating material approximately 1/32" thick into the current test jack jaws. Both switches of the current test switch pair must be open when using the current test plug or insulating material in this manner to short-circuit the current transformer secondary.

A cover operated switch can be supplied with its contacts wired in series with the trip circuit. This switch opens the trip circuit when the cover is removed. This switch can be added to the existing type FT cases at any time.

### Testing

The relays can be tested in service, in the case but with the external circuits isolated or out of the case as follows:

### Testing In Service

The ammeter test plug can be inserted in the current test jaws after opening the knife-blade switch to check the current thru the relay. This plug consists of two conducting strips separated by an insulating strip. The ammeter is connected to these strips by terminal screws and the leads are carried out thru holes in the back of the insulated handle.

Voltages between the potential circuits can be measured conveniently by clamping #2 clip leads on the projecting clip lead lug on the contact jaw.

### Testing In Case

With all blades in the full open position, the ten circuit test plug can be inserted in the contact jaws. This connects the relay elements to a set of binding posts and completely isolates the relay circuits from the external connections by means of an insulating barrier on the plug. The external test circuits are connected to these binding posts. The plug is inserted in the bottom test jaws with the binding posts up and in the top test switch jaws with the binding posts down.

The external test circuits may be made to the relay elements by #2 test clip leads instead of the test plug. When connecting an external test circuit to the current elements using clip leads, care should be taken to see that the current test jack jaws are open so that the relay is completely isolated from the external circuits. Suggested means for isolating this circuit are outlined above under "Electrical Circuits".

### Testing Out of Case

With the chassis removed from the case, relay elements may be tested by using the ten circuit test plug or by #2 test clip leads as described above. The factory calibration is made with the chassis in the case and removing the chassis from the case will change the calibration values by a small percentage. It is recommended that the relay be checked in position as a final check on calibration.

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#### Instantaneous (HZ) Element Settings

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Using equation (1)

$$TS = \frac{10 \times .90 \times 6 \times 40}{1000} = 2.16$$

Set tap 2 on the .02 to 2.0 ohm relay and core screw = 1.08.

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The index or time lever limits the motion of the disc and thus varies the time of operation. The latter decreases with lower lever settings as shown in the typical time curves.

### CAUTION

Be sure that the connector screws are turned up tight so as to make a good contact, for the operating current passes through it. Since the overload and the impedance element current coils are connected directly in the current transformer circuits the latter should be short-circuited before changing the connector screw. This can be done conveniently by inserting the extra connector screw, in the new tap and removing the old screw from its original setting.

## ADJUSTMENTS AND MAINTENANCE

The proper adjustments to insure correct operation of this relay have been made at the factory and should not be disturbed after receipt by the customer. If the adjustments have been changed, the relay taken apart for repairs, or if it is desired to check the adjustments at regular maintenance periods, the instructions below should be followed.

All contacts should be periodically cleaned with a fine file S#1002110 file is recommended for this purpose. The use of abrasive material for cleaning contacts is not recommended, because of the danger of embedding small particles in the face of the soft silver and thus impairing the contact.

#### Instantaneous Impedance (HZ) Element

Refer to Figure 3. For the 60 cycle relays adjust the stop screw on the rear of the beam to give a clearance of .025 inch between the rear of the beam and the voltage iron circuit. This may be checked with a feeler gauge. With the beam in the reset position, i.e., back against the stop, adjust the gap between the adjustable iron and the beam to .009 inch. Care should be taken in this adjustment to keep the gap the same on both sides. Also, with the beam in the same position, adjust the gap between the front end of the beam and the stop in the upper core screw to .020 inch.

The beam should be balanced as follows. Connect the relay as shown in the test diagram, Figure 11. With any tap and scale setting, check the impedance measured by the relay with 35 volts potential restraint. Apply 5 volts restraint and adjust the balance weight on the beam until the beam just trips with  $1/7$  of the current required to trip with 35 volts restraint. Make certain that the stop on the voltage side is absolutely clean, otherwise the impedance at which the beam trips may be affected, particularly at the low voltages. The stop can be easily cleaned by drawing a piece of clean white paper between the beam and the stop while the beam is firmly pressed down.

## TYPE HRZ RELAY

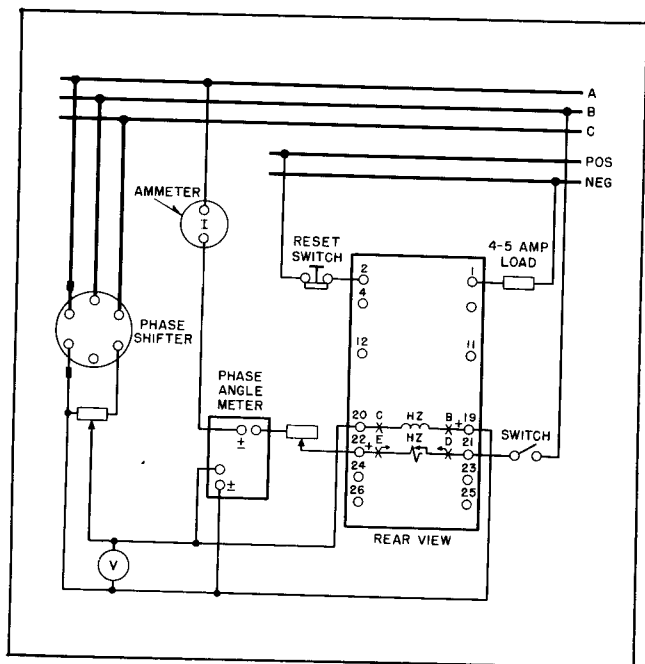
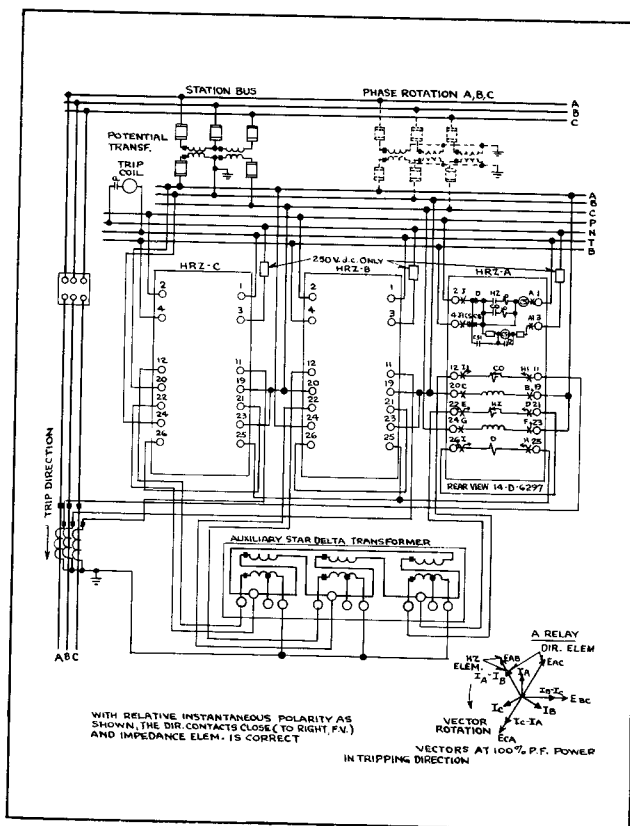


Fig. 11—Diagram of Test Connections for the Instantaneous (HZ) element of the type HRZ Relay in the type FT case. Omit Test Switches for the relay in Standard Case.

The stationary contacts should be adjusted to give .015 inch clearance between them and the silver bridge on the beam when the beam is in the reset position. The bridge should be made to touch both contacts simultaneously, and deflect the contact springs at least .010 inch before the beam strikes the bronze stop on the core screw.

It is difficult to accurately adjust the contacts by eye. A good method consists in first adjusting one of the contacts to the correct gap and then applying just sufficient current to trip the beam against a restraint of about 5 volts. While the beam is in this position, that is, lightly pressing on the one contact, the other contact should be slowly adjusted upward by means of the set screw until it just touches the silver bridge without lifting it off the other contact. The trip circuit should be energized so that the lighting of a lamp or the tripping of an auxiliary relay will show when both contacts are made.

A further caution in regard to the contact adjustment is that too much follow or deflection of the stationary contacts will slightly delay the resetting of the high-speed



\*Fig. 12—External Connections for the type HRZ Relay in the type FT case. Omit Test Switch for the relay in Standard Case.

element and thus the directional element contacts may get closed before the impedance contacts are open and result in unnecessary tripping.

Directional Element

Check the free movement of the directional element loop with the relay in a vertical position to see that it is free from friction and properly centered. The loop should assume a vertical position with the contacts open when the element is completely de-energized.

With the loop in the vertical position adjust the front and back stationary contacts for .020 inch separation from the vertical moving contact. Adjust the contact back stop screws to just touch the stationary contacts, then back off  $1/4$  of a turn to give correct contact follow. Adjust the two-stop screws which limit the movement of the loop (these screws are located to the rear of the current coil) so that the loop strikes these stops at

## TYPE HRZ RELAY

the same instant the stationary contacts strike their back stop.

Too much follow on the directional contacts should be avoided in order to allow the directional element to reset fast enough by gravity to properly coordinate with the high speed impedance element.

Energize the loop with normal potential long enough to bring it up to temperature (about 10 or 15 minutes) and adjust the bearing screws so there is about .010 inch end play. See that the loop does not bind or strike against the iron or coil when pressed against either end jewel.

The minimum pick-up of the element is 10 amperes at 2.0 volts (unity power factor). Apply these values to the element and see that contacts make good contact in the correct direction. Reverse the direction of current to see that the contacts make good contact in the opposite direction.

When the directional element is energized on voltage alone, there may be a small torque which may hold contacts either open or closed. This torque is small and shows up only at high voltages with the entire absence of current. At voltages high enough to make this torque discernible, it will be found that only a fraction of an ampere in the current coils will produce wattmeter torque to insure positive action. This is mentioned because the slight torque shown on voltage alone has no significance in actual service and has no practical effect on the directional element operation.

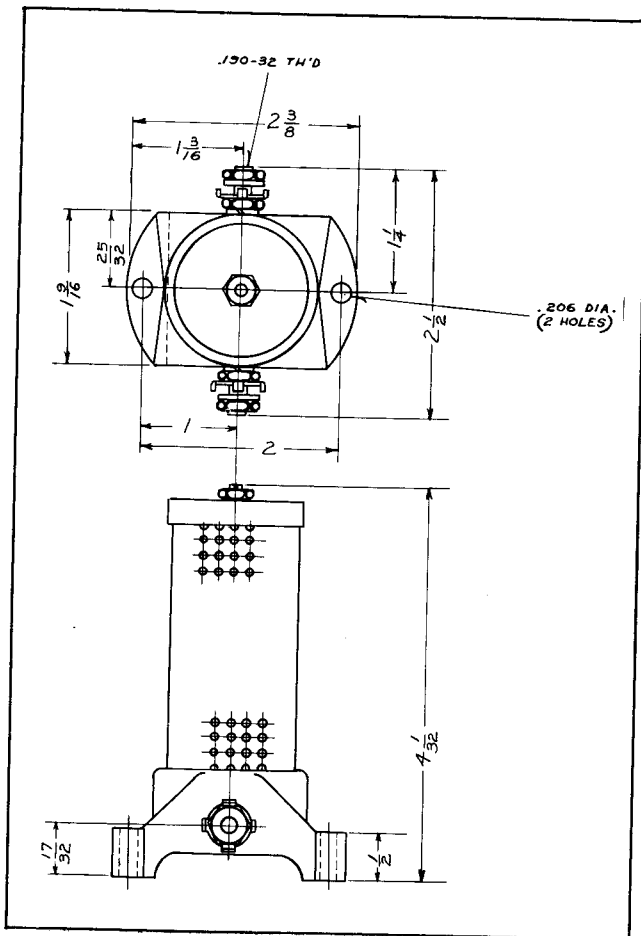
Check the coordination of the directional and impedance contacts as follows. Set the impedance element on the maximum tap and scale setting. Connect the relay with the correct polarity so that the right-hand (front view) directional contacts close and apply rated d-c volts to the directional control circuit. Apply 115 volts a-c to the impedance and directional element potential coils and pass

5 amperes at unity power factor thru the current circuit. Check trip circuit to see that it is not completed with the voltage on the impedance and directional elements is suddenly applied or interrupted. Do not interrupt the current circuit. Make several such tests. The trip circuit should draw about 5 amperes d-c for this test so that the contactor switch will pick up and seal in if the elements fail to coordinate. Otherwise, a failure to coordinate is not necessarily indicated by the flicker of a lamp, since the blocking resistor will prevent the pick-up of a trip coil plunger until the auxiliary contactor falls out. This coordination test has been described for the most severe conditions. Consequently, an occasional failure to coordinate may be tolerated, since, in service, the directional element will be resetting under the positive action of reverse power flow rather than under the influence of gravity alone, as described in this test. If proper coordination is not obtained, it may be necessary to reduce the follow on the directional or impedance element contacts, as the case may be.

### Contactor Switch (Seal-in-Switch)

Adjust the stationary core of the switch for a clearance between the stationary core and the moving core of  $1/64$ " when the switch is picked up. This can be done by turning the relay-up-side down or by disconnecting the switch and turning it up-side-down. Then screw up the core screw until the moving core starts rotating. Now, back off the core screw until the moving core stops rotating. This indicates the points where the play in the assembly is taken up, and where the moving core just separates from the stationary core screw.

Back off the core screw approximately one turn and lock in place. This prevents the moving core from striking and sticking to the stationary core because of residual magnetism. Adjust the contact clearance of  $3/32$ " by means of the two small nuts on either side of the Micarta disc. The switch should pick up at 2 amperes d.c. Test for sticking after 30 amperes have been passed through the coil.



**Fig. 13—Outline and Drilling Plan for the External Control Circuit Resistor for the 250 volt d.c. relays. For Reference Only.**

### Auxiliary Contactor Switch

(Directional Control Circuit)

The adjustments are the same as for the seal-in contactor switch except that the contact separation should be  $\frac{3}{64}$  inch. The switch should pick-up at not more than 80 volts d.c. Apply 140 volts d.c. to the circuit and see that the contacts drop out when the coil is shorted by the left-hand directional contacts. For the 250 volt d.c. relays the pick-up should be 165 volts and the contacts should drop-out when the directional element contacts short-circuit the coil with 250 to 280 volts applied to the circuit. Energize the directional element with 50 volts and 10 amperes in phase suddenly applied. The contactor switch must operate the first time the directional contacts close without flut-tering or bouncing of the contacts.

### Operation Indicator

Adjust the indicator to operate at 1.0 ampere d.c. gradually applied. Test for sticking after 30 amperes d.c. is passed through the coil.

## RENEWAL PARTS

Repair work can be done most satisfactorily at the factory. However, interchangeable parts can be furnished to the customers who are equipped for doing repair work. When ordering parts, always give the complete nameplate data.

## ENERGY REQUIREMENTS

The burdens of the various circuits of the 60 cycle relay are as follows:

**TYPE HRZ RELAY**DEFINITE MINIMUM TIME CO ELEMENT AT 60 CYCLES

Ampere Range	Tap	V.A. at 5 Amperes	V.A. at Tap Current	Power Factor	Continuous Rating (Amperes)	One Second Rating (Amperes)
2/6	2	108	17	60° lag	4	140
	2.5	68	17	60° lag	5	140
	3	47	17	60° lag	5	140
	3.5	35	17	60° lag	6	140
	4	26	17	60° lag	7	140
	5	17	17	60° lag	8	140
	6	12	17	60° lag	10	140
4/15	4	26	17	60° lag	8	250
	5	17	17	60° lag	8	250
	6	12	17	60° lag	9	250
	8	6.5	17	60° lag	10	250
	10	4.5	17	60° lag	12	250
	12	3	17	60° lag	13	250
	15	2	17	60° lag	15	250

INVERSE TIME CO ELEMENT AT 60 CYCLES

Ampere Range	Tap	V.A. at 5 Amperes	V.A. at Tap Current	Power Factor	Continuous Rating (Amperes)	One Second Rating (Amperes)
0.5/2.5	0.5	200	2	66° lag	2	70
	0.6	140	2	66° lag	2	70
	0.8	78	2	66° lag	2	70
	1.0	50	2	66° lag	3	70
	1.5	22	2	66° lag	3	70
	2.0	12.5	2	66° lag	4	70
	2.5	8	2	66° lag	5	70
2/6	2	12.4	2	66.4° lag	8	250
	2.5	8	2	66.4° lag	8	250
	3	5.6	2	66.4° lag	8	250
	3.5	4.1	2	66.4° lag	8	250
	4	3.1	2	66.4° lag	9	250
	5	2	2	66.4° lag	9	250
	6	1.3	2	66.4° lag	10	250
4/15	4	3.1	2	66.4° lag	16	250
	5	2	2	66.4° lag	16	250
	6	1.4	2	66.4° lag	16	250
	8	0.8	2	66.4° lag	17	250
	10	0.5	2	66.4° lag	18	250
	12	0.3	2	66.4° lag	19	250
	15	0.2	2	66.4° lag	20	250

VERY INVERSE TIME CO ELEMENT AT 60 CYCLES

Ampere Range	Tap	V.A. at 5 Amperes	V.A. at Tap Current	Power Factor	Continuous Rating (Amperes)	One Second Rating (Amperes)
0.5/2.5	0.5	125	1.25	66.4° lag	2	100
	0.6	87	1.25	66.4° lag	2	100
	0.8	49	1.25	66.4° lag	2	100
	1.0	31	1.25	66.4° lag	3	100
	1.5	14	1.25	66.4° lag	3	100
	2.0	8	1.25	66.4° lag	4	100
	2.5	5	1.25	66.4° lag	5	100
2/6	2	8	1.25	66.4° lag	8	250
	2.5	5	1.25	66.4° lag	8	250
	3	3.5	1.25	66.4° lag	8	250
	3.5	2.5	1.25	66.4° lag	8	250
	4	1.9	1.25	66.4° lag	9	250
	5	1.25	1.25	66.4° lag	9	250
	6	0.9	1.25	66.4° lag	10	250

# TYPE HRZ RELAY

## VERY INVERSE TIME CO RELAYS AT 60 CYCLES

(Cont'd.)

4/15	4	1.9	1.25	66.4° lag	16	250
	5	1.25	1.25	66.4° lag	16	250
	6	0.9	1.25	66.4° lag	16	250
	8	0.5	1.25	66.4° lag	17	250
	10	0.3	1.25	66.4° lag	18	250
	12	0.2	1.25	66.4° lag	19	250
	15	0.15	1.25	66.4° lag	20	250

### DIRECTIONAL ELEMENT SERIES COIL

<u>Rating</u>	<u>V.A. at 5 Amperes</u>	<u>Power Factor</u>	<u>One Second Rating (Amperes)</u>
5	3.5	45° lag	140

### DIRECTIONAL ELEMENT POTENTIAL POLARIZING COIL, ALONE

<u>Rating</u>	<u>V.A. at 115 Volts</u>	<u>Power Factor</u>
115 V	9	28° lag

### IMPEDANCE ELEMENT CURRENT COILS

<u>Tap</u>	<u>V. A. at 5 Amperes</u>	<u>Power Factor</u>
45	2.0	30° lag
13.5	0.55	30° lag

### IMPEDANCE ELEMENT POTENTIAL COILS

<u>V.A. at 115 Volts</u>	<u>Power Factor</u>
1.8	20° lag

## TYPE HRZ RELAY

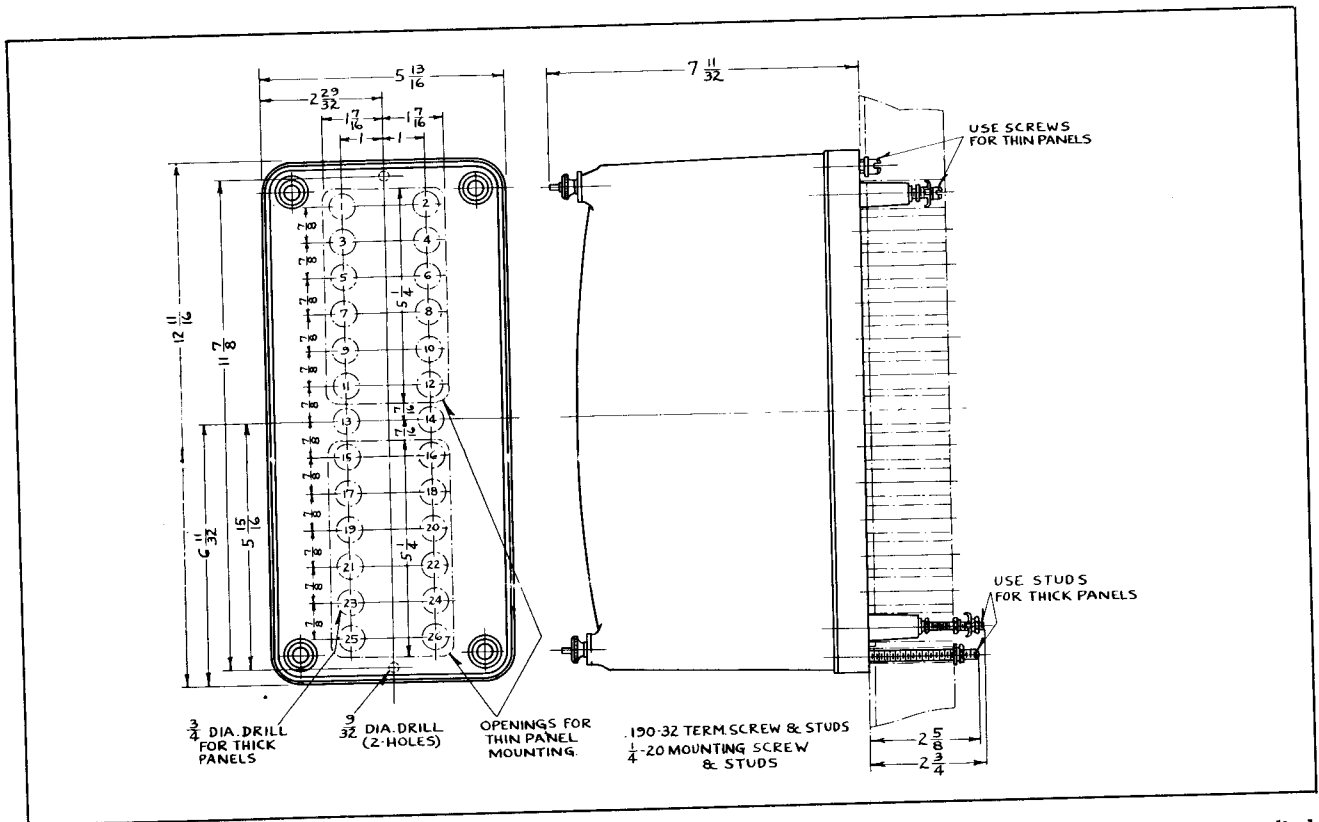


Fig. 14—Outline and Drilling Plan for the Standard Projection Type Case. See the Internal Schematics for terminals supplied. For Reference Only.

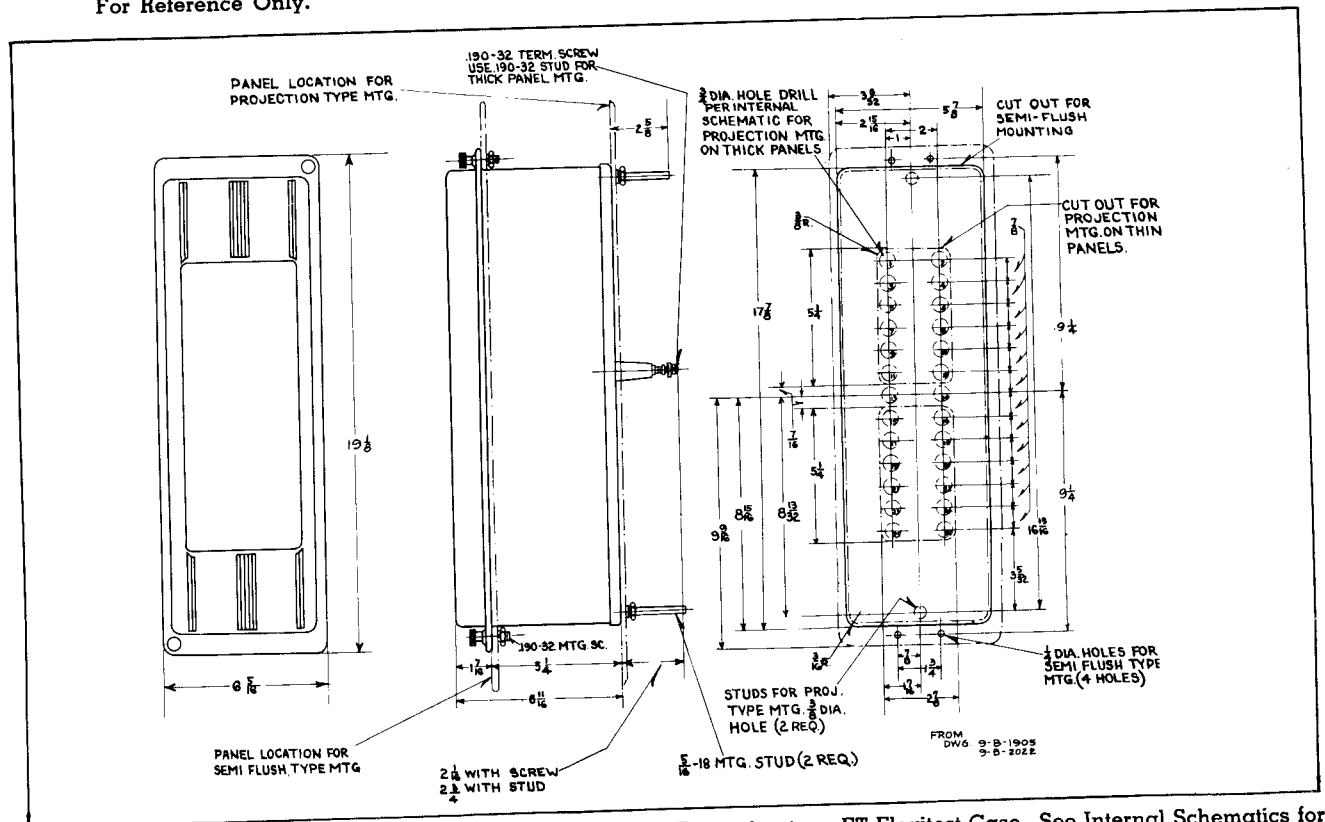


Fig. 15—Outline and Drilling Plan for the M20 Semi-flush or Projection type FT Flexitest Case. See Internal Schematics for terminals supplied. For Reference Only.









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