INSTRUCTION MANUAL

TRANSFORMER PROTECTION RELAY

GRT100 - ***B

TOSHIBA CORPORATION

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Safety Precautions

Before using this product, be sure to read this chapter carefully.

This chapter describes safety precautions when using the GRT100. Before installing and using the equipment, read and understand this chapter thoroughly.

Explanation of symbols used

Signal words such as DANGER, WARNING, and two kinds of CAUTION, will be followed by important safety information that must be carefully reviewed.

A DANGER

Indicates an imminently hazardous situation which will result in death or serious injury if you do not follow instructions.

AWARNING

Indicates a potentially hazardous situation which could result in death or serious injury if you do not follow instructions.

ACAUTION

Indicates a potentially hazardous situation which if not avoided, may result in

minor injury or moderate injury.

CAUTION

Indicates a potentially hazardous situation which if not avoided, may result in

property damage.

A DANGER

• Current transformer circuit

Never allow the current transformer (CT) secondary circuit connected to this equipment to be opened while the primary system is live. Opening the CT circuit will produce a dangerous high voltage.

AWARNING

Exposed terminals

Do not touch the terminals of this equipment while the power is on, as the high voltage generated is dangerous.

Residual voltage

Hazardous voltage can be present in the DC circuit just after switching off the DC power supply. It takes about 30 seconds for the voltage to discharge.

ACAUTION

Earth

Earth the earthing terminal of the equipment securely

CAUTION

Operation conditions

Use the equipment within the range of ambient temperature, humidity and dust as detailed in the specification and in an environment free of abnormal vibration.

Ratings

Before applying AC voltage and current or DC power supply to the equipment, check that they conform to the equipment ratings.

Printed circuit board

Do not attach and remove the printed circuit board while the DC power to the equipment is on, as this may cause the equipment to malfunction.

Battery

Avoid placing the back side of the printed circuit board with a battery (SPM board) directly on top of a metal conductor or wrapping it with metal foil, as this may short-circuit the battery power supply. However, the board may be placed on an antistatic conductive mat.

External circuit

When connecting the output contacts of the equipment to an external circuit, carefully check the supply voltage used and prevent the connected circuit from overheating.

Connection cable

Carefully handle the connection cable without applying excessive force.

Modification

Do not modify this equipment, as this may cause the equipment to malfunction, and any such

modifications will invalidate the warranty.

• Disposal

When disposing of this equipment, do so in a safe manner according to local regulations

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■ The data given in this manual are subject to change without notice. (Ver. 0.8)

1. Introduction

The GRT100 provides transformer protection for two- or three- winding power transformers connected to single, double or a one-and-a-half busbar system.

The GRT100 is member of the G-series numerical relays which are built on common hardware modules and featured with the following functions:

- Human interfaces on the relay front panel, and local and remote PCs 4 × 40 character LCD and keypad RS232C and RS485 communication ports
- Meeting and recording of event, fault and disturbance
- IRIG-B time synchronization
- Automatic supervision
- User configurable binary output

GRT100 has two model series which differ according to the number of three-phase current inputs for differential protection as follows:

Relay Type and Model

Relay Type:

- Type GRT100; Numerical transformer protection relay

Relay Model:

- Model 100 series; 2 three-phase current inputs, applied to two-winding transformers
- Model 101; 13 N/O programmable output contacts
- Model 102; 23 N/O programmable output contacts
- Model 200 series; 3 three-phase current inputs, applied to two- and three-winding transformers
- Model 201; 13 N/O programmable output contacts
- Model 202; 23 N/O programmable output contacts

Model 100 series have 2 three-phase current inputs and can be applied to two-winding transformers. Model 200 series have 3 three-phase current inputs and can be applied to two- and three-winding transformers.

2. Application Notes

2.1 Application

The GRT100 provides high-speed transformer and reactor protection, and realises high dependability and security for diverse faults such as single-phase faults, multi-phase faults, overload and over-excitation.

The GRT100 is used as a main protection and backup protection of the following transformers and reactors.

- Two-winding or three-winding power transformers
- Auto-transformers
- Generator-transformer units
- Shunt reactors

The GRT100 provides the stabilization for magnetizing inrush and overexcitation.

GRT100 provides the following metering and recording functions.

- Metering
- Fault records
- Event records
- Disturbance records

GRT100 provides the following human interfaces for relay setting or viewing of stored data.

- Relay front panel: LCD, LED display and operation keys
- Local PC
- Remote PC

The relay can be integrated with a local PC or a remote PC through a communication port. A local PC can be connected via the RS232C port on the front panel of the relay. A remote PC can also be connected through the RS485 port on the rear panel of the relay.

2.2 Protection Scheme

GRT100 provides the following protection schemes with measuring elements in parentheses. Appendix A shows block diagrams of the GRT100 series.

- Current differential protection (DIFT)
- Restricted earth fault protection (1REF-3REF)
- Time-overcurrent protection (1OC-3OC, 1OCI-3OCI, 1EF-3EF and 1EFI-3EFI)
- Thermal overload protection (THR)
- Frequency protection (FRQ)
- Overexcitation protection (V/F)
- Trip and/or indication of external devices (Buchholtz relay, pressure or temperature sensing devices etc.)

The number of measuring elements for the restricted earth fault protection and time-overcurrent protection is dependent on the relay models.

Figure 2.2.1 and 2.2.2 show the relationship between AC inputs and the measuring elements applied in each model.

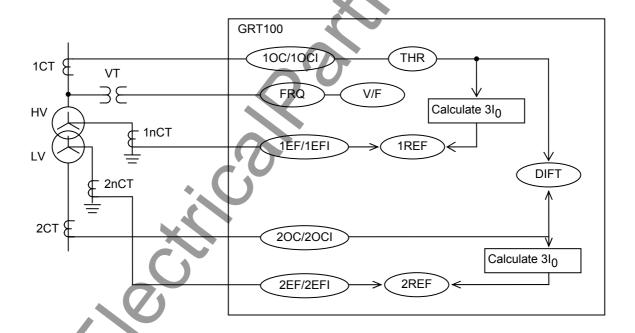


Figure 2.2.1 Measuring Elements of Model 100s

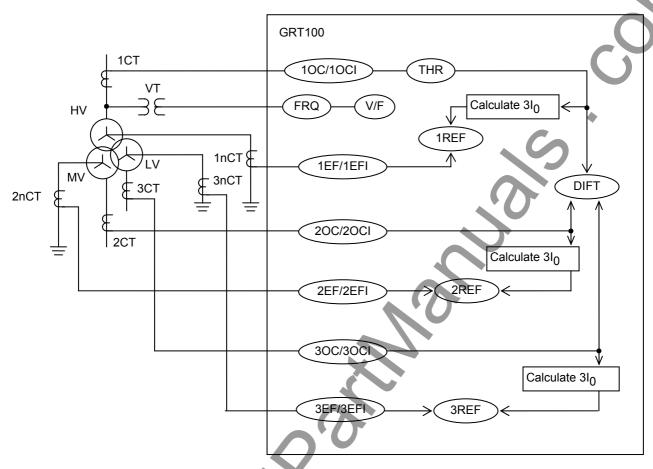


Figure 2.2.2 Measuring Elements of Model 200s

2.3 Current Differential Protection

2.3.1 Differential Scheme

Current differential protection DIFT provides an overall transformer protection deriving phase current from each transformer winding, calculating the differential current on a per phase basis and detecting phase-to-phase and phase-to-earth faults.

The current differential protection is based on Kirchhoff's first law that the vector summation of all currents flowing into a protected zone must be zero. Figure 2.3.1 shows the principle of current differential protection. Differential current (id) is the vector summation of all terminal current of the transformer. The differential current (id=i1+i2) is zero because the current (i1) equals current (-i2) during a load condition or an external fault. During an internal fault, the differential current (id) is not zero because the current (i1) does not equal to the current (-i2), and the DIFT operates.

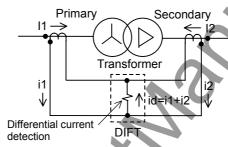


Figure 2.3.1 Current Differential Protection

Scheme logic

Figure 2.3.2 shows the scheme logic of current differential protection. Current differential element DIFT comprises sub-elements HOC, DIF, 2F and 5F which operate for the differential current on a per phase basis.

Note: For the symbols used in the scheme logic, see Appendix M.

HOC is a high-set overcurrent element operating for the differential current. It provides high-speed protection for heavy internal faults.

DIF is a percentage restraining element and has dual restraining characteristics, a weak restraint in the small current region and a strong restraint in the large current region, to cope with erroneous differential current which may be caused due to output imbalance of CTs in case of an external fault. (For the characteristics, see Section 2.11.)

DIF output signal can be blocked when 2F or 5F element detects second harmonic inrush current during transformer energization or fifth harmonic components during transformer over-excitation. The blocking is enabled by setting the scheme switch [2F-LOCK] or [5F-LOCK] to "ON". The following two blocking scheme is selectable by the scheme switch [DIFTPMD]. (For details, see Table 2.3.1.)

"3POR": When any one phase of 2F or 5F element operates, the trip by DIF element is blocked in all three phases. The "3POR" is recommended for the transformers whose second harmonic component may be low because its block function is stronger than that of the "2PAND" below.

"2PAND": Even if 2F or 5F element operates, the trip by DIF element is allowed when any two phases or more of DIF element operate. The "2PAND" is recommended for the transformers whose second harmonic component is higher. The relay does not operate due to inruch current so long as second harmonic is detected by two

phases of 2F element.

Protection by DIF and HOC can perform instantaneous three-phase tripping of up to five breakers. Any of the five breaker tripping signals DIFT-1 to DIFT-5 are enabled or disabled by the scheme switch [DIF1] to [DIF5] settings.

Table 2.3.1 Blocking Scheme during Magnetising inrush

Setting	2PAND	3POR ♠			
Scheme	Even if 2F or 5F element operates during manetising inrush, the trip by DIF element is allowed when any two phases or more of DIF element operate. When any one phase of 2F or 5F element operates during manetising inrush, to DIF element is blocked.				
Sensitivity of 2F and 5F element	$I_{2f}/I_{1f} \ge 10$ to 50% or $I_{5f}/I_{1f} \ge 10$ to 50%				
Scheme logic	Refer to Figure 2.3.2				
Response against magnetizing inrush	No problem: When second or fifth hartmonic component of any two phases is lower than their sensitivity setting, the DIF may operate.	No problem: When second or fifth hartmonic component of any one phase is higher than their sensitivity setting, the DIF is surely blocked.			
Detection at internal fault	No problem	No problem			
Application	The "2PAND" is recommended for a transformer with small or midium capacity whose second harmonic component in inrush current is genarally higher than that of transformer with large capacity.	The "3POR" is recommended for a transformer with large capacity whose second harmonic component in inrush current is generally lower. This block function is stronger than that of the "2PAND".			

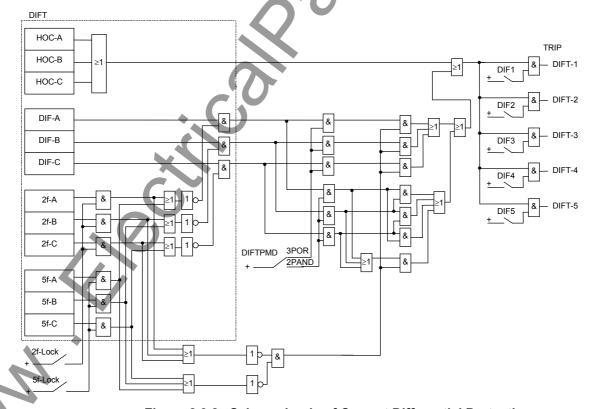


Figure 2.3.2 Scheme Logic of Current Differential Protection

2.3.2 Matching of CT Secondary Currents

In order to restrain erroneous differential currents, the currents supplied to the differential elements must be matched in phase and amplitude under through-load and through-fault conditions.

In GRT100, the matching is performed through the settings.

2.3.2.1 Matching of Phase Angle

It is necessary to compensate for phase angle difference among line currents on each side of the transformer when the transformer windings have both star- and delta-connections.

GRT100 can compensate for the phase angle difference by the setting and does not require CT secondary circuit arrangement such as delta-connection on the star-connected side of the power transformer which was common for the former transformer protection.

The phase angle matching is performed by inputting the phase angle of each winding according to the hands of a clock. For details of the setting, refer to 2.3.4.

2.3.2.2 Matching of CT Ratio

When I_1 to I_3 relevant to 1CT to 3CT secondary currents are supplied, the differential current I_d is calculated employing the following equation,

$$I_d = kct1 \cdot I_1 + kct2 \cdot I_2 + kct3 \cdot I_3$$

where kct1 to kct3 are settings corresponding to 1CT to 3CT.

The setting kct1 is obtained by using the following equation.

kct1 =
$$I_n/I_{base1}$$

= $I_n/(\sqrt{3} \times I_{base1})$ if the 1CT is delta-connected.

where

 I_n = rated secondary current of the 1CT.

 I_{base1} = secondary current of the 1CT based on the kVA rating of the power transformer.

= transformer capacity(kVA)/($\sqrt{3}$ × rated voltage(kV)) × CT ratio of 1CT

If the 1CT secondary circuit is delta-connected, $\sqrt{3} \times I_{base1}$ is used instead of I_{base1} in the equation above.

The settings kct2 and kct3 are obtained in the same way.

The differential current I_d is zero under through-load and through-fault conditions.

 $ket1 \times I_1$ to $ket3 \times I_3$ are equal to the rated secondary current of each CT when the rated line currents based on the kVA rating of the power transformer flow.

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2.3.3 Connection between CT Secondary Circuit and the GRT100

The GRT100 is provided with 2 or 3 three-phase current input terminals depending on the relay models.

To validate the phase angle matching mentioned above and input in-phase current of each winding to the relay, connect the CT secondary circuits to the current input terminal of the relay as follows;

As shown below, the phases used in the phase angle setting (indicated with arrowhead) must be connected to the AC input terminals with the least number in the terminal group such as 1, 9, 17, then other two phases should be connected to the terminals with larger number clockwise from the setting phase, such as 3 and 5, 11 and 13, or 19 and 21.

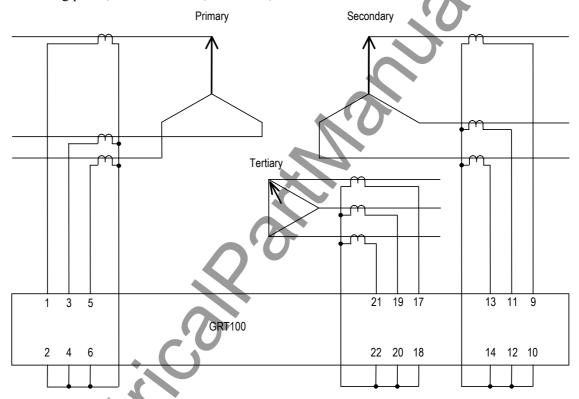


Figure 2.3.3 Connection of CT Secondary Circuit and the GRT100

Terminal numbers and corresponding input currents are shown in the following table.

Model	Terminal block	Terminal number	Input current
100 series / 200 series	TB1	1-2	
		3-4	Current of primary winding
		5-6	
		9-10	
•		11-12	Current of secondary winding
		13-14	
		17-18	
		19-20	Current of tertiary winding
		21-22	

2.3.4 Setting

The following shows the setting elements necessary for the current differential protection and their setting ranges. The setting can be performed on the LCD screen or PC screen.

Element			Range	Step	Default	Remarks
DIFT						
DIF		$i_{\mathbf{k}}$	0.10 - 1.00 (*)	0.01	0.30	Minimum operating current
		p1	10 — 100%	1%	100%	% slope of small current region
		p2	10 - 200%	1%	200%	% slope of large current region
		kp	1.00 - 20.00(*)	0.01	1.00	Break point of dual characteristics
		k2f	10 — 50%	1%	15%	Second harmonic detection
		k5f	10 — 100%	1%	30%	Fifth harmonic detection
HOC		kh	2.00 - 20.00(*)	0.01	2.00	High-set overcurrent protection
CT matching						
		kct1	0.05 - 50.00	0.01	1.00	Primary winding
CT ratio		kct2	0.05 - 50.00	0.01	1.00	Secondary winding
	L	kct3	0.05 - 50.00	0.01	1.00	Tertiary winding
		d1	0 – 11	1	0	Primary winding
Phase angle		d2	0 – 11	1	0	Secondary winding
		d3	0 – 11	1	0	Tertiary winding
Scheme switch						Enable or disable to
[DIFTPMD]			3POR / 2PAND		3POR	Trip mode
[2F - LOCK]			Off / On		On	block by second harmonic
[5F - LOCK]		•	Off / On		On	block by fifth harmonic
[DIF1] to [DIF5]]		Off / On		(**)	output tripping signal

- (*): Multiplier of CT secondary rated current including CT ratio sorrection.
- (**): Default settings are dependent on the models. See Appendix H.

Setting of ik

ik determines minimum operation sensitivity of DIF element. ik is set as a ratio to the CT secondary rated current.

Minimum setting of ik is determined from the maximum erroneous differential current under normal operating conditions.

Setting of p1, p2 and kp

Percentage restraining factor (% slope)

- = (Differential current) / (Through current)
- = (Differential current) / [{(Incoming current) + (Outgoing current)} /2]

p1 is the percentage restraining factor which defines the DIF restraining characteristic in the small current region. The setting is determined by the sum of:

- CT accuracy error (generally considered as 5%)
- Tap error: Error between maximum/minimum tap and the middle tap when taking the middle tap of the tap changer as a reference.
- Matching error: The error due to CT mismatch may be small enough to be neglected in the setting.
- Relay calculation error, and others (5%)

The recommended setting is "Sum of above" \times 1.5 (margin).

p2 is the percentage restraining factor which defines the restraining characteristic in the large current region. The setting is determined from the maximum erroneous differential current which is generated when a large through fault current flows.

kp is the break point of the dual percentage restraining characteristics. It is set above the maximum operating current level of the transformer between the maximum forced-cooled rated current and the maximum emergency overload current level, as a ratio to the CT secondary rated current.

Setting of k2f

k2f is set to detect the second harmonic content in the inrush current during transformer energization and blocks GRT100 to prevent incorrect operation due to the inrush current. A setting of 15% is suggested if there is no data on the minimum second harmonic content.

Setting of k5f

k5f is set to detect the fifth harmonic content during transformer over-excitation and blocks GRT100 to prevent incorrect operation due to transient over-excitation conditions.

A setting of 30% is suggested if there is no data on the minimum fifth harmonic content.

Setting of kh

Set above the estimated maximum inrush current.

Setting for CT ratio matching

Taking the transformer shown in Figure 2.3.4 as an example, the CT ratio matching settings kct1 to kct3 can be calculated as follows. For transformer capacity, take the maximum one from the rated capacity of the three windings.

Calculation steps		Primary	Secondary	Tertiary
(1)	Transformer capacity (kVA)		40×10^3	
(2)	Voltage(kV)	154	66	11
(3)	Rated line current(A)	150	350	2100
V	$=(1)/(\sqrt{3}\times(2))$			
(4)	CT ratio	60	120	240
(5)	Secondary rated line current(A) =(3)/(4)	2.50	2.92	8.75
(6)	CT secondary rating(A)	5	5	5
(7)	Setting =(6)/(5)	Kct1=2.00	Kct2=1.71	Kct3=0.57

Note: kct1 to kct3 should be set to 2.00 or less. If more, the CT ratio matching of relay input current may be not stable.

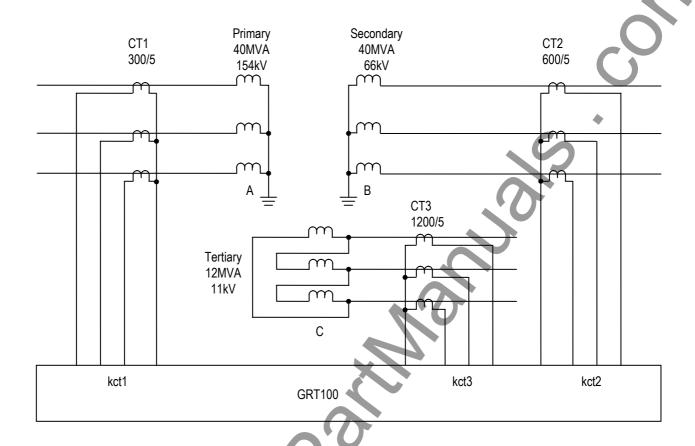


Figure 2.3.4 CT Ratio Matching

Setting for phase angle matching

The phase angle differences between line currents on each side of the power transformer are corrected by setting according to the hands of a clock as follows:

Rule 1:

If all the windings are star-connected, then take one of the windings as a reference winding and set 1 (= one o'clock) for it. For other winding(s), set the phase angle difference from the reference winding by the expression of the leading angle. One hour corresponds to leading by thirty degrees.

Example 1 If the setting winding leads the reference winding by 60°, set 3 (= three o'clock).

Example 2 If the setting winding is in phase with the reference winding, set 1 (= one o'clock).

Example 3 If the setting winding lags the reference winding by 60° (that is leading by 300°), set 11 (= eleven o'clock).

Rule 2:

If any of the windings are delta-connected, take one of the delta-connected winding(s) as a reference winding and set 0 (= noon) for it. For other star- or delta-connected winding(s), set according to the Rule 1 mentioned above.

Example 1 If the setting winding leads the reference winding by 60°, set 2 (= two o'clock).

Example 2 If the setting winding is in phase with the reference winding, set 0 (= noon).

Example 3 If the setting winding lags the reference winding by 60° (that is leading by 300°), set 10 (ten o'clock).

The settings for the two-winding transformer connections described in IEC60076-1 are listed in Table 2.3.2.

Three-winding transformers are also set according to the above mentioned rules.

Example 4 Setting for star/star/delta transformer.





Secondary



Tertiary

	Setting
Primary	11
Secondary	11
Tertiary	0

(Note) The following calculation is performed in the relay for phase angle correction.

Setting	Calculation	Remarks
0	la = la	
1	$la = (la - lc) / \sqrt{3}$	Setting value
2	la = -lc	0
3	$la = (-lc + lb)/\sqrt{3}$	11 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
4	la = lb	10 2
5	$la = (lb - la) / \sqrt{3}$	9 \longleftrightarrow 3
6	la = –la	9
7	$la = (-la + lc)/\sqrt{3}$	8 / / 4
8	la = lc	
9	$la = (lc - lb)/\sqrt{3}$	7
10	la = -lb	
11	$la = (la - lb)/\sqrt{3}$	

Table 2.3.2 Setting for Phase Angle Matching

(a) Settings for typical connections of 2-windings transformer

Transformer connections		Settings for phase angle correction	Remarks
describ	ed in IEC60076-1	Primary , Secondary)
Yy0	\downarrow	1 , 1	*
Dd0	\bigwedge	0 , 0	25
Yd1	\uparrow \land	1 , 0	
Dy1	\triangle \prec	0 , 11	
Dd2	$\triangle \triangleleft$	0 , 10 or 2 , 0	Based on primary winding. Based on secondary winding.
Dd4	\bigwedge	0 , 8 or 4 , 0	Based on primary winding. Based on secondary winding.
Yd5	\downarrow	5 , 0	
Dy5	\bigwedge \bigwedge	0 , 7	
Yy6	\downarrow	1 , 7 or 7 , 1	Based on primary winding. Based on secondary winding.
Dd6	\wedge	0 , 6 or 6 , 0	
Yd7	$\uparrow \nearrow$	7 , 0	
Dy7	★	0 , 5	
Dd8		0 , 4 or 8 , 0	Based on primary winding. Based on secondary winding.
Dd10	\triangle	0 , 2 or 10 , 0	Based on primary winding. Based on secondary winding.
Yd11	$\uparrow \nearrow$	11 , 0	
Dy11	\triangle \searrow	0 , 1	

(b) Settings for typical connections of 3-windings transformer

Transformer connections described in IEC60076-1		Settings for phase angle correction				Remarks		
		Prim	Primary, Secondary, Tertiary					Remarks
Yy0d1		1	,	1	,	0		O
Yy0d11		11	,	11	,	0	5	*
Yd1d1		1	,	0	,	0		
Yd11d11		11	,	0	,	0		
Dy11d0	$A \perp A$	0	,	1		0		
Dy1d0		0	, 4	11		0		
Dd0d0	$\bigwedge \bigwedge \bigwedge$	0	,	0	,	0		
Yy0y0		7		1	,	1		

Note:

- 1. If all the windings are star-connected, then take one of the windings as a reference winding and set 1 (= one hour) for it.
- 2. If any of the windings are delta-connected, take one of the delta-connected winding(s) as a reference winding and set 0 for it.

2.4 Restricted Earth Fault Protection

Restricted earth fault protection (REF) is a zero-phase current differential scheme and applied for a star-connected winding whose neutral is earthed directly or through a low impedance. It gives highly sensitive protection for internal earth faults.

REF employs a low impedance current differential scheme which detects the differential current between the residual current derived from the three-phase line currents and the neutral current in the neutral conductor as shown in Figure 2.4.1

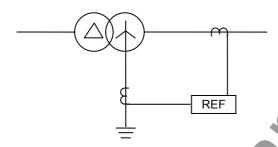


Figure 2.4.1 Restricted Earth Fault Protection

REF and the overall differential protection DIFT use the three-phase line currents in common.

GRT100 has two or three REF elements depending on the models to provide separate protection for all star-connected and neutral-earthed windings. The elements have the same percentage restraining characteristics and are stable for all faults outside the protected zone.

Figure 2.4.2 shows the scheme logic of restricted earth fault protection when three REF elements are applied. Each REF element can perform instantaneous or time-delayed tripping of up to five breakers. Any of the five breaker tripping signals 1REF-1 to 3REF-5 are enabled or disabled by the scheme switch [1REF1] to [3REF5] settings.

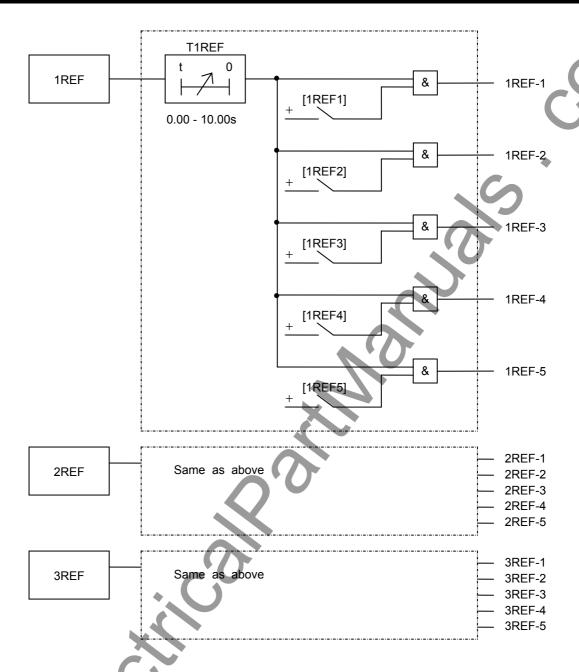


Figure 2.4.2 Scheme Logic of Restricted Earth Fault Protection

Appendix L shows applications of the three REF elements to various types of transformers. When protecting a two- or three-winding transformer, 1REF, 2REF and 3REF elements should be applied to the primary (or high-voltage) winding, secondary (or medium-voltage) winding and tertiary (or low-voltage) winding respectively. This is valid for an auto-transformer protection but the application must refer to Appendix L.

In the application to auto-transformers, one REF element may introduce two or three line currents and one neutral current as shown in the Appendix L. 1REF to 3REF elements recognize the number of the line currents according to the scheme switch setting of [1REF] to [3REF].

Setting

The following shows the setting elements for the restricted earth fault protection and their setting ranges.

Element		Range	Step	Default	Remarks
1REF	1ik	0.05 - 0.50(*)	0.01	0.50	Minimum operating current
	1kct1	1.00 - 50.00	0.01	1.00	*
	1kct2	1.00 - 50.00	0.01	1.00	CT ratio matching
	1kct3	1.00 - 50.00	0.01	1.00	
	1p2	50 — 100%	1%	100%	% slope of DF2
	1kp	0.50 - 2.00(*)	0.01	1.00	DF2 sensitivity
2REF	2ik	0.05 - 0.50(*)	0.01	0.50	Minimum operating current
	2kct1	1.00 - 50.00	0.01	1.00	
	2kct2	1.00 - 50.00	0.01	1.00	CT ratio matching
	2kct3	1.00 - 50.00	0.01	1.00	
	2p2	50 — 100%	1%	100%	% slope of DF2
	2kp	0.50 - 2.00(*)	0.01	1.00	DF2 sensitivity
3REF	3ik	0.05 - 0.50(*)	0.01	0.50	Minimum operating current
	3kct1	1.00 - 50.00	0.01	1.00	
	3kct2	1.00 - 50.00	0.01	1.00	CT ratio matching
	3kct3	1.00 - 50.00	0.01	1.00	
	3p2	50 – 100%	1%	100%	% slope of DF2
	3kp	0.50 - 2.00(*)	0.01	1.00	DF2 sensitivity
T1REF		0.00 - 10.00s	0.01s	0.00s	
T2REF		0.00 - 10.00s	0.01s	0.00s	Delayed tripping
T3REF		0.00 - 10.00s	0.01s	0.00s	
Scheme switch					
[1REF1] to [1REF5]		Off/On		(**)	Enable or disable to output
[2REF1] to [2REF5]		Off/On		(**)	tripping signal
[3REF1] to [3REF5]		Off/On		(**)	N. J. W. Starter
[1REF] to [3REF]		110/210/310		1lo	Number of line currents input to 1REF, 2REF and 3REF elements

^{(*):} Multiplier of secondary rated current

Setting of ik (1ik, 2ik and 3ik)

1ik, 2ik and 3ik of minimum operating current settings are set as a ratio to the line CT secondary rated current.

^{(**):} Default settings are dependent on the models. See Appendix H.

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Setting of kct (1kct1-1kct3, 2kct1-2kct3 and 3kct1-3kct3)

CT ratio matching is performed between the line CT(s) and the neutral CT by setting 1kct1-1kct3 for 1REF element, 2kct1-2kct3 for 2REF element and 3kct1-3kct3 for 3REF element. The settings are obtained as a ratio of the line CTs ratio to the neutral CT ratio and the line CTs have the notations shown in the Appendix L according to 1REF to 3REF applications.

For example, the settings of 1kct1, 1kct2, 2kct1 and 2kct2 are calculated;

1kct1 = (CT ratio of line CT 1ct-1)/(CT ratio of neutral CT 1nCT)

1kct2 = (CT ratio of line CT 1ct-2)/(CT ratio of neutral CT 1nCT)

2kct1 = (CT ratio of line CT 2ct-1)/(CT ratio of neutral CT 2nCT)

2kct2 = (CT ratio of line CT 2ct-2)/(CT ratio of neutral CT 2nCT)

where,

CT ratio = (primary rated current)/(secondary rated current).

Setting of scheme switch [1REF] to [3REF]

[1REF] to [3REF] are set to "1I0", "2I0" or "3I0" when they introduce one, two or three line currents respectively.

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6 F 2 S 0 7 8 9

2.5 Overcurrent Protection

GRT100 provides definite time and inverse time overcurrent elements for both phase faults and earth faults, separately for each transformer winding. Three phase currents from each set of line CTs are used for the phase fault protection elements, while the earth fault protection is based on the neutral CT input. These elements can be used selectively depending on the requirements of the particular application, but the following points should be noted:

- In the case of large power transformers, overcurrent protection is usually employed only as back-up protection for terminal faults, and for uncleared LV system faults. In such cases, the overcurrent elements can be applied either on one or both sides of the transformers as required.
- Coverage of internal transformer faults is generally limited.
- It is common practice to apply IDMTL phase and earth fault overcurrent protection as back-up for the LV system. Current and time settings must be arranged to grade with downstream relays and fuses. The phase fault current setting must also be set to exceed the maximum overload current.
- High-set instantaneous overcurrent protection can be applied on the primary side to provide back-up protection for terminal faults. The current setting must be higher than the maximum through-fault current to ensure that the element does not operate for faults on the LV side.

One of the following IEC-standard-compliant inverse time characteristics or one long time inverse characteristic is available for the inverse current protection.

• standard inverse IEC 60255-3

• very inverse IEC 60255-3

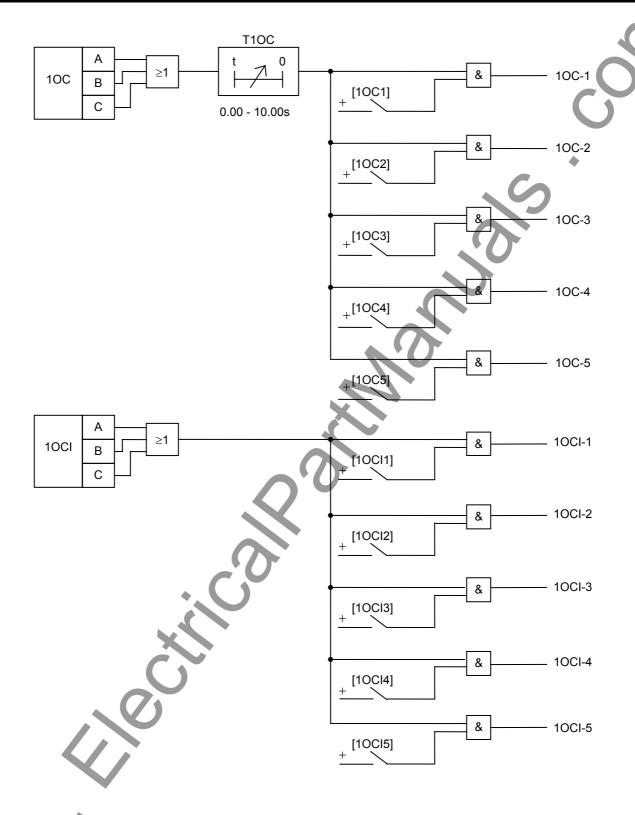
• extremely inverse IEC 60255-3

Up to three definite time elements (1OC to 3OC) and inverse time elements (1OCI to 3OCI) input three phase currents from line CTs in the transformer windings.

Up to three definite time elements (1EF to 3EF) and inverse time elements (1EFI to 3EFI) input neutral currents from CTs in the neutral circuit.

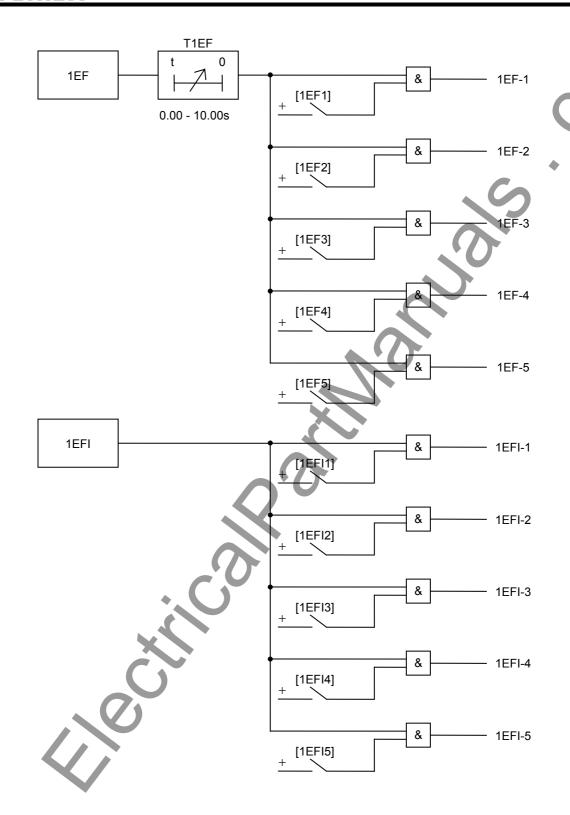
Figure 2.5.1 and Figure 2.5.2 show the scheme logic of overcurrent protection. Each element can perform time-delayed tripping of up to five breakers. The breaker tripping signals are blocked by the scheme switch settings.

The number of overcurrent elements applied depends on the relay models.



Note: 2OC and 3OC provides the same logic as 1OC. 2OCI and 3OCI provides the same logic as 1OCI.

Figure 2.5.1 Scheme Logic of the Overcurrent Protection



Note: 2EF and 3EF provides the same logic as 1EF. 2EFI and 3EFI provides the same logic as 1EFI.

Figure 2.5.2 Scheme Logic of the Overcurrent Protection for Earth Faults

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Setting

The following shows the setting elements for the overcurrent protection and their setting ranges.

Element	Range	Step	Default	Remarks
10C	0.10 – 20.0(*)	0.01	2.00	Definite time overcurrent (line)
20C	0.10 - 20.0(*)	0.01	2.00	Definite time overcurrent (line)
30C	0.10 – 20.0(*)	0.01	2.00	Definite time overcurrent (line)
T10C	0.00 - 10.00s	0.01s	1.00s	Delayed tripping for 10C
T2OC	0.00 - 10.00s	0.01s	1.00s	Delayed tripping for 20C
T3OC	0.00 - 10.00s	0.01s	1.00s	Delayed tripping for 3OC
10Cl	0.10 - 5.00(*)	0.01	1.00	Inverse time overcurrent (line)
20CI	0.10 - 5.00(*)	0.01	1.00	Inverse time overcurrent (line)
3OCI	0.10 - 5.00(*)	0.01	1.00	Inverse time overcurrent (line)
T10Cl	0.05 – 1.00	0.01	1.00	Time multiplier setting for 10Cl
T2OCI	0.05 – 1.00	0.01	1.00	Time multiplier setting for 20Cl
T3OCI	0.05 – 1.00	0.01	1.00	Time multiplier setting for 3OCI
1EF	0.10 - 20.00(*)	0.01	2.00	Definite time overcurrent (neutral)
2EF	0.10 - 20.00(*)	0.01	2.00	Definite time overcurrent (neutral)
3EF	0.10 - 20.00(*)	0.01	2.00	Definite time overcurrent (neutral)
T1EF	0.00 - 10.00s	0.01s	1.00s	Delayed tripping for 1EF
T2EF	0.00 - 10.00s	0.01s	1.00s	Delayed tripping for 2EF
T3EF	0.00 - 10.00s	0.01s	1.00s	Delayed tripping for 3EF
1EFI	0.10 - 5.00(*)	0.01	1.00	Inverse time overcurrent (neutral)
2EFI	0.10 - 5.00(*)	0.01	1.00	Inverse time overcurrent (neutral)
3EFI	0.10 - 5.00(*)	0.01	1.00	Inverse time overcurrent (neutral)
T1EFI	0.05 — 1.00	0.01	1.00	Time multiplier setting for 1EFI
T2EFI	0.05 — 1.00	0.01	1.00	Time multiplier setting for 2EFI
T3EFI	0.05 — 1.00	0.01	1.00	Time multiplier setting for 3EFI
Scheme switch				Inverse time characteristic selection of
M1OCI to M3OCI	Long-Std-Very-Ext		Std	OCI elements
M1EFI to M3EFI	Long-Std-Very-Ext		Std	EFI elements
Scheme switch	Off/On		(**)	Enable or disable tripping by
[10C1] to [30C5]				OC elements
[10Cl1] to [30Cl5]				OCI elements
[1EF1] to [3EF5]				EF elements
[1EFI1] to [3EFI5]				EFI elements

^{(*):} Multiplier of CT secondary rated current

^{(**):} Default settings are dependent on the models. See Appendix H.

The overcurrent elements use three-phase line currents and neutral current together with the differential protection and the restricted earth fault protection. For the setting, following relations between the overcurrent elements and the applying windings must be noticed.

1OC, 1OCI: Primary (high-voltage) winding

2OC, 2OCI: Secondary (medium-voltage) winding

3OC, 3OCI: Tertiary (low-voltage) winding
1EF, 1EFI: 1REF applied neutral circuit
2EF, 2EFI: 2REF applied neutral circuit
3EF, 3EFI: 3REF applied neutral circuit

2.6 Thermal Overload Protection

The thermal overload protection is applied to protect transformers from electrical thermal damage. A-phase current is used to detect the thermal overload of a transformer. The characteristics are exponential functions according to IEC 60255-8 standards and take into account the I^2R losses due to the particular operational current and the simultaneous cooling due to the coolant. In this way the tripping time during an overload condition takes the pre-load into consideration. An alarm stage can be set to operate before reaching the tripping condition.

Figure 2.6.1 shows the scheme logic of thermal overcurrent protection. THR tripping output can be given to up to five breakers. Any of the five breaker tripping signals THR-1 to THR-5 can be blocked by the scheme switch [THR1] to [THR5] settings. Alarming signal THR-A can be blocked by the scheme switch [THRA] setting.

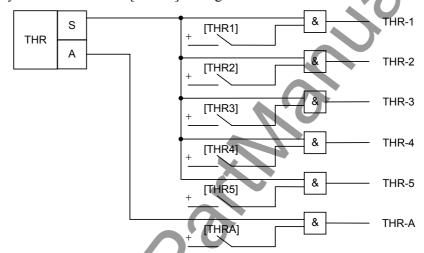


Figure 2.6.1 Scheme Logic of Thermal Overload Protection

Setting

The following shows the setting elements for the thermal overload protection and their setting ranges.

Element	Range	Step	Default	Remarks
τ	0.5 — 500.0min	0.1min	60.0min	Thermal time constant
k	0.10 - 4.00	0.01	1.30	Constant
IB	$0.50 - 2.50^{(*)}$	0.01	1.00	Basic current
lp	0.00 - 1.00(*)	0.01	0.00	Pre-specified load current
AT	0 — 10min	1min	10min	Time for alarm (before trip)
Scheme switch				Enable or disable
THR1 to THR5	Off/On		(**)	Trip
THRA	Off/On		On	Alarm

^{(*):} Multiplier of CT secondary rated current

Note: Ip sets a minimum level of previous load current to be used by the thermal element, and is typically used when testing the element. For the majority of applications, Ip should be set to zero, in which case the previous load current, Ip, is calculated internally by the thermal model, providing memory of conditions occurring before an overload.

^{(**):}Default settings are dependent on the models. See Appendix H.

2.7 Frequency Protection

GRT100 provides an underfrequency or overfrequency protection and/or alarms for load shedding or for detecting such an overfrequency condition caused by disconnecting load from a particular generation location.

The frequency element FRQ comprises two frequency elements 81-1 and 81-2, the former is used for tripping and the latter for alarms.

Figure 2.7.1 shows the scheme logic of frequency protection. The tripping element 81-1 outputs underfrequency and overfrequency trip signals L1 and H1. Either underfrequency or overfrequency protection is enabled by setting the scheme switch [FRQ-UF1] to "ON" or "OFF".

The alarm element 81-2 outputs underfrequency and overfrequency alarm signals L2 and H2. Either underfrequency or overfrequency alarms are enabled by setting the scheme switch [FRQ-UF2] to "ON" or "OFF".

Frequency protection can perform time-delayed tripping of up to five breakers. Any of the breaker tripping signals FRQ-1 to FRQ-5 can be blocked by the scheme switch [FRQ1] to [FRQ5] settings.

Alarm signal FRQ-A can be blocked by the scheme switch [FRQA] setting.

Frequency protection is blocked under the condition that the system voltage is lower than the setting of the undervoltage element UV.

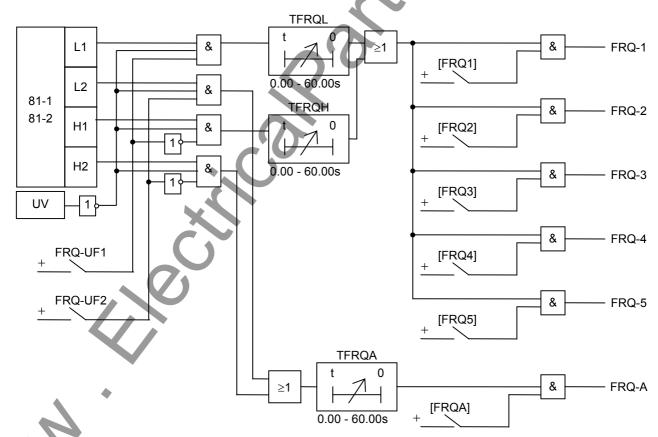


Figure 2.7.1 Scheme Logic of Frequency Protection

Setting

The following shows the setting elements for the frequency protection and their setting ranges.

Element	Range	Step	Default	Remarks
81-1 (L1, H1)	45.00 - 55.00Hz (54.00 - 66.00Hz	0.01Hz 0.01Hz	49.00Hz 59.00Hz) (*)	Trip
81-2 (L2, H2)	45.00 - 55.00Hz (54.00 - 66.00Hz	0.01Hz 0.01Hz	48.00Hz 58.00Hz)	Alarms
UV	40-100V	1V	40V	Undervoltage block
TFRQL	0.00 - 60.00s	0.01s	10.00s	Underfrequency trip time delay
TFRQH	0.00 - 60.00s	0.01s	10.00s	Overfrequency trip time delay
TFRQA	0.00-60.00s	0.01s	10.00s	Alarm time delay
Scheme switch				Enable or disable
[FRQ-UF1]	Off/On		On	Trip
[FRQ-UF2]	Off/On		On	Alarm
[FRQ1] to [FRQ5]	Off/On		(**)	Trip
[FRQA]	Off/On		On	Alarm

^{(*):} Frequency values shown in parentheses are for the case of 60Hz rating. Other frequency values are shown for the case of 50Hz rating.

^(**): Default settings are dependent on the models. See Appendix H.

2.8 Overexcitation Protection

Overexcitation protection is applied to protect transformers from overvoltage and overfluxing conditions.

Any single phase-to-phase connected voltage is used to detect overexcitation. Trip and alarm characteristics, which are based on a measurement of the voltage/frequency ratio, are provided.

Figure 2.8.1 shows the scheme logic of overexcitation protection. Overexcitation element V/F responds to voltage/frequency and outputs three signals. Signal T has an inverse time characteristic. Signals H and A have high-set and low-set definite time characteristics respectively. Signal T and signal H with a delayed pick-up timer TVFH are used for tripping. Signal A is used for alarm with a delayed pick-up timer TVFA.

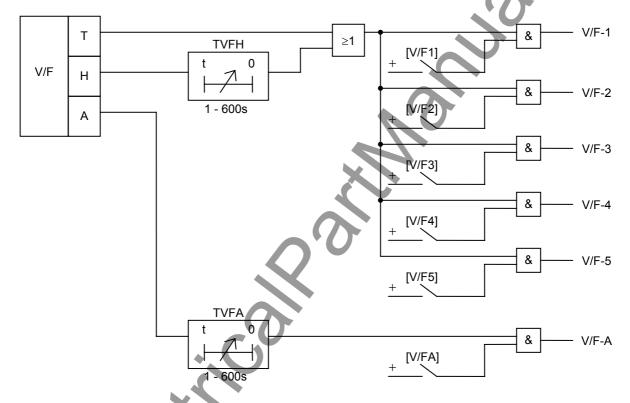


Figure 2.8.1 Scheme Logic of Overexcitation Protection

Overexcitation protection can trip up to five breakers. Any of the breaker tripping signals V/F-1 to V/F-5 can be blocked by the scheme switch [V/F1] to [V/F5] settings.

Alarm signal V/F-A can be blocked by the scheme switch [V/FA] setting.

Setting

The following shows the setting elements for the overexcitation protection and their setting ranges.

Element	Range	Step	Default	Remarks
V	100.0 - 120.0V	0.1V	100.0V	Transformer rated voltage / VT ratio
Α	$1.03 - 1.30^{(*)}$	0.01	1.03	Alarm
L	1.05 - 1.30	0.01	1.05	Low level
Н	1.10 – 1.40	0.01	1.40	High level
LT	1 – 600s	1s	600s	Operation time at low level (Inverse time curve)
HT	1 – 600s	1s	1s	Operation time at high level (Inverse time curve)
RT	60 - 3600s	1s	250s	Reset time after removing overexcitation condition
TVFH	1 – 600s	1s	10s	Operating time at high level setting (Definite time delay)
TVFA	1 - 600s	1s	10s	Alarm time (Definite time delay)
Scheme switch			X	
[V/F1] to [V/F5]	Off/On	-	(**)	Enable or disable tripping
[V/FA]	Off/On		On	Enable or disable alarm

^{(*):} Multiplier of (rated voltage) / (rated frequency)

^{(**):} Refer to Appendix H for default setting.

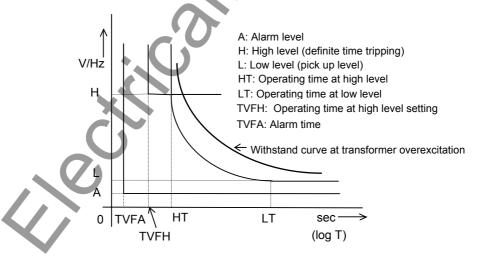


Figure 2.8.2 Setting Points

2.9 Trip by External Devices

Up to four binary signals MECANICAL TRIP1 to MECANICAL TRIP4 can be used for tripping external devices. Figure 2.9.1 shows the scheme logic for the signal MECANICAL TRIP1. The signal can trip up to five breakers. Any of the tripping signals MECHANICAL TRIP1-1 to MECHANICAL TRIP1-5 can be blocked by the scheme switches [M.T1-1] to [M.T1-5] setting.

Other binary signals have the same scheme logic.

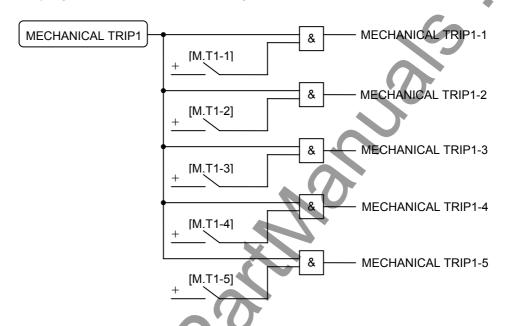


Figure 2.9.1 Scheme Logic of Trip by External Device

Setting

The following shows the setting elements for tripping by external devices and their setting ranges.

Element Rang	ge Step	Default	Remarks
Scheme switch			Enable or disable tripping
M.T1-1 to -5			
M.T2-1 to -5 Off/C)n	(*)	
M.T3-1 to -5 M.T4-1 to -5			

(*): Default settings are dependent on the models. See Appendix H.

2.10 Tripping Output

Figure 2.10.1 shows the tripping logic. Each protection can output five tripping signals to enable tripping for five breakers. The tripping signals are set according to the number of breakers to be tripped and drive the high-speed tripping output relays TRIP-1 to TRIP-5.

When the scheme switch [L/O] is set to "ON", the tripping output relays are latched and can only be reset by energising the binary input for 'Indication Reset' operation. When the switch is set to "OFF", they are reset automatically after clearing the fault.

The tripping output relays reset 200ms after the tripping signal disappears. When [L/O] is set to "OFF", the tripping circuit must be opened with the auxiliary contact of the breaker prior to reset of the tripping relay to prevent the tripping relay from directly interrupting the tripping current of the breaker.

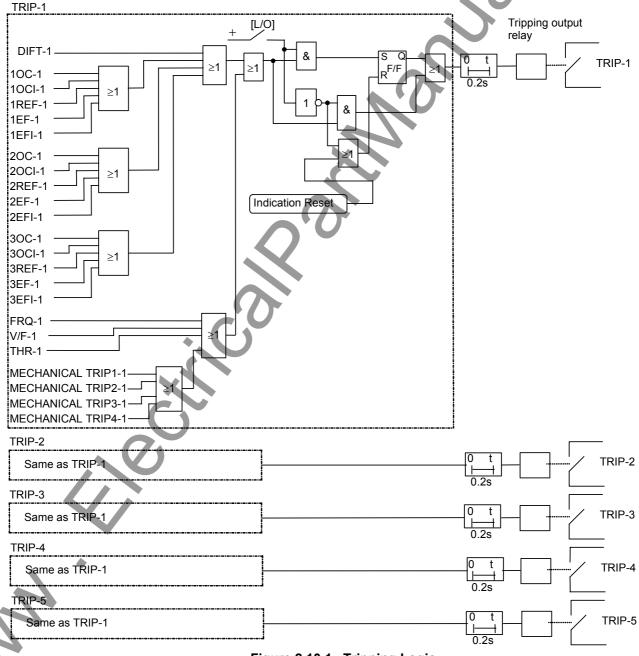


Figure 2.10.1 Tripping Logic

2.11 Characteristics of Measuring Elements

2.11.1 Percentage Current Differential Element DIF

The segregated-phase current differential element DIF has dual percentage restraining characteristics. Figure 2.11.1 shows the characteristics of DF1 and DF2 on the differential current (I_d) and restraining current (I_r) plane. I_d is a vector summation of phase current of all windings and I_r is a scalar summation of phase current of all windings.

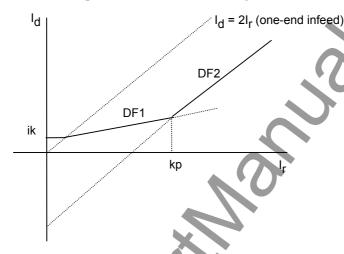


Figure 2.11.1 Current Differential Element

Characteristic DF1 is expressed by the following equation:

$$I_d \ge p1 \cdot I_r + (1 - p1/2)ik$$

where,

p1: slope of DF1

ik: minimum operating current

Id and Ir are defined as follows for a three-winding transformer.

$$I_d = |kct1 \cdot I_1 + kct2 \cdot I_2 + kct3 \cdot I_3|$$

$$I_r = (kct1 \cdot |I_1| + kct2 \cdot |I_2| + kct3 \cdot |I_3|)/2$$

where,

ket1 ,ket2 ,ket3 : CT ratio matching settings of primary, secondary and tertiary winding

I₁, I₂, I₃: currents of primary, secondary and tertiary winding

This characteristic has weaker restraint in the small current region and ensures sensitivity to low level faults.

Characteristic DF2 is expressed by the following equation:

$$I_d \ge p2 \cdot I_r + (p1 - p2)kp + (1 - p1/2)ik$$

where,

p2: slope of DF2

kp: break point of DF1 characteristic

This characteristic has stronger restraint in the large current region and ensures stability against CT saturation during through faults.

2.11.2 High-set Overcurrent Element HOC

High-set overcurrent element HOC is an instantaneous overcurrent characteristic, and is applied in the differential circuit. The characteristic is expressed by the following equation:

$$I_d \ge kh$$

Id is defined as follows for three-winding transformer.

$$I_d = |kct1 \cdot I_1 + kct2 \cdot I_2 + kct3 \cdot I_3|$$

where,

kct1, kct2, kct3: CT ratio matching settings of primary, secondary and tertiary winding

HOC is an un-restrained current differential element which can protect a transformer against damage due to a heavy internal fault, because it has a simple operation principle and high-speed operation. Note that HOC is not immune to transformer inrush currents and therefore cannot be applied with a sensitive setting.

2.11.3 Restricted Earth Fault Element REF

The restricted earth fault element REF has dual percentage restraining characteristics. Figure 2.11.2 shows the characteristics on the differential current (Id) and restraining current (Ir) plane. Id is a differential current between the residual current of each winding and the neutral current and Ir is a restraining current which is the larger of the residual current and the neutral current.

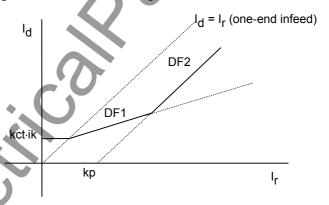


Figure 2.11.2 Restricted Earth Fault Element

Characteristic DF1 is expressed by the following equation:

$$I_d \ge p1 \cdot I_r + (1-p1) \cdot ik \cdot kct$$

where,

p1: slope of DF1 (fixed to 10%)

ik: minimum operating current

kct: CT ratio matching of line CT to neutral CT (when plural line CTs are applied, maximum kct is employed.)

For the 1REF element, I_d and I_r are calculated by the following equations when applied to a circuit

with one neutral CT and three line CTs. (For the REF element application, see Appendix L.)

$$I_d = |1kct1 \cdot I_{10} + 1kct2 \cdot I_{20} + 1kct3 \cdot I_{30} + I_N|$$

$$I_{r} = \text{max.}(|1\text{kct1} \cdot I_{1a}|, |1\text{kct1} \cdot I_{1b}|, |I1\text{kct1} \cdot I_{1c}|, |1\text{kct2} \cdot I_{2a}|, |1\text{kct2} \cdot I_{2b}|, |1\text{kct2} \cdot I_{2c}|, |1\text{kct3} \cdot I_{3a}|, |1\text{kct3} \cdot I_{3b}|, |1\text{kct3} \cdot I_{3c}|, |1\text{kct3}$$

where,

I₁₀, I₂₀, I₃₀: residual current of primary, secondary and tertiary winding

I_{1a}, I_{1b}, I_{1c}, I_{2a}, I_{2b}, I_{2c}, I_{3a}, I_{3b}, I_{3c}: phase current of primary, secondary and tertiary winding

I_N: residual current of neutral circuit

1kct1, 1kct2, 1kct3: CT ratio matching of primary, secondary and tertiary line CT to neutral CT

Characteristic DF2 is expressed by the following equation:

$$I_d \ge p2 (I_r - kp)$$

where

p2: slope of DF2

kp: break point of DF1 characteristic

2.11.4 Inverse Time Overcurrent Element OCI and EFI

The OCI and EFI elements have one long time inverse characteristic and three inverse time characteristics in conformity with IEC 60255-3 as shown in Figure 2.11.3. One of these characteristics can be selected.

These characteristics are expressed by the following equations.

Long Time Inverse

$$t = T \times \frac{120}{(I/Is)-1}$$

Standard Inverse

$$t = T \times \frac{0.14}{(I/Is)^{0.02} - 1}$$

Very Inverse

$$t = T \times \frac{13.5}{(I/Is) - 1}$$

Extremely Inverse

$$t = T \times \frac{80}{\left(I/Is\right)^2 - 1}$$

where,

t: operating time

I: fault current

Is: current setting

T: time multiplier setting

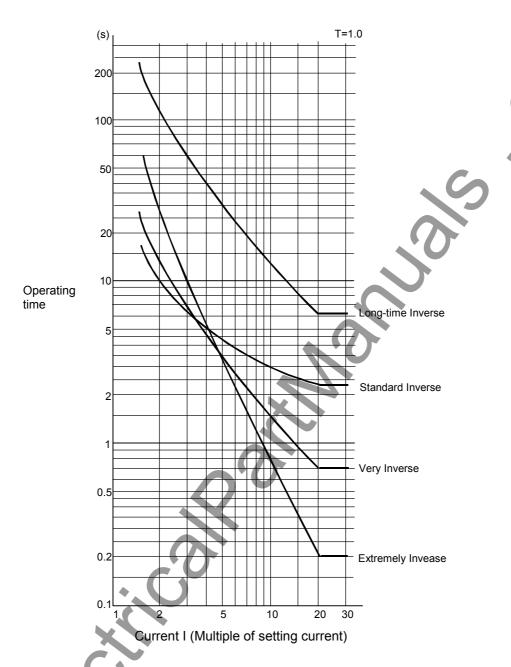


Figure 2.11.3 Characteristics of Inverse Time Overcurrent Element

2.11.5 Definite Time Overcurrent element OC and EF

The OC and EF elements measure the phase currents and the residual current respectively.

2.11.6 Thermal Overload Element THR

Thermal overload element THR has a characteristic based on thermal replica according to IEC 60255-8 standards (see Appendix N), which evaluates the phase current (A-phase) of CT secondary circuits. Figure 2.11.4 shows the characteristic of THR element. The element has trip and alarm stages.

Trip stage:

$$t = \tau \cdot Ln \frac{I^2 - Ip^2}{I^2 - (k \cdot I_B)^2}$$

Alarm stage:

$$t = \tau \cdot Ln \frac{(I^2 - Ip^2) \cdot (1 - T_A/\tau)}{I^2 - (k \cdot I_B)^2}$$

where

t: operating time

 τ : thermal time constant

I: load current

k·I_B: allowable overload current as specified in IEC 60255-8 (refer to Appendix N)

I_B: basic current of transformer (rated current)

k: constant (allowable overload current / IB)

Ip: prior load current before the overload occurs

T_A: time for alarm

Ln: natural logarithm

Figure 2.11.5 shows the thermal curve for a range of time constant settings under cold state when the prior load current Ip is zero.

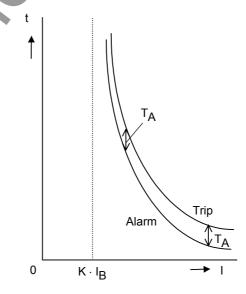


Figure 2.11.4 Characteristic of Thermal Overload Element

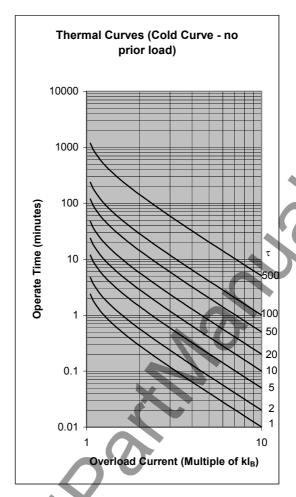


Figure 2.11.5 Thermal Curves

2.11.7 Frequency Element FRQ

GRT100 has two elements for trip or alarm. Each element operates either in overfrequency or underfrequency.

2.11.8 Overexcitation Element V/F

The characteristic is based on the ratio of voltage to frequency. The alarm is definite time delayed, while the tripping characteristic is either definite time or inverse time, as shown in Figure 2.11.7.

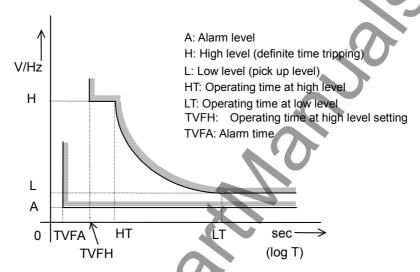


Figure 2.11.7 Characteristic of Overexcitation Element

The inverse time characteristic of V/F is expressed by the following equation.

$$t = \frac{K_2}{(V/F) - K_1}$$

where,

t: operating time

V : voltage (any phase-to-phase voltage)

F: frequency

V/F=(Vm/Fm)/(Vs/Fs)

(Vm: Input voltage, Fm: Input frequency, Vs: Setting of rated voltage, Fs: Rated frequency)

$$K_{l} = \frac{(LT) \times L - (HT) \times H}{(LT) - (HT)}$$

$$K_2 = \frac{(LT) \times (HT) \times (H - L)}{(LT) - (HT)}$$

The V/F element has a reset feature with definite time reset (RT). When the V/F falls below the reset threshold, the integral state of the inverse time function is reset to the initial value after the RT time.

Example: V/F=(Vin/Fin)/(V/Fs)=(130/50)/(100/50)=1.3, in case of Vin: Input voltage (130V), Fin: Input frequency (50Hz), V: Rated voltage (100V), Fs: Rated frequency (50Hz)

3. Technical Description

3.1 Hardware Description

3.1.1 Outline of Hardware Modules

Case outline of GRT100 is shown in Appendix F.

The hardware structures of their models are shown in Figure 3.1.1 to Figure 3.1.4. The front view shows the equipment without the human machine interface module.

The GRT100 consists of the following hardware modules. The human machine interface module is provided with the front panel.

- Transformer module (VCT)
- Signal processing module (SPM)
- Binary input and output module 1 (IO1)
- Binary input and output module 2 (IO2)
- Human machine interface module (HMI)

The following hardware modules are added depending on the model.

• Binary output module 3 (IO3)

Front view without front panel

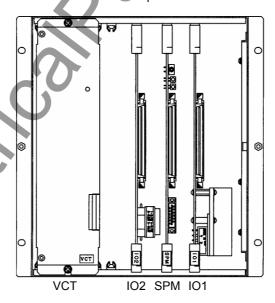


Figure 3.1.1 Hardware Structure (Model: 101, 201)

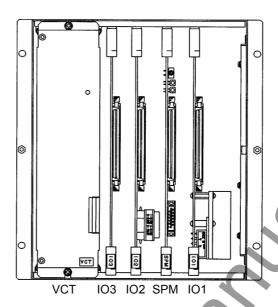


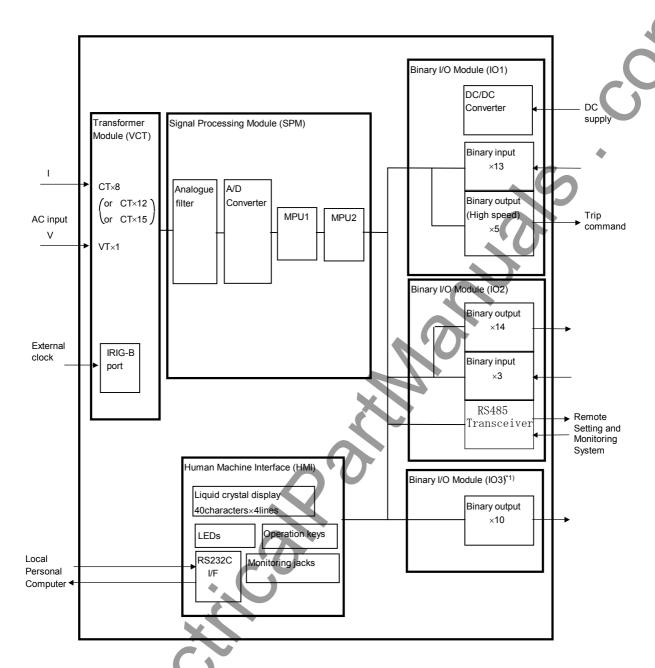
Figure 3.1.2 Hardware Structure (Model: 102, 202)

The correspondence between each model and module used is as follows:

	Models	101	102	201	202
Module			0		
VCT	_ <	×	×	×	×
SPM		×	×	×	×
IO1		×	×	×	×
IO2	-'0'	×	×	×	×
103			×		×
HMI	•	×	×	×	×

Note: The VCT and SPM modules are not interchangeable among different models.

The hardware block diagram of the GRT100 using these moduls is shown in Figure 3.1.3.



(*1) I03: required for Model 102, 202

Figure 3.1.3 Hardware Block Diagram (Models 101, 102, 201 and 202)

3.1.2 Transformer Module

The transformer module (VCT module) insulates between the internal and external circuits through an auxiliary transformer and transforms the magnitude of AC input signals to suit the electronic circuits. The AC input signals are as follows:

- three-phase currents (Ia, Ib and Ic) for a winding
- neutral current (I_N) for a winding
- phase-to-phase voltage

Figure 3.1.4 shows a block diagram of the transformer module. There are 8 to 12 auxiliary CTs and 1 auxiliary VT mounted in the transformer module depending on the relay model. (For the correspondence between the relay model and number of AC input signals, see Table 3.2.1.)

The transformer module is also provided with an IRIG-B port. This port collects the serial IRIG-B format data from the external clock for synchronization of the relay calendar clock. The IRIG-B port is insulated from the external circuit by a photo-coupler. A BNC connector is used as the input connector.

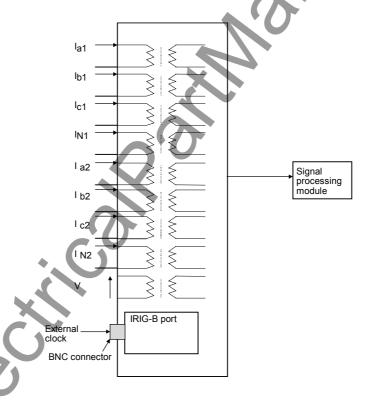


Figure 3.1.4 Transformer Module (e.g. models 101, 102)

3.1.3 Signal Processing Module

As shown in Figure 3.1.5, the signal processing module (SPM) consists of an analogue filter, multiplexer, analogue to digital (A/D) converter and main processing units (MPU1 and MPU2) and executes all kinds of processing such as protection, measurement, recording and display.

The analogue filter performs low-pass filtering for the corresponding current and voltage signals.

The A/D converter has a resolution of 16 bits and samples input signals at sampling frequencies of 2400 Hz (at 50 Hz) and 2880 Hz (at 60 Hz).

The MPU1 carries out operations for the measuring elements for protection, while the MPU2 carries out scheme logic operations, recording, display and signal transmission control. Both of them implements 60 MIPS and uses two RISC (Reduced Instruction Set Computer) type 32-bit microprocessors.

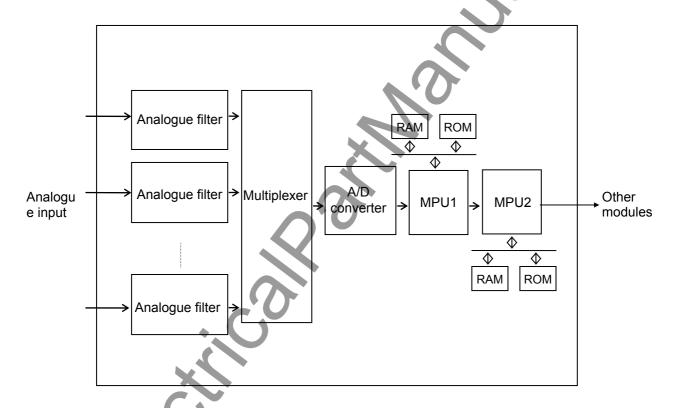


Figure 3.1.5 Signal Processing Module

3.1.4 Binary Input and Output Module

There are four types of binary input and output module (IO module): IO1 to IO3. IO1 and IO2 are used for all the relay models, while IO3 is used depending on the model (see Section 3.1.1).

3.1.4.1 IO1 Module

As shown in Figure 3.1.6, the IO1 module incorporates a DC/DC converter, 13 photo-coupler circuits (BI1-BI13) for binary input signals and 5 auxiliary relays (TP-1 to TP-5) dedicated to the circuit breaker tripping command.

The input voltage rating of the DC/DC converter is 48/60V, 110V/125V or 220V/250V. The normal range of input voltage is -20% to +20%.

The five tripping command auxiliary relays are the high-speed operation type and have one normally open output contact.

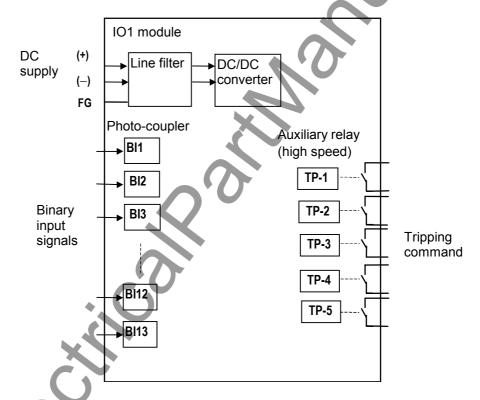


Figure 3.1.6 IO1 Module

3.1.4.2 IO2 Module

As shown in Figure 3.1.7, the IO2 module incorporates 3 photo-coupler circuits (BI14-BI16) for binary input signals, 14 auxiliary relays (BO1-BO13 and FAIL) for binary output signals and an RS-485 transceiver.

The auxiliary relay FAIL has one normally closed contact, and operates when a relay failure or abnormality in the DC circuit is detected. BO1 to BO13 each have one normally open contact. The BO12 and BO13 are the high-speed operation type.

The RS-485 transceiver is used for the link with the remote setting and monitoring (RSM) system. The external signal is insulated from the relay internal signal.

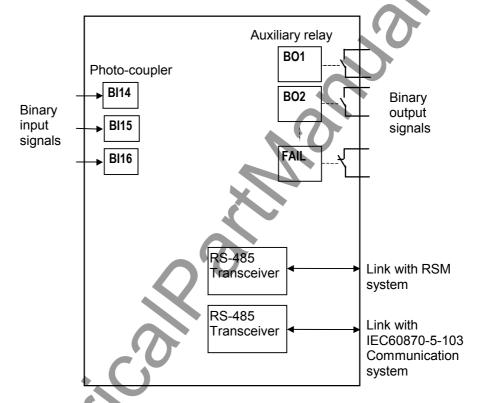


Figure 3.1.7 IO2 Module

3.1.4.3 IO3 Module

The IO3 module is used to increase the number of binary inputs or the number of binary outputs. The IO3 module incorporates 10 auxiliary relays (BO1-BO10) for binary outputs. All auxiliary relays each have one normally open contact.

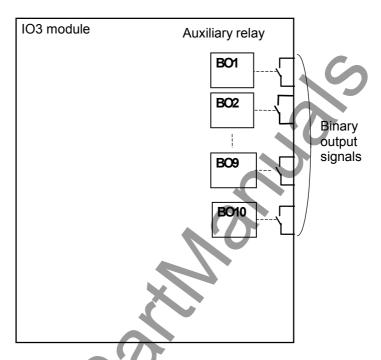


Figure 3.1.8 IO3 Module

6 F 2 S 0 7 8 9

3.1.5 Human Machine Interface (HMI) Module

The operator can access the GRT100 via the human machine interface (HMI) module. As shown in Figure 3.1.9, the HMI module has a liquid crystal display (LCD), light emitting diodes (LED), view and reset keys, operation keys, testing jacks and an RS-232C connector on the front panel.

The LCD consists of 40 columns by 4 rows with a backlight and displays record, status and setting data.

There are a total of 8 LED indicators and their signal labels and LED colors are defined as follows:

Label	Color	Remarks
IN SERVICE	Green	Lit when relay is in service.
TRIP	Red	Lit when trip command is issued.
ALARM	Red	Lit when failure is detected.
TESTING	Red	Lit when disabling automatic monitoring function or resetting the time counting of THR and V/F elements by the scheme switches.
(LED1)	Red	
(LED2)	Red	
(LED3)	Red	
(LED4)	Red	

LED1 to LED4 are user-configurable.

Once it has started operating, the TRIP LED continues to operate even after the trip command disappears. Pressing the RESET key resets it. Other LEDs operate as long as a signal is present. The RESET key is ineffective for these LEDs.

The VIEW key starts the LCD indication and switches between windows. The (RESET) key clears the LCD indication and turns off the LCD backlight.

The operation keys are used to display the record, status and setting data on the LCD, input the settings or change the settings.

The monitoring jacks and two pairs of LEDs, A and B, on top of the jacks can be used while the test mode is selected in the LCD window. Signals can be displayed on LED A or LED B by selecting the signal to be observed from the "Signal List" or "Variable Timer List" and setting it in the window and the signals can be transmitted to an oscilloscope via the monitoring jacks. (For the "Signal List" or "Variable Timer List", see Appendix B or C.)

The RS-232C connector is a 9-way D-type connector for serial RS-232C connection. This connector is used for connection with a local personal computer.

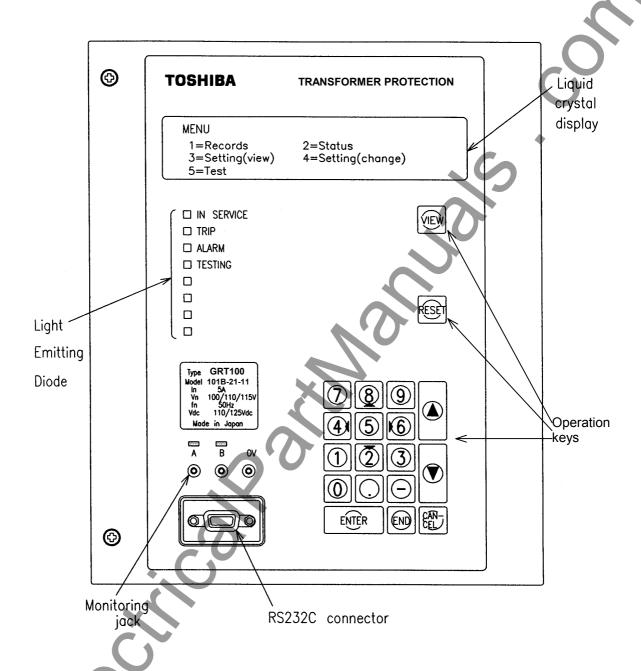


Figure 3.1.9 Front Panel

3.2 Input and Output Signals

3.2.1 Input Signals

AC input signals

Table 3.2.1 shows the AC input signals necessary for each of the GRT100 models and their respective input terminal numbers. See Appendix G for external connections.

Winding 1, 2 and 3 in the Table correspond to high-voltage or primary, medium-voltage or secondary, and low-voltage or tertiary winding respectively.

Terminal No. GRT100-101, 102 Terminal No. GRT100-201, 202 TB1 TB1 1-2 A phase current of winding 1 1-2 A phase current of winding 1 3-4 B phase current of winding 1 3-4 B phase current of winding 1 5-6 5-6 C phase current of winding 1 phase current of winding 1 7-8 Neutral current of winding 1 7-8 Neutral current of winding 1 9-10 9-10 A phase current of winding 2 A phase current of winding 2 11-12 11-12 B phase current of winding 2 B phase current of winding 2 13-14 13-14 C phase current of winding 2 C phase current of winding 2 15-16 Neutral current of winding 2 15-16 Neutral current of winding 2 17-18 17-18 A phase current of winding 3 19-20 19-20 B phase current of winding 3 21-22 21-22 C phase current of winding 3 23-24 23-24 Neutral current of winding 3 25-26 25-26 27-28 Phase to phase voltage of winding 1 27-28 Phase to phase voltage of winding 1 30 30 (earth) (earth)

Table 3.2.1 AC Input Signals

Binary input signals

Table 3.2.2 shows the binary input signals necessary for the GRT100, their driving contact conditions and functions enabled. See Appendix G for external connections.

The binary input circuit of the GRT100 is provided with a logic level inversion function as shown in Figure 3.2.1. Each input circuit has a binary switch BISW which can be used to select either normal or inverted operation. This allows the inputs to be driven either by normally open or normally closed contacts. Where the driving contact meets the contact conditions indicated in Table 3.2.2 then the BISW can be set to "N" (normal). If not, then "I" (inverted) should be selected.

The default setting of the BISW is "N" (normal) for all input signals.

Further, all binary input functions are programmable by PLC (Programmable Logic Circuit) function.

If a signal is not required, the function concerned is disabled.

The operating voltage of binary input signal is typical 74V DC at 110V/125V DC rating and 138V DC at 220/250V DC. The minimum operating voltage is 70V DC at 110/125V DC rating

and 125V DC at 220/250V DC.

Table 3.2.2	Binary In	put Signals
-------------	-----------	-------------

Signal Names	Driving Contact Condition / Function Enabled	BISW*
Mechanical trip	Closed when external device operated. / Initiate trip command	1
Mechanical trip	from operation of external device. Closed when external device operated. / Initiate trip command from operation of external device.	2
Mechanical trip	Closed when external device operated. / Initiate trip command from operation of external device.	3
Mechanical trip	Closed when external device operated. / Initiate trip command from operation of external device.	4
Indication reset	Closed to reset TRIP LED indication. / Reset indication externally.	5
Signal for event record	Closed when external device operated. / Initiate event record with external signal.	14
Signal for event record	Closed when external device operated. Initiate event record with external signal.	15
Signal for event record	Closed when external device operated. / Initiate event record with external signal.	16

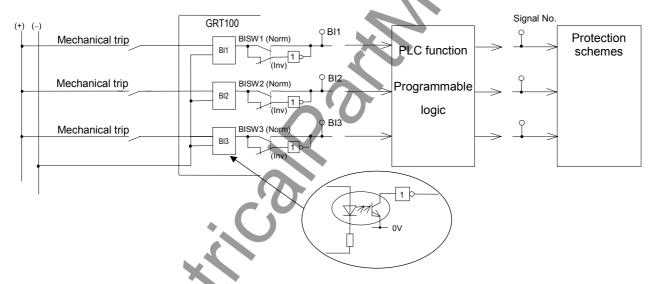


Figure 3.2.1 Logic Level Inversion

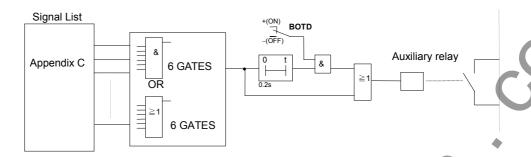
3.2.2 Binary Output Signals

The number of output binary signals and their output terminals vary depending on the relay models. See Appendix G for details. For all models, all outputs except the tripping command, signal for command protections and relay failure signal can be configured.

The signals shown in the signal list in Appendix B can be assigned to the output relay individually or in arbitrary combinations. Signals can be combined using either an AND circuit or OR circuit with 6 gates each as shown in Figure 3.2.2. The output circuit can be configured according to the setting menu. Appendix D shows the factory default settings.

A 0.2s delayed drop-off timer can be attached to these assigned signals. The delayed drop-off time is disabled by the scheme switch [BOTD].

The relay failure contact closes when a relay defect or abnormality in the DC power supply circuit is detected.



6 F 2 S 0 7 8 9

Figure 3.2.2 Configurable Output

3.2.3 PLC (Programmable Logic Controller) Function

GRT100 is provided with a PLC function allowing user-configurable sequence logics on binary signals. The sequence logics with timers, flip-flops, AND, OR, NOT logics, etc. can be produced by using the PC software "PLC editor tool" and linked to signals corresponding to relay elements or binary circuits.

Configurable binary inputs, binary outputs and LEDs, and the initiation trigger of disturbance record are programmed by the PLC function. Temporary signals are provided for complicated logics or for using a user-configured signal in many logic sequences.

PLC logic is assigned to protection signals by using the PLC editor tool. For PLC editor tool, refer to PLC TOOL instruction manual.

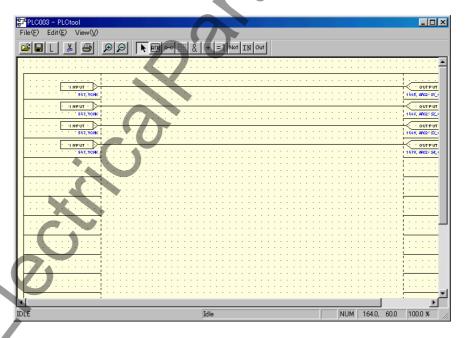


Figure 3.2.3 Sample Screen of PLC Editor

3.3 Automatic Supervision

3.3.1 Basic Concept of Supervision

Though the protection system is in a non-operating state under normal conditions, it is waiting for a power system fault to occur at any time and must operate for the fault without fail. Therefore, the automatic supervision function, which checks the health of the protection system during normal operation by itself, plays an important role. The numerical relay based on the microprocessor operations is suitable for implementing this automatic supervision function of the protection system. The GRT100 implements the automatic supervision function taking advantage of this feature based on the following concept:

- The supervising function should not affect protection performance.
- Perform supervision with no omissions wherever possible.
- When a failure occurs, it should be able to easily identify the failure location.

Note: Automatic supervision function includes automatic monitor function and automatic test function. For the terminology, refer to IEC IEV 60448.

3.3.2 Relay Monitoring and Testing

The relay is supervised with the following items

AC input imbalance monitoring

The AC current input is monitored such that the following equation is satisfied and the health of the AC input circuit is checked.

```
\begin{split} & \text{Max}(|I_a|,\,|I_b|,\,|I_c|) - 4 \times \text{Min}(|I_a|,\,|I_b|,\,|I_c|) \ \geq k0 \\ & \text{where,} \\ & \text{Max}(|I_a|,\,|I_b|,\,|I_c|) = \text{Maximum amplitude among } I_a,\,I_b \text{ and } I_c \\ & \text{Min}(|I_a|,\,|I_b|,\,|I_c|) = \text{Minimum amplitude among } I_a,\,I_b \text{ and } I_c \\ & k_0 = 20\% \text{ of rated current} \end{split}
```

A/D accuracy checking

An analogue reference voltage is transmitted to a prescribed channel in the analogue-to-digital (A/D) converter, and it is checked that the data after A/D conversion is within a prescribed range and that the A/D conversion characteristics are correct.

Memory monitoring

The memories are monitored as follows depending on the type of the memory and checked that the memory circuits are healthy:

• Random access memory monitoring:

Writes/reads prescribed data and checks the storage function.

• Program memory monitoring: Checks the checksum value of the written data.

• Setting value monitoring: Checks discrepancy between the setting values stored in

duplicate.

Watchdog Timer

A hardware timer which is cleared periodically by software is provided and it is checked that the software is running normally.

DC Supply monitoring

The secondary voltage level of the built-in DC/DC converter is monitored and checked that the DC voltage is within a prescribed range.

3.3.3 Failure Alarms

When a failure is detected by the automatic supervision, it is followed with LCD display, LEDs indication, external alarms and event recording. Table 3.3.1 summarizes the supervision items and alarms.

The LCD messages are shown on the "Auto-supervision" screen which is displayed automatically when a failure is detected or displayed by pressing the VIEW key. The event record messages are shown on the "Event record" screen by opening the "Record" sub-menu.

Those alarms are retained until the failure is recovered.

Those alarms can be disabled collectively by setting the scheme switch [AMF] to OFF. The setting is used to block unnecessary alarms during commissioning test or maintenance.

When the Watchdog Timer detects that the software fails to running normally, LCD display and event recording on the failure cannot be expected.

DC supply failure disables the LCD display and event recording on the failure as well.

For the discrimination of the two failures mentioned above, refer to Section 6.7.2.

Supervision Item	LCD Message	LED "IN SERVICE"	LED "ALARM"	Ext. alarm	Event record Message
AC input imbalance monitoring	(1)	On/Off (2)	On	(4)	CT err Relay fail
A/D accuracy check	(1)	Off	On	(4)	Relay fail
Memory monitoring					
Watchdog Timer)	Off	On	(4)	
DC supply monitoring		Off	(3)	(4)	Relay fail

Table 3.3.1 Supervision Items and Alarms

- (1): Diverse messages are provided as expressed with "---fail" in the Table in Section 6.7.2.
- (2): The LED is on when the scheme switch [SVCNT] is set to "ALM" and off when set to "ALM & BLK" (refer to Section 3.3.4).
- (3). Whether the LED is lit or not depends on the degree of the voltage drops.
- (4): The binary output relay "FAIL" operates.

3.3.4 Trip Blocking

When a failure is detected by the following supervision items, the trip function is blocked as long as the failure exists and restored when the failure is removed.

A/D accuracy check

- Memory monitoring
- Watchdog Timer
- DC supply monitoring

When a failure is detected by the AC input imbalance monitoring, the scheme switch [SVCNT] setting can be used to determine if both tripping is blocked and an alarm is initiated, or, if only an alarm is initiated.

3.3.5 Setting

The setting elements necessary for the automatic supervision and its setting range are shown in the table below.

Element	Range	Step	Default	Remarks
[SVCNT]	ALM&BLK / ALM		ALM&BLK	Alarming and/or blocking

3.4 Recording Function

The GRT100 is provided with the following recording functions:

Fault recording

Event recording

Disturbance recording

These records are displayed on the LCD of the relay front panel or on the local or remote PC.

3.4.1 Fault Recording

Fault recording is started by a tripping command of the GRT100 or PLC command by user-setting (max. 4) and the following items are recorded for one fault:

Date and time of fault occurrence

Operating phase or fault phase

Tripping command

Tripping mode

Power system quantities

Up to the 4 most-recent faults can be stored as fault records. If a new fault occurs when 4 faults have been stored, the record of the oldest fault is deleted and the record of the latest fault is then stored.

Date and time of fault occurrence

The time resolution is 1 ms using the relay internal clock.

To be precise, this is the time at which a tripping command has been initiated, and thus it is approximately 10 ms after the occurrence of the fault.

Operating phase or fault phase

The operating phase or fault phase can be selected.

The operating or fault phase is determined by differential element (DIFT) and high-set overcurrent element (HOC) operating phase.

The fault phase recording is available when the primary winding of the transformer is star-connected. However, the operating phase recording is recommended in case of a star-delta power transformer because the fault phase at the delta-winding side cannot be recorded.

The fault phase is expressed taking that of primary winding as a reference phase.

Tripping command

The tripping output relay(s) operated is shown in terms of number (e.g. TP-1: 1, TP-2: 2 etc.).

Tripping mode

This shows the protection scheme that initiated the tripping command.

Power system quantities

The following power system quantities in pre-faults and faults are recorded.

(However, the power system quantities are not recorded for evolving faults.)

- Magnitude and phase angle of phase current of each winding (I_{a1}, I_{b1}, I_{c1} up to I_{a3}, I_{b3}, I_{c3})
- Magnitude and phase angle of neutral current of each winding (I_{n1} up to I_{n3})
- Magnitude and phase angle of symmetrical component current of each winding (I₁₁, I₂₁, I₀₁ up to I₁₃, I₂₃, I₀₃)
- Magnitude and phase angle of phase-to-phase voltage (V)
- Magnitude of phase differential current (Ida, Idb, Idc)
- Magnitude of residual differential current for REF protection (Id01 up to Id03
- Frequency

Phase angles above are expressed taking that of voltage as a reference phase angle. If the voltage input is not provided, that of positive sequence current of primary winding is used as a reference phase angle.

3.4.2 Event Recording

The events shown in Table 3.4.1 are recorded with the 1 ms resolution time-tag when the status changes. The user can select the recording items.

Up to 96 records can be stored. If an additional event occurs when 96 records have been stored, the oldest event record is deleted and the latest event record is then stored.

Table 3.4.1 Event Record Items

Event	LCD Indication		
Mechanical trip 1 command output or reset	Mech. trip 1	On or Off	
Mechanical trip 2 command output or reset	Mech. trip 2	On or Off	
Mechanical trip 3 command output or reset	Mech. trip 3	On or Off	
Mechanical trip 4 command output or reset	Mech. trip 4	On or Off	
Trip command output or reset	Trip	On or Off	
Indication reset input or rest	Ind. reset	On or Off	
Relay failure detected or restored	Relay fail	On or Off	
CT1 current circuit failure detected or restored	CT1 err	On or Off	
CT2 current circuit failure detected or restored	CT2 err	On or Off	
CT3 current circuit failure detected or restored	CT3 err	On or Off	
External event signal 1 output or reset	Event 1	On or Off	
External event signal 2 output or reset	Event 2	On or Off	
External event signal 3 output or reset	Event 3	On or Off	
System setting changed (*)	Sys. set change		
Relay setting changed (*)	Rly. set change		
Group setting changed (*)	Grp. set change		

^{(*):} The event of setting change is classified into three events. The event "System setting changed" corresponds to all the setting changes except setting changes in the sub-menu "Protection". (See section 4.2.6 for changing the settings). The event "Relay setting changed" corresponds

to setting change of measuring elements and timers in the sub-menu "Protection". The event "Group setting changed" corresponds to other setting changes in the sub-menu "Protection".

Setting

The recording mode can be set for each event. One of the following four modes is selectable.

Modes	Setting
Not to record the event.	None
To record the event when the status changes to "operate".	Operate
To record the event when the status changes to "reset".	Reset
To record the event when the status changes both to "operate" and "reset".	Both

For the setting, see the Section 4.2.6.5. The default setting is "Both" for all events except those marked with (*) in Table 3.4.1. The events marked with (*) have a default setting of "Operate".

3.4.3 Disturbance Recording

Disturbance Recording is started when overcurrent starter elements operate or a tripping command is output, or PLC command by user-setting (max. 4: Signal No. 2632 to 2635) is output. The records include 13 analog signals (primary: I_{a1} , I_{b1} , I_{c1} , I_{n1} , secondary: I_{a2} , I_{b2} , I_{c2} , I_{n2} , tertiary: I_{a3} , I_{b3} , I_{c3} , I_{n3} , voltage: V). Following binary signals listed below and the dates and times at which recording started are also recorded.

-Trip-1	-5F	-20Cl	-FRQ
-Trip-2	-1REF	-30CI	-V/F
-Trip-3	-2REF	-1EF	-THR
-Trip-4	-3REF	-2EF	-Mec. Trip
-Trip-5	-100	-3EF	
-DIFT	-20C	-1EFI	
-HOC	-3OC	-2EFI	
-2F	-10CI	-3EFI	

The LCD display only shows the dates and times of disturbance records stored. Details can be displayed on the PC. For how to obtain disturbance records on the PC, see the PC software instruction manual.

The pre-fault recording time is fixed at 0.3s and post-fault recording time can be set between 0.1 and 3.0s.

The number of records stored depends on the post-fault recording time. The approximate relationship between the post-fault recording time and the number of records stored is shown in Table 3.4.2.

Note: If the recording time setting is changed, all previously recorded data is deleted.

Table 3.4.2 Post Fault Recording Time and Number of Disturbance Records Stored

Model	Recording time Frequency	0.1s	0.5s	1.0s	1.5s	2.0s	2.5s	3.0s
101	50HZ	40	21	12	9	7	6	5
102	60Hz	35	17	10	7	6	5	4
201	50HZ	31	15	9	7	5	4	♦ 3
202	60Hz	26	13	8	5	4	3	3

Disturbance recording is initiated when overcurrent elements operate, a tripping signal is output, 2F or 5F element operates or external event signals are input. Three-phase overcurrent elements 1OCP-S to 3OCP-S are applied to the line CTs and neutral overcurrent elements 1OCP-G to 3OCP-G to the neutral CTs.

The initiations are blocked by the scheme switches.

Settings

The elements necessary for starting disturbance recording and their setting ranges are shown in the table below.

Element	Range	Step Default(**)	Remarks
10CP-S	0.10 - 20.00(*)	0.01	Phase overcurrent element
20CP-S	0.10 - 20.00(*)	0.01	
3OCP-S	0.10 - 20.00(*)	0.01	
10CP-G	0.05 - 20.00(*)	0.01	Neutral overcurrent element
20CP-G	0.05 - 20.00(*)	0.01	
3OCP-G	0.05 - 20.00(*)	0.01	
Scheme switch	ON/OFF		Initiating disturbance record
TRIP1 to TRIP5	\bigcirc		by tripping
10CPS to 30CPS			by phase overcurrent element
10CPG to 30CPG	•		by neutral overcurrent element
2F			by 2F element
5F			by 5F element
EVENT1 to EVENT3			by external event

^{(*):} Multiplier of CT secondary rated current

^{(**):} Default settings are dependent on the models. See Appendix H.

6 F 2 S 0 7 8 9

3.5 Metering Function

The GRT100 performs continuous measurement of the analogue input quantities. The measurement data shown below are displayed on the LCD of the relay front panel or on the local or remote PC.

- Magnitude and phase angle of phase current of each winding (I_{a1}, I_{b1}, I_{c1} up to I_{a3}, I_{b3}, I_{c3})
- Magnitude and phase angle of neutral current of each winding (I_{n1} up to I_{n3})
- Magnitude and phase angle of symmetrical component current of each winding (I₁₁, I₂₁, I₀₁ up to I₁₃, I₂₃, I₀₃)
- Magnitude and phase angle of phase-to-phase voltage (V)
- Magnitude of phase differential current (Ida, Idb, Idc)
- Magnitude of residual differential current for REF protection (Id01 up to Id03)
- Frequency

Phase angles above are expressed taking that of positive sequence voltage as a reference phase angle, where leading phase angles are expressed plus.

The above system quantities are displayed in values on the primary side or on the secondary side of the CT by the setting. To display accurate values, it is necessary to set the CT ratio and VT ratio too. For the setting method, see "Setting the transformer parameters" in 4.2.6.7.



4. User Interface

4.1 Outline of User Interface

The user can access the relay from the front panel.

Local communication with the relay is also possible using a personal computer (PC), equipped with the RSM (Remote Setting and Monitoring) software via an RS232C port. Furthermore, remote communication is also possible using a PC equipped with the RSM via an RS485 and a protocol converter.

This section describes the front panel configuration and the basic configuration of the menu tree of the local human machine communication ports and HMI (Human Machine Interface).

4.1.1 Front Panel

As shown in Figure 3.1.13, the front panel is provided with a liquid crystal display (LCD), light emitting diodes (LED), operation keys, VIEW and RESET keys, monitoring jack and RS232C connector.

LCD

The LCD screen, provided with a 4-line, 40-character back-light, displays detailed information of the relay interior such as records, status and setting. The LCD screen is normally unlit, but pressing the VIEW key will display the digest screen and pressing any key other than VIEW and RESET will display the menu screen.

These screens are turned off by pressing the (RESET) key or (END) key. If any display is left for 5 minutes or longer without operation, the back-light will go off.

LED

There are 8 LED displays. The signal labels and LED colours are defined as follows:

	Label	Color	Remarks
	IN SERVICE	Green	Lit when the relay is in service.
	TRIP	Red	Lit when a trip command is issued.
	ALARM	Red	Lit when a failure is detected.
/	TESTING	Red	Lit when disabling automatic monitoring function or resetting the time counting of THR and V/F elements by the scheme switches.
V	(LED1)	Red	
	(LED2)	Red	
	(LED3)	Red	
	(LED4)	Red	

LED1 to LED4 are configurable.

The TRIP LED lights up once the relay is operating and remains lit even after the trip command goes off. The TRIP LED can be turned off by pressing the RESET key. Other LEDs are lit as long as a signal is present and the RESET key is invalid while the signal is being maintained.

Operation keys

The operation keys are used to display records, status, and set values on the LCD, as well as to input or change set values. The function of each key is as follows:

① 0-9, -: Used to enter a selected number, numerical values and text strings.

② ▼, ▲: Used to move between lines displayed on a screen

Keys 2, 4, 6 and 8 marked with ▼, ◀, ▶ and ▲ are also used to enter text strings.

③ CANCEL: Used to cancel entries and return to the upper screen

(4) (END): Used to end entry operation, return to the upper screen or turn off the display.

⑤ (ENTER): Used to store or establish entries.

VIEW and RESET keys

Pressing (VIEW) key displays digest screens such as "Metering", "Latest fault" and "Auto-supervision".

Pressing (RESET) key turns off the display.

Monitoring jacks

The two monitoring jacks A and B and their respective LEDs can be used when the test mode is selected on the LCD screen. By selecting the signal to be observed from the "Signal List" and setting it on the screen, the signal can be displayed on LED A or LED B, or transmitted to an oscilloscope via a monitoring jack.

RS232C connector

The RS232C connector is a 9-way D-type connector for serial RS232C connection with a local personal computer.

4.1.2 Communication Ports

The following three interfaces are provided as communication ports:

- RS232C port
- RS485 port
- IRIG-B port

RS232C port

This connector is a standard 9-way D-type connector (straight type) for serial port RS232C transmission and is mounted on the front panel. By connecting a personal computer to this connector, setting and display functions can be performed from the personal computer.

RS485 port

Two RS485 ports can be provided.

One RS485 port (PORT-1: COM1) is used to connect between relays and between the relay and the protocol converter G1PR2 to construct a network communication system. (For the system configuration, see Figure 4.4.1 in Section 4.4.) The other port (PORT-2: COM2) is used to communicate substation control and monitoring system (Protocol: IEC 60870-5-103).

This port is on the back of the relay, as shown in Figure 4.1.1.

IRIG-B port

The IRIG-B port is mounted on the transformer module, and collects serial IRIG-B format data from the external clock to synchronize the relay calendar clock. The IRIG-B port is isolated from the external circuit by a photo-coupler. A BNC connector is used as the input connector.

This port is on the back of the relay, as shown in Figure 4.1.1.

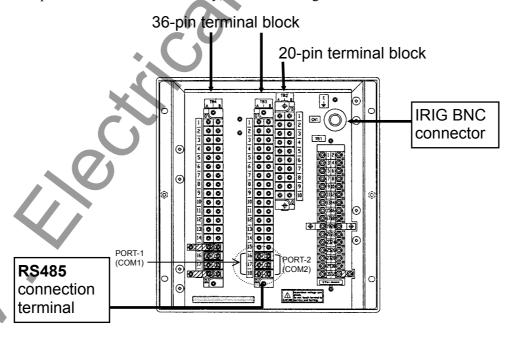


Figure 4.1.1 Locations of Communication Port

4.2 Operation of the User Interface

The user can access such functions as recording, measurement, relay setting and testing with the LCD display and operation keys.

4.2.1 LCD and LED Displays

Displays during normal operation

When the GRT100 is operating normally, the green "IN SERVICE" LED is lit and the LCD is off.

Press the VIEW key when the LCD is off to display the digest screens which are "Metering", "Latest fault" and "Auto-supervision" screens in turn. The last two screens are displayed only when there is some data. The following are the digest screens and can be displayed without entering the menu screens.

```
      Metering 1
      08/Dec/1997
      22:56

      Ia1 ***.*kA
      Ia2 **.**kA
      In1 **.**kA

      Ib1 ***.*kA
      Ib2 **.**kA
      In2 **.**kA

      Ic1 ***.*kA
      Ic2 **.**kA
```

Note: I □1 for primary(high-voltage) winding current

I $\square 2$ for secondary(medium-voltage) winding current

I □3 for tertiary(low-voltage) winding current

Ia□, Ib□, Ic□ for phase current

In ☐ for neutral current

```
Auto-supervision 08/Dec/1997 22:56
D10 err
```

Press the RESET key to turn off the LCD.

For any display, the back-light is automatically turned off after five minutes.

Displays in tripping

If a fault occurs and a tripping command is initiated when the LCD is off, the "Latest fault" screen is displayed on the LCD automatically and the red "TRIP" LED lights.

Press the <u>(VIEW)</u> key to display the digest screens in turn including the "Metering" and "Auto-supervision" screens.

Press the (RESET) key to turn off the LEDs and LCD display.

If the tripping command is initiated when any of the screens is displayed, the current screen remains displayed and the red "TRIP" LED lights.

When any of the menu screens is displayed, the VIEW and RESET keys do not function. To return to the digest screen, do the following:

- Return to the top screen of the menu by repeatedly pressing the END key.
- Press the (END) key to turn off the LCD.
- Press the VIEW key to display the digest screen.
- Press the (RESET) key to turn off the "TRIP" LED and LCD.

Displays in automatic supervision operation

If the automatic supervision function detects a failure while the LCD is off, the "Auto-supervision" screen is displayed automatically, showing the location of the failure and the "ALARM" LED lights.

Press the VIEW key to display other digest screens in turn including the "Metering" and "Latest fault" screens.

Press the (RESET) key to turn off the LCD display. However, the "ALARM" LED remains lit if the failure continues.

After recovery from a failure, the "ALARM" LED and "Auto-supervision" display turn off automatically.

If a failure is detected while any of the screens is displayed, the current screen remains displayed and the "ALARM" LED lights.

While any of the menu screens is displayed, the VIEW and RESET keys do not function. To return to the digest "Auto-supervision" screen, do the following:

- Return to the top screen of the menu by repeatedly pressing the END key.
- Press the END key to turn off the LCD.
- Press the VIEW key to display the digest screen.
- Press the RESET key to turn off the LCD.

4.2.2 Relay Menu

Figure 4.2.1 shows the menu hierarchy in the GRT100. The main menu has five sub-menus, "Record", "Status", "Setting (view)", "Setting (change)", and "Test". For details of the menu hierarchy, see Appendix E.

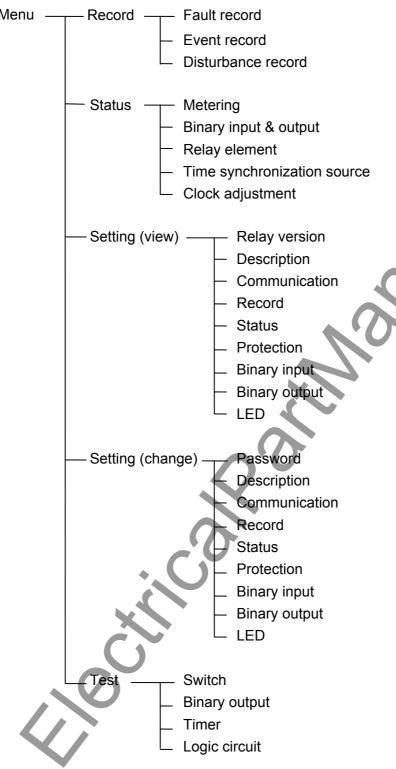


Figure 4.2.1 Relay Menu

Record

In the "Record" menu, the fault records, event records and disturbance records are displayed or erased.

Status

The "Status" menu displays the power system quantities, binary input and output status, relay measuring element status, signal source for time synchronization (IRIG-B, RSM or IEC) and adjusts the clock.

Setting (view)

The "Setting (view)" menu displays the relay version, plant name and the current settings of relay address and RS232C baud rate in communication, record, status, protection, configurable binary inputs and outputs, and configurable LEDs.

Setting (change)

The "Setting (change)" menu is used to set or change the settings of password, plant name, relay address and RS232C baud rate in communication, record, status, protection, configurable binary inputs and outputs, and configurable LEDs.

Since this is an important menu and is used to set or change settings related to relay tripping, it has password security protection.

Test

The "Test" menu is used to set testing switches, to forcibly operate binary output relays, to measure variable timer time and to observe the binary signals in the logic circuit.

When the LCD is off, press any key other than the VIEW and RESET keys to display the top "MENU" screen and then proceed to the relay menus.

```
MENU
1 = Record 2 = Status
3 = Setting (view) 4 = Setting (change)
5 = Test
```

To display the "MENU" screen when the digest screen is displayed, press the [RESET] key to turn off the LCD, then press any key other than the VIEW and [RESET] keys.

Press the END key when the top screen is displayed to turn off the LCD.

An example of the sub-menu screen is shown below. The top line shows the hierarchical layer of the screen, screen title and total number of lines of the screen. The last item is not displayed for all the screens. "/6" displayed on the far left means that the screen is in the sixth hierarchical layer, while 1/7 displayed on the far right means that the screen has seven lines excluding the top line and that the cursor is on the first line.

To move the cursor downward or upward for setting or for viewing other lines not displayed on the window, use the ∇ and \triangle keys.

/6 V T	& CT	r a t	tio			1 / 7
1 C T	(1 -	20000):	2000	_	
2 C T	(1 -	20000):	1 0 0 0		
3 C T	(1 -	20000):	4 0 0		
1 n C T	(1 -	20000):	100		
2 n C T	(1 -	20000):	100		
3 n C T	(1 -	20000):	100		
V T	(1 -	20000):	400		

To move to the lower screen or move from the left-side screen to the right-side screen in Appendix E, select the appropriate number on the screen. To return to the higher screen or move from the right-side screen to the left-side screen, press the END key.

The CANCEL key can also be used to return to the higher screen but it must be used carefully because it may cancel entries made so far.

To move between screens of the same hierarchical depth, first return to the higher screen and then move to the lower screen.

4.2.3 Displaying Records

The sub-menu of "Record" is used to display fault records, event records and disturbance records.

4.2.3.1 Displaying Fault Records

To display fault records, do the following:

- Open the top "MENU" screen by pressing any keys other than the VIEW and RESET keys.
- Select 1 (= Record) to display the "Record" sub-menu.

```
/ 1 Record
1 = Fault record
2 = Event record
3 = Disturbance record
```

• Select 1 (= Fault record) to display the "Fault record" screen.

```
/2 Fault Record
1=Display 2=Clear
```

• Select 1 (= Display) to display the dates and times of fault records stored in the relay from the top in new-to-old sequence.

```
/3 Fault record 1/4

#1 16/0ct/1997 18:13:57.031

#2 20/Sep/1997 15:29:22.463

#3 04/Jul/1997 11:54:53.977
```

• Move the cursor to the fault record line to be displayed using the \triangle and ∇ keys and press the ENTER key to display the details of the fault record.

```
Fault Record #1
16/Oct/1997
                 18:13:57.031
Phase BC
                              Trip
                                       1-2-3-4-5
DIFT
Prefault
             values
                   ***. *°
                                                  ***. *°
I a 1 **. ** k A
                              la2 **. **kA
                   ***. *°
      **. ** k A
                              1 b 2
                                    **. ** k A
                   ***. *°
      **. ** k A
                              1 c 2
                                    **. ** k A
                   ***. *°
      **. ** k A
                              1 1 2
                   ***. *°
      **. ** k A
                              1 2 2
                   ***. *°
      **. ** k A
                              102
                                    **. ** k A
      **. ** k A
                   ***. *°
                              1 n 2
I a 3
      **. ** k A
      **. ** k A
I b 3
      **. ** k A
I c 3
I 1 3
      **. ** k A
      **. ** k A
I 2 3
      **. ** k A
I 0 3
      **. ** k A
I n 3
                   *** *°
      ***. * k V
V
      ***. **pu
Ida
Ιdb
      ***. **pu
Fault
         values
I a 1
      **. ** k A
I b 1
          * * k A
          * * k A
                                c 2
                                1 2
I 1 1
          * * k A
I 2 1
          * * k A
                              1 2 2
                                         * * k A
I 0 1
                              102
          * * k A
                                         * * k A
                              1 n 2
I n 1
          * * k A
I a 3
          * * k A
I b 3
I c 3
I 1 3
I 2 3
I 0 3
I n 3
                               l d 0 1
       * * .
            **pu
                               ld02 ***. **pu
      ***. **pu
                               ld03 ***. **pu
```

Note: I \square 1 for primary(high-voltage) winding current

I $\square 2$ for secondary(medium-voltage) winding current

I □3 for tertiary(low-voltage) winding current

In□ for neutral current

I1□, I2□, I0□ for symmetrical component current

Ida, Idb, Idc for differential current

Ido1, Ido2, Ido3 for zero-phase differential current in 1REF, 2REF, 3REF

The lines which are not displayed in the window can be displayed by pressing the \triangle and ∇ keys.

To clear all the fault records, do the following:

• Open the "Record" sub-menu.

- Select 1 (Fault record) to display the "Fault record" screen.
- Select 2 (= Clear) to display the following confirmation screen.

```
/2 Fault record
Clear all fault records?
ENTER=Yes CANCEL=No
```

• Press the ENTER (= Yes) key to clear all the fault records stored in non-volatile memory.

If all fault records have been cleared, the "Latest fault" screen of the digest screens is not displayed.

4.2.3.2 Displaying Event Records

To display events records, do the following:

- Open the top "MENU" screen by pressing any keys other than the VIEW and RESET keys.
- Select 1 (= Record) to display the "Record" sub-menu.
- Select 2 (= Event record) to display the "Event record" screen.

```
/2 Event Record
1 = Display 2 = Clear
```

• Select 1 (= Display) to display the events with date and time from the top in new-to-old sequence.

```
/3 Event record 2/48
16/0ct/1998 23:18:04.294 Trip Off
16/0ct/1998 23:18:03.913 Trip On
12/Feb/1998 03:51:37.622 Rly.set change
```

The lines which are not displayed in the window can be displayed by pressing the \triangle and ∇ keys.

To clear all the event records, do the following:

- Open the "Record" sub-menu.
- Select 2 (Event record) to display the "Event record" screen.
- Select 2 (= Clear) to display the following confirmation screen.

```
/2 Event record
Clear all event records?
ENTER=Yes CANCEL=No
```

• Press the ENTER (= Yes) key to clear all the event records stored in non-volatile memory.

4.2.3.3 Displaying Disturbance Records

Details of the disturbance records can be displayed on the PC screen only (*); the LCD displays only the recorded date and time for all disturbances stored in the relay. To display them, do the

following:

(*) For the display on the PC screen, refer to RSM100 manual.

- Open the top "MENU" screen by pressing any keys other than the VIEW and RESET key
- Select 1 (= Record) to display the "Record" sub-menu.
- Select 3 (= Disturbance record) to display the "Disturbance record" screen.

```
/ 2 Disturbance record
1 = Display 2 = Clear
```

• Select 1 (= Display) to display the date and time of the disturbance records from the top in new-to-old sequence.

```
/3 Disturbance record 3/12
#1 16/0ct/1997 18:13:57.031
#2 20/Sep/1997 15:29:22.463
#3 04/Jul/1997 11:54:53.977
```

The lines which are not displayed in the window can be displayed by pressing the \triangle and ∇ keys.

To clear all the disturbance records, do the following:

- Open the "Record" sub-menu.
- Select 3 (Disturbance record) to display the "Disturbance record" screen.
- Select 2 (= Clear) to display the following confirmation screen.

```
/2 Disturbance record
Clear all disturbance records?
ENTER=Yes CANCEL=No
```

• Press the ENTER (= Yes) key to clear all the disturbance records stored in non-volatile memory.

4.2.4 Displaying the Status

From the sub-menu of "Status", the following statuses can be displayed on the LCD:

Metering data of the protected transformer

Status of binary inputs and outputs

Status of measuring elements output

Status of time synchronization source

The data are renewed every second.

This sub-menu is also used to adjust the time of the internal clock.

4.2.4.1 Displaying Metering Data

To display metering data on the LCD, do the following.

• Select 2 (= Status) on the top "MENU" screen to display the "Status" screen.

```
/1 Status
1 = Metering 2 = Binary I/0
3 = Relay element 4 = Time sync source
5 = Clock adjustment
```

• Select 1 (= Metering) to display the "Metering" screen.

```
Metering
I b 1
                                   I b 2
I c 1
                                   I c 2
             * * k A
I 1 1
                                   I 1 2
I 2 1
               * k A
                                   I 2 2
I 0 1
I n 1
I a 3
I b 3
I c 3
I 1 3
I 2 3
I 0 3
I n 3
Ida
Ιdb
Idc
T H M
Frequency
                                     **. * H Z
```

Note: I 1 for primary(high-voltage) winding current

I 2 for secondary(medium-voltage) winding current

1 □3 for tertiary(low-voltage) winding current

Ia \square , Ib \square , Ic \square for phase current

In□ for neutral current

I1□, I2□, I0□ for symmetrical component current

Ida, Idb, Idc for differential current

Ido1, Ido2, Ido3 for zero-phase differential current in 1REF, 2REF, 3REF

Metering data is expressed as primary values or secondary values depending on the setting. For setting, see Section 4.2.6.6.

TOSHIBA

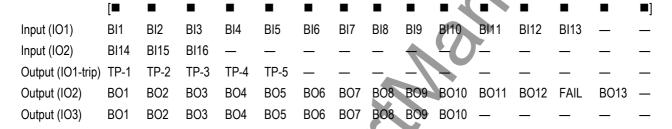
4.2.4.2 Displaying the Status of Binary Inputs and Outputs

To display the binary input and output status, do the following:

- Select 2 (= Status) on the top "MENU" screen to display the "Status" screen.
- Select 2 (= Binary I/O) to display the binary input and output status.

/2 Binary input &	output		3 / 5
Input (I01)	$[\ 0\ 0\ 0\ 0\ 0\ 0\ 0$	0 0 0	0000]
Input (I02)	[0 0 0]		
0 u t p u t (I 0 1 - t r i p)	[000000		
0 u t p u t (I 0 2)	[000 000	0 0 0	000 00]
0 u t p u t (I 0 3)	[0 0 0 0 0 0 0]	0 0 0	0]

The display format is shown below.



Lines 1 and 2 show the binary input status. BI1 to BI16 corresponds to each binary input signal. For details of the binary input signals, see Appendix G. The status is expressed with logical level "1" or "0" at the photo-coupler output circuit. IO1 and IO2 in the table indicate the name of the module containing the binary input circuits.

Lines 3 to 5 show the binary output status. TP-1 to TP-5 of line 3 corresponding to the tripping command output. FAIL of line 4 corresponds to the relay failure output. Other outputs expressed with BO1 to BO13 are configurable. The status of these outputs is expressed with logical level "1" or "0" at the input circuit of the output relay driver. That is, the output relay is energized when the status is "1".

IO1 to IO3 in the table indicate the names of the module containing the binary output relays.

To display all the lines, press the \triangle and ∇ keys.

4.2.4.3 Displaying the Status of Measuring Elements

To display the status of the measuring elements on the LCD, do the following:

- Select 2 (= Status) on the top "MENU" screen to display the "Status" screen.
- Select 3 (= Relay element) to display the status of the relay elements.

/2 Relay element					3 /	9
DIFT	[0000	0 0 0	0 0 0	0 0 0		7
REF	[0000					
0 C	[000]	0 0 0	0 0 0			7
0 C I	Γ000	0 0 0	0 0 0			1
EF	[0000			(/	-	٦
EFI	[0000		4			٦
THR	[00]					٦
V / F	[0000					٦
FRQ	[000]	0	1			٦

The display format is as shown below.

	[■						-								■]
DIET	Α	В	С	Α	В	С	A	В	C	A	В	С	_	_	_
DIFT		DIF			2F		X	5F			HOC				
REF	1	2	3	_	_	-		_	_	_	_	_	_	_	_
OC	Α	В	С	Α	В	C	A	В	С	_	_	_	_	_	_
00		10C			20C			30C							
OCI	A	В	С	A	В	C	A	В	С	_	_	_	_	_	_
EF	1	10CI 2	3		20CI	_	_	30CI —	_	_	_	_	_	_	_
EFI	1	2	3) _	_	_	_	_	_	_	-	_	_	_
THR	S	Α	X	_	_	_	_	_	_	_	_	_	_	_	_
V/F	Н	Т	A	_	_	_	_	_	_	_	_	_	_	_	_
FRQ	L1	L2	H1	H2	_	_	_	_	_	_	_	_	_	_	_

Line 1 shows the operation status of current differential elements. Line 2 shows the status of restricted earth fault elements. Line 3 shows the status of overcurrent elements. Line 4 shows the status of time overcurrent elements. Line 5 shows the status of the overcurrent element for earth fault. Line 6 shows the status of time overcurrent elements for earth fault. Lines 7, 8 and 9 show the status of thermal overload element, overexcitation element and frequency element respectively.

The status of each element is expressed with logical level "1" or "0". Status "1" means the element is in operation.

To display all the lines on the LCD, press the \triangle and ∇ keys.

4.2.4.4 Displaying the Status of the Time Synchronization Source

The internal clock of the GRT100 can be synchronized with external clocks such as the IRIG-B time standard signal clock, RSM (relay setting and monitoring system) clock, or IEC60870-5-103. To display on the LCD whether these clocks are active or inactive and which clock the relay is synchronized with, do the following:

- Select 2 (= Status) on the top "MENU" screen to display the "Status" screen.
- Select 4 (= Time sync source) to display the status of time synchronization sources.

```
/2 Time synchronization source
*IRIG: Active
RSM: Inactive
IEC: Inactive
```

The asterisk on the far left shows that the internal clock is synchronized with the marked source clock. If the marked source clock is inactive, the internal clock runs locally.

For details of the setting time synchronization, see Section 4.2.6.6.

4.2.4.5 Adjusting the Time

To adjust the clock when the internal clock is running locally, do the following:

- Select 2 (= Status) on the top "MENU" screen to display the "Status" screen.
- Select 5 (= Clock adjustment) to display the setting screen.

/ 2	1.2	Feb/1998 22:56	. 19 [10	c a 1]	1 /	5
Minut		0 - 59)	41	cai,	1 /	J
Hour	(0-23):	2 2			
Dау	(1 - 31):	1 2			
Month	ı (1 - 12):	2			
Year	(1990- 2089):	1998			

Line 1 shows the current date, time and time synchronization source with which the internal clock is synchronized. The time can be adjusted only when [Local] is indicated on the top line, showing that the clock is running locally. When [IRIG] or [RSM] or [IEC] is indicated, the following adjustment is invalid.

- Enter a numerical value within the specified range for each item and press the (ENTER) key.
- Press the END key to adjust the internal clock to the set hours without fractions and return to the previous screen.

If a date which does not exist in the calendar is set and (END) is pressed, "Error: Incorrect date" is displayed on the top line and the adjustment is discarded. Adjust again.

4.2.5 Viewing the Settings

The sub-menu "Setting (view)" is used to view the settings made using the sub-menu "Setting (change)" except for the relay version.

The following items are displayed:

Relay version

Description

Communication (Relay address and baud rate in the RSM or IEC60870-5-103)

Recording setting

Status setting

Protection setting

Binary input setting

Binary output setting

LED setting

Enter a number on the LCD to display each item as described in the previous sections.

4.2.5.1 Relay Version

To view the relay version, do the following.

• Press 3 (= Setting (view)) on the main "MENU" screen to display the "Setting (view)" screen.

• Press 1 (= Version) on the "Setting (view)" screen and the "Relay version" screen appears.

```
/2 Relay version

Relay type:
Serial No.:
Main software:

PLC data:
IEC103 data:
```

4.2.5.2 Settings

The "Description", "Comm.", "Record", "Status", "Protection", "Binary input", "Binary output" and "LED" screens display the current settings input using the "Setting (change)" sub-menu.

4.2.6 Changing the Settings

The "Setting (change)" sub-menu is used to make or change settings for the following items:

Password

Description

Communication (Relay address and baud rate in the RSM or IEC60870-5-103)

Recording

Status

Protection

Binary input

Binary output

LED

All of the above settings except the password can be seen using the "Setting (view)" sub-menu.

4.2.6.1 Setting Method

There are three setting methods as follows.

- To enter a selective number
- To enter numerical values
- To enter a text string

To enter a selected number

If a screen as shown below is displayed, perform setting as follows.

The number to the left of the cursor shows the current setting or default setting set at shipment. The cursor can be moved to upper or lower lines within the screen by pressing the \triangle and ∇ keys. If setting (change) is not required, skip the line with the \triangle and ∇ keys.

/6 Scher	ne swite	e h	1 / * * *
DIFTPMD	1 = 3 P O R	2 = 2 P A N D	1 _
1REF	1 = 1 I 0	2 = 2 I 0 3 = 3 I 0	1
2R E F	1 = 1 I 0	2 = 2 I 0	1
3R E F	1 = 1 I 0	2 = 2 1 0 3 = 3 1 0	1
M1 OCI	1 = L o n g	2 = S t d $3 = V e r y$ $4 = E x$	t 1
M2 O C I	1 = L o n g	2 = S t d $3 = V e r y$ $4 = E x$	t 1
M3 O C I	1 = L o n g	2 = S t d $3 = V e r y$ $4 = E x$	t 1
M1 E F I	$1 = L \circ n g$	2 = S t d $3 = V e r y$ $4 = E x$	t 1
M2 E F I	$1 = L \circ n g$	2 = S t d $3 = V e r y$ $4 = E x$	t 1
M3 E F I ♠	1 = L o n g	2 = S t d $3 = V e r y$ $4 = E x$	t 1
L/ 0	0 = 0 f f	1 = 0 n	1
2F - L 0 C K	0 = 0 f f	1 = 0 n	1
5F - L O C K	0 = 0 f f	1 = 0 n	1
DIF1	0 = 0 f f	1 = 0 n	1
DIF2	0 = 0 f f	1 = 0 n	1
D1 F 3	0 = 0 f f	1 = 0 n	1
DIF4	0 = 0 f f	1 = 0 n	1
D1 F 5	0 = 0 f f	1 = 0 n	1
1R E F 1	0 = 0 f f	1 = 0 n	1
1R E F 2	0 = 0 f f	1 = 0 n	1
1R E F 3	0 = 0 f f	1 = 0 n	1
1R E F 4	0 = 0 f f	1 = 0 n	1
1R E F 5	0 = 0 f f	1 = 0 n	1
:		:	:

- Move the cursor to a setting line.
- Enter the selected number. (Numbers other than those displayed cannot be entered.)

• Press the ENTER key to confirm the entry and the cursor will move to the next line below (On the lowest line, the entered number blinks.)

• After completing the setting on the screen, press the (END) key to return to the upper menu

To correct the entered number, do the following.

- If it is before pressing the ENTER key, press the CANCEL key and enter the new number.
- If it is after pressing the ENTER key, move the cursor to the correct line by pressing the ▲ and ▼ keys and enter the new number.

Note: If the CANCEL key is pressed after any entry is confirmed by pressing the ENTER key, all the entries performed so far on the screen concerned are canceled and screen returns to the upper one.

When the screen shown below is displayed, perform setting as follows

The number to the right of "Current No. = " shows the current setting.

```
      /3 Change active group (Active group = *)

      1 = Group 1
      2 = Group 2
      3 = Group 3
      4 = Group 4

      5 = Group 5
      6 = Group 6
      7 = Group 7
      8 = Group 8

      Current No. = *
      Select No. = _
```

- Enter a number to the right of "Select No. = ". (Numbers other than those displayed cannot be entered.)
- Press the ENTER key to confirm the entry and the entered number blinks.
- After completing the setting on the screen, press the END key to return to the upper screen.

To correct the entered number, do the following.

- If it is before pressing the ENTER key, press the CANCEL key and enter the new number.
- If it is after pressing the ENTER key, enter the new number.

To enter numerical values

When the screen shown below is displayed, perform setting as follows:

The number to the left of the cursor shows the current setting or default setting set at shipment. The cursor can be moved to upper or lower lines within the screen by pressing the \triangle and ∇ keys. If setting (change) is not required, skip the line with the \triangle and ∇ keys.

76 V T	& C T	rat	io		1 /7
1 C T	(1 -	20000):	2000 _	
2 C T	(1 -	20000):	1 0 0 0	
3 C T	(1 -	20000):	400	
1 n C T	(1 -	20000):	100	
2 n C T	(1 -	20000):	100	
3 n C T	(1 -	20000):	100	
VT	(1 -	20000):	400	

- Move the cursor to a setting line.
- Enter the numerical value.

• Press the (ENTER) key to confirm the entry and the cursor will move to the next line below. (If a numerical value outside the displayed range is entered, "Error: Out of range" appears on the top line and the cursor remains on the line. Press the (CANCEL) key to clear the entry.)

• After completing the setting on the screen, press the END key to return to the upper screen.

To correct the entered numerical value, do the following.

- If it is before pressing the ENTER key, press the CANCEL key and enter the new numerical value.
- If it is after pressing the ENTER key, move the cursor to the correct line by pressing the ▲ and ▼ keys and enter the new numerical value.

Note: If the CANCEL key is pressed after any entry is confirmed by pressing the ENTER key, all the entries made so far on the screen concerned are canceled and the screen returns to the upper one.

To enter a text string

Text strings are entered in the bracket under the "Plant name" or "Description" screen.

To select a character, use keys 2, 4, 6 and 8 to move the blinking cursor down, left, right and up. "→" and "←" on each of lines 2 to 4 indicate a space and backspace, respectively. A maximum of 22 characters can be entered within the brackets.

- Set the cursor position in the bracket by selecting " \rightarrow " or " \leftarrow " and pressing the (ENTER) key.
- Move the blinking cursor to select a character.
- Press the (ENTER) to enter the blinking character at the cursor position in the brackets.
- Press the END key to confirm the entry and return to the upper screen.

To correct the entered character, do either of the following.

- Discard the character by selecting "←" and pressing the (ENTER) key and enter the new character.
- Discard the whole entry by pressing the CANCEL key and restart the entry from the first.

To complete the setting

Enter after making entries on each setting screen by pressing the (ENTER) key, the new settings are not yet used for operation, though stored in the memory. To validate the new settings, take the following steps.

• Press the END key to the upper screen. Repeat this until the confirmation screen shown below is displayed. The confirmation screen is displayed just before returning to the "Setting (change)" sub-menu.

```
/2 *************
Change settings?
ENTER=Yes CANCEL=No
```

• When the screen is displayed, press the ENTER key to start operation using the new settings, or press the CANCEL key to correct or cancel entries. In the latter case, the screen turns back to the setting screen to enable re-entries. Press the CANCEL key to cancel entries made so far and to turn to the "Setting (change)" sub-menu.

4.2.6.2 Password

For the sake of security of changing the settings, password protection can be set as follows;

• Press 4 (= Setting (change)) on the main "MENU" screen to display the "Setting (change)" screen.

```
/1 Setting (change)
1 = Password 2 = Description 3 = RSM comm
4 = Record 5 = Status 6 = Protection
7 = Binary input 8 = Binary output 9 = LED
```

• Press 1 (= Password) to display the "Password" screen.

```
/2 Password
Input new password [_ ]
Retype new password [ ]
```

- Enter a 4-digit number within the brackets after "Input new password" and press the ENTER key.
- For confirmation, enter the same 4-digit number in the brackets after "Retype new password" and press the ENTER key.
- Press the END key to display the confirmation screen. If the retyped number is different from that first entered, the following message is displayed on the bottom of the "Password" screen before returning to the upper screen.

"Mismatch-password unchanged."

Re-entry is then requested.

Password trap

After the password has been set, the password must be entered in order to enter the setting change screens.

If Φ (= Setting (change)) is entered on the top "MENU" screen, the password trap screen "Password" is displayed. If the password is not entered correctly, it is not possible to move to the "Setting (change)" sub-menu screens.

```
Password [_ ]
```

Canceling or changing the password

To cancel the password protection, enter "0000" in the two brackets on the "Password" screen. The "Setting (change)" screen is then displayed without having to enter a password.

The password can be changed by entering a new 4-digit number on the "Password" screen in the same way as the first password setting.

If you forget the password

Press CANCEL and RESET together for one second on the top "MENU" screen. The screen disappears, and the password protection of the GRT100 is canceled. Set the password again.

4.2.6.3 Description

To enter the plant name and other data, do the following. These data are attached to records.

- Press 4 (= Setting (change)) on the main "MENU" screen to display the "Setting (change)" screen.
- Press 2 (= Description) to display the "Description" screen.

```
/2 Description
1=Plant name 2=Description
```

• To enter the plant name, select 1 (= Plant name) on the "Description" screen.

To enter special items, select 2 (= Description) on the "Description" screen.

```
/3 Description [ _ ]
ABCDEFGHIJKLMNOPQRSTUVWXYZ () [ ] @ \longleftrightarrow
abcdefghijklmnopqrstuvwxvz { } * / + - < = > \longleftrightarrow
0123456789 !"#$%&'::..^
```

• Enter the text string.

4.2.6.4 Communication

If the relay is linked with RSM (relay setting and monitoring system) or IEC60870-5-103, the relay address must be set. Do this as follows:

- Press 4 (= Setting (change)) on the main "MENU" screen to display the "Setting (change)" screen.
- Press 3 (= Comm.) to display the "Communication" screen.

```
/2 Communication
1 = Address
2 = Switch
```

• Press 1 (= Address) to enter the relay address number.

```
/3 Address 1/2
HDLC ( 1- 32): 1_
IEC ( 0- 254): 2
```

• Enter the address number on "HDLC" column for RSM and "IEC" column for IEC60870-5-103 and press the ENTER key.

CAUTION: Do not overlap the relay address number.

• Press 2 (= Switch) on the "Communication" screen to select the protocol and transmission speed (baud rate), etc., of the RSM or IEC60870-5-103.

```
/ 3 Switch 1/3
2 3 2 C 1 = 9 . 6 2 = 19 . 2 3 = 38 . 4 4 = 57 . 6 1 _ _ I E C B R 1 = 9 . 6 2 = 19 . 2 2
I E C B L K 1 = Normal 2 = Blocked 1
```

• Select the number corresponding to the system and press the ENTER key.

<232C>

This line is to select the RS-232C band rate when the RSM system applied.

Note: The default setting of the 232C is 9.6kbps. The 57.6kbps setting, if possible, is recommended to serve user for comfortable operation. The setting of RSM100 is also set to the same baud rate.

<IECBR>

This line is to select the baud rate when the IEC60870-5-103 system applied.

<IECBLK>

Select 2 (=Blocked) to block the monitor direction in the IEC60870-5-103 communication.

4.2.6.5 Setting the Recording

To set the recording function as described in Section 4.2.3, do the following:

- Press 4 (= Setting (change)) on the main "MENU" screen to display the "Setting (change)" screen.
- Press 4 (= Record) to display the "Record" screen.

```
/ 2 Record
1 = Fault record 2 = Event record
3 = Disturbance record
```

Setting the fault recording

• Press 1 (= Fault record) to display the "Fault record" screen.

```
/3 Fault record 1/1 Phase mode 1=0 perating 2=F ault 1
```

• Enter 1 or 2 and press the ENTER key.

Enter 1 (= Operating) to display the operating phase.

Enter 2 (= Fault) to display the fault phase.

Setting the event recording

• Press 2 (= Event record) to display the "Event record" screen.

```
      /3 Event record
      0 = None
      3 = Both 1/16

      Mech. Trip1
      1 = 0 perate
      2 = Reset 3 _

      Mech. Trip2
      1 = 0 perate
      2 = Reset 3

      Mech. Trip3
      1 = 0 perate
      2 = Reset 3
```

• Enter 0 or 1 or 2 or 3 and press the ENTER key. Repeat this for all events.

Enter 0 (= None) not to record the event.

Enter 1 (= Operate) to record the event when the status changes to "operate".

Enter 2 (= Reset) to record the event when the status changes to "reset".

Enter 3 (= Both) to record the event when the status changes both to "operate" and "reset".

Setting the disturbance recording

• Press 3 (= Disturbance record) to display the "Disturbance record" screen.

```
/3 Disturbance record
1=Record time & starter
2=Scheme switch
```

• Press 1 = Record time & starter) to display the "Record time & starter" screen.

```
/4 Record time & starter
                                          1 / 5
                  3.0):
                            1.0
10CPS ( 0.10-
                20.00):
                          1.00
                                         рu
20CPS ( 0.10-
                20.00):
                           1.00
                                         рu
10CPG(0.05-
                20.00):
                          1.00
                                        рu
20CPG(0.10-
                20.00):
                          1.00
                                        рu
```

• Enter the recording time and starter element settings.

To set starters, do the following:

• Press 2 (= Scheme switch) on the "Disturbance record" screen to display the "Scheme switch" screen.

/ 4	Schem	ne swite	c h	1 / 16
TRI	P 1	0 = 0 ff	1 = 0 n	1 _
TRI	P 2	0 = 0 f f	1 = 0 n	1
TRI	P 3	0 = 0 f f	1 = 0 n	1
TRI	P 4	0 = 0 f f	1 = 0 n	1
TRI	P 5	0 = 0 f f	1 = 0 n	1

- Enter 1 to use as a starter or enter 0 if not to use. Repeat this for all items.
- Enter the signal number to record binary signals in Appendix B.

4.2.6.6 Status

To set the status display described in Section 4.2.4, do the following.

Press 5 (= Status) on the "Setting (change)" sub-menu to display the "Status" screen.

```
/2 Status
1 = Metering
2 = Time synchronization
3 = Time zone
```

Setting the metering

Press 1 (= Metering) to display the "Metering" screen.

```
/3 Metering 1/1 Display value 1=Primary 2=Secondary 1 _
```

• Enter the selected number and press the ENTER key. Repeat this for all items.

Setting the time synchronization

The calendar clock can run locally or be synchronized with the external IRIG-B time standard signal, RSM or IEC clock. This is selected by setting as follows.

• Press 2 (= Time synchronization) to display the "Time synchronization" screen.

```
/3 Time synchronization 1/1
Sync 0=0ff 1=IRIG 2=RSM 3=IEC 1 _
```

• Enter the selected number and press the ENTER key.

Note: When to select IRIG-B, RSM or IEC, check that they are active on the "Time synchronization source" screen in "Status" sub-menu. If it is set to an inactive IRIG-B, RSM or IEC, the calendar clock runs locally.

Setting the time zone

When the calendar clock is synchronized with the IRIG-B time standard signal, it is possible to transfer GMT to the local time.

• Press 3 (= Time zone) to display the "Time zone" screen.

```
/3 Time zone 1/1
GMT ( -12- +12): +9 _ hrs
```

• Enter the difference between GMT and local time and press the (ENTER) key.

4.2.6.7 Protection

The GRT100 can have 8 setting groups for protection according to the change of power system operation, one of which is assigned to be active. To set protection, do the following:

• Press 6 (= Protection) on the "Setting (change)" screen to display the "Protection" screen.

```
/2 Protection
1 = Change active group
2 = Change setting
3 = Copy group
```

Changing the active group

• Press 1 (= Change active group) to display the "Change active group" screen.

• Enter the selected number and press the ENTER key.

Changing the settings

Almost all the setting items have default values that are set when the product GRT100 was shipped. For the default values, see Appendix D and H. To change the settings, do the following:

• Press 2 (= Change setting) to display the "Change setting" screen.

```
      /3 Change setting
      (Active group= *)

      1 = Group1
      2 = Group2
      3 = Group3
      4 = Group4

      5 = Group5
      6 = Group6
      7 = Group7
      8 = Group8
```

• Press the group number to change the settings and display the "Protection" screen.

```
/4 Protection
1 = Transformer parameter
2 = Trip
(Group *)
```

Settings are required for transformer parameter and protection functions.

Setting the transformer parameters

Enter the VT&CT ratio as follows:

• Press 1 (= Transformer parameter) on the "Protection" screen to display the "Transformer parameter" screen.

```
/5 Transformer parameter (Group *)
1=VT & CT ratio
```

• Press 1 (VT&CT ratio) to display the "VT&CT ratio" screen.

/6 V T	& C T	rat	iо			1/7
1 C T	(1 -	20000)	:	2000	-
2 C T	(1 -	20000)	:	1 0 0 0	
3 C T	(1 -	20000)	:	400	. 0
1 n C T	(1 -	20000)	:	100	
2 n C T	(1 -	20000)	:	100	
3 n C T	(1 -	20000)	:	100	
V T	(1 -	20000)	:	400	

- Enter the VT ratio and press the ENTER key.
- Enter the CT ratio and press the (ENTER) key

CAUTION

Do not set the CT primary rated current. Set the CT ratio.

(CT ratio) = (CT primary rated current [A]) / (Relay rated current [A])

• Press the END key to return the display to the "Transformer parameter" screen.

Setting the protection function

To set the protection schemes, scheme switches and protection elements, do the following. Protection elements are measuring elements and timers.

Note: Depending on the selected protection scheme and scheme switch setting, some of the scheme switches and protection elements are not used and so need not be set. The protection function setting menu of the GRT100 does not display unnecessary setting items. Therefore, start by setting the protection scheme, then set the scheme switch, then the protection elements.

As a result of the above, note that some of the setting items described below may not appear in the actual setting.

• Press 2 (= Trip) on the "Protection" screen to display the "Trip" screen.

```
5 Trip
1=Scheme switch
2=Protection element
```

Setting the scheme switch

• Press 1 (= Scheme switch) to display the "Scheme switch" screen.

/6 Schem	ne swite	: h			1 / * * *
DIFTPMD	1 = 3 P O R	2 = 2 P A N D			1 _
1R E F	1 = 1 I O	2 = 2 I 0 3 =	3 I 0		1
2R E F	1 = 1 I O	2 = 2 I 0 3 =	3 I 0		1
3R E F	1 = 1 I 0	2 = 2 I 0 3 =	3 I 0		1
M1 O C I	1 = L o n g	2 = S t d 3 = V	ery 4	$= E \times t$	1
M2 O C I	1 = L o n g	2 = S t d 3 = V	ery 4	$= E \times t$	1
M3 O C I	1 = L o n g	2 = S t d 3 = V	ery 4	$= E \times t$	1
M1 E F I	1 = L o n g	2 = S t d 3 = V	ery 4	= E x t	1
M2 E F I	1 = L o n g	2 = S t d 3 = V	ery 4	= E x t	
M3 E F I	1 = L o n g	2 = S t d 3 = V	ery 4	= E x t	1
L/ 0	0 = 0 f f	1 = 0 n			1
2F - L O C K	0 = 0 f f	1 = 0 n			1
5F - L O C K	0 = 0 f f	1 = 0 n			1
DIF1	0 = 0 f f	1 = 0 n			1
DIF2	0 = 0 f f	1 = 0 n			1
DIF3	0 = 0 f f	1 = 0 n			1
DIF4	0 = 0 f f	1 = 0 n			1
DIF5	0 = 0 f f	1 = 0 n			1
1R E F 1	0 = 0 f f	1 = 0 n			1
1R E F 2	0 = 0 f f	1 = 0 n			1
1R E F 3	0 = 0 f f	1 = 0 n			1
1R E F 4	0 = 0 f f	1 = 0 n			1
1R E F 5	0 = 0 f f	1 = 0 n			1
:		/ :			:

• Enter the number corresponding to the switch status to be set and press the (ENTER) key for each switch.

The setting of REF depends on the type of the transformer. The setting method is shown in Appendix L.

• After setting all switches, press the END key to return to the "Trip" screen.

Setting the protection elements

• Press 2 (= Protection element) on the "Trip" screen to display the "Protection element" screen.

```
6 Protection element (Group = *)
1 = DIFT 2 = REF 3 = 0 C
4 = THR 5 = V/F 6 = FRQ
```

<DIFT>

- Press 1 (= DIFT) to display the "DIFT" screen. The measuring elements used in the current differential protection are set using this screen.
- Enter the numerical value and press the (ENTER) key for each element.
- After setting all elements, press the END key to return to the "Protection element" menu.

/7 DIFT				1 / 1 3
i k (0.10-	1.00):	0.10	_ p u
p 1 (10-	100):	1 0	%
p 2 (10-	200):	1 0 0	%
k p (1.00-	20.00):	1.00	рu
kct1 (0.05-	50.00):	1.00	
kct2 (0.05-	50.00):	1.50	
kct3 (0.05-	50.00):	2.00	
d 1 (0 -	11):	1 0	\ (\sigma)
d 2 (0 -	11):	1	
d 3 (0 -	11):	3	
k 2 f (10-	50):	1 0	%
k5f (10-	100):	5 0	%
kh (2.00-	20.00):	2.00	рu

<REF>

- Press 2 (= REF) to display the "REF" screen. The measuring elements and timers used in the restricted earth fault protection are set using this screen.
- Enter the numerical value and press the ENTER key for each element.
- After setting all elements, press the END key to return to the "Protection element" menu.

		4		
/7 REF				1 / 2 1
1 i k (0.05-	0 (50):	0.05 _	рu
1 k c t 1 (1.00-	50.00):	1.00	
1 k c t 2 (1.00-	50.00):	1.00	
1 k c t 3 (1.00-	50.00):	1.00	
1 p 2 (50-	100):	5 0	%
1 k p (0.50-	2.00):	1.00	рu
2 i k (0.05-	0.50):	0.50	рu
2 k c t 1 (1.00-	50.00):	1.00	
2 k c t 2 (1.00-	50.00):	1.00	
2 k c t 3 (1.00-	50.00):	1.00	
2 p 2	50-	100):	5 0	%
2 k p (2.00):	1.00	рu
3 i k		0.50):	0.50	рu
3 k c t 1 (1.00-	50.00):	1.00	
3 k c t 2 (1.00-	50.00):	1.00	
3 k c t 3 (1.00-	50.00):	1.00	
3 p 2 (50-	100):	5 0	%
3 k p (0.50-	2.00):	1.00	рu
T1REF(· · ·	10.00):	0.01	S
T 2 R E F (0.00-	10.00):	0.01	S
T3REF(0.00-	10.00):	0.01	S

<0C>

• Press 3 (OC) to display the "OC" screen. The overcurrent elements and timers are set using this screen.

• Enter the numerical value and press the (ENTER) key for each element.

• After setting all elements, press the (END) key to return to the "Protection element" menu

/7 OC					1 / 2 4
1 0 C	(0.10-	20.00):	0.10_	рu
2 0 C	(0.10-	20.00):	0.10	рu
3 O C	(0.10-	20.00):	0.10	рu
T 1 0 C	(0.00-	10.00):	0.00	S
T 2 0 C	(0.00-	10.00):	0.00	s
T 3 0 C	(0.00-	10.00):	0.00	S
1 0 C I	(0.10-	5.00):	0.10	p u
2 0 C I	(0.10-	5.00):	0.10	p u
3 O C I	(0.10-	5.00):	0.10	p u
T 1 0 C I	(0.05-	1.00):	0.50	
T 2 0 C I	(0.05-	1.00):	0.50	
T 3 0 C I	(0.05-	1.00):	0.50	
1 E F	(0.10-	20.00):	0.10	рu
2 E F	(0.10-	20.00);	0.10	рu
3 E F	(0.10-	20.00):	0.10	рu
T 1 E F	(0.00-	10.00):	0.00	s
T 2 E F	(0.00-	10.00):	0.00	S
T 3 E F	(0.00-	10.00):	0.00	S
1 E F I	(0.10-	5.00):	0.10	рu
2 E F I	(0.10-	5.00):	0.10	рu
3 E F I	(0.10-	5.00):	0.10	рu
T1EFI	(0.05-	1.00):	0.50	
T 2 E F I	(0.05-	1.00):	0.50	
T 3 E F I	(0.05-	1.00):	0.50	

<THR>

- Press 4 (= THR) to display the "THR" screen. The measuring elements and the timer used in the thermal overload protection are set using this screen.
- Enter the numerical value and press the ENTER key for each element.
- After setting all elements, press the (END) key to return to the "Protection element" menu.

/7	THR				1 / 5
τ	(0.5-	500.0):	0.5_	min
k	(0.10-	4.00):	0.10	
ΙB	(0.50-	2.50):	0.50	рu
Ιp	(0.00-	1.00):	0.50	рu
ΤA	(0 -	10):	0	min

<V/F>

- Press 5 (= V/F) to display the "V/F" screen. The measuring elements and timers used in the overexcitation protection are set using this screen.
- Enter the numerical value and press the ENTER key for each element.

• After setting all elements, press the (END) key to return to the "Protection element" menu.

/ 7	V / F				1 / 9
V	(100.0-	120.0):	100.0	V
A	(1.03-	1.30):	1.10	рu
L	(1.05-	1.30):	1.20	рu
Н	(1.10-	1.40):	1.30	рu
LT	(1 -	600):	1	S
НТ	(1 -	600):	1	8
RT	(60-	3600):	6 0	S
TVF	H (1 -	600):	1	S
TVF	A (1 -	600):	1	S

<FRQ>

- Press 6 (= FRQ) to display the "FRQ" screen. The measuring elements and timers used in the frequency protection are set using this screen.
- Enter the numerical value and press the ENTER key for each element.
- After setting all elements, press the END key to return to the "Protection element" menu.

/7 FRQ		1 /	6
81-1 (45.00-55.00) 45.00	Нz	
	45.00-55.00): 45.00	Нz	
UV (40-100) 40	V	
TEPOI (0.00-60:00): 0.00	S	
	0.00 - 60.00): 0.00	S	
TFRQA (0.00-60.00): 0.00	s	

Setting group copy

To copy the settings of one group and overwrite them to another group, do the following:

• Press 3 (= Copy group) on the "Protection" screen to display the "Copy group A to B" screen.

```
/3 Copy group A to B (Active group = *)
A ( 1- 8):
B ( 1- 8):
```

- Enter the group number to be copied in line A and press the ENTER key.
- Enter the group number to be overwritten by the copy in line B and press the ENTER key.

4.2.6.8 Binary Input

The logic level of binary input signals can be inverted by setting before entering the scheme logic. Inversion is used when the input contact cannot meet the conditions described in Table 3.2.2.

• Press 7 (= Binary input) on the "Setting (change)" sub-menu to display the "Binary input" screen.

/2 Bi	nar	y input	$1 = N \circ r m$	2 = I n v	1 / 8
BISW	1	Mechanica1	trip1		1 _
BISW	2	Mechanical	trip2		1
BISW	3	Mechanical	trip3		1
BISW	4	Mechanical	trip4		1
BISW	5	Indication	reset		1
BISW1	. 4	Event 1			1
BISW1	. 5	Event 2			F
BISW1	. 6	Event 3			Y

• Enter 1 (= Normal) or 2 (= Inverted) and press the ENTER key for each binary input.

4.2.6.9 Binary Output

All the binary outputs of the GRT100 except the tripping command, and the relay failure signal are user-configurable. It is possible to assign one signal or up to six ANDing or ORing signals to one output relay. Available signals are listed in Appendix B.

It is also possible to attach a drop-off delay time of 0.2 seconds to these signals. The drop-off delay time is disabled by the scheme switch [BOTD].

Appendix D shows the factory default settings,

To configure the binary output signals, do the following:

Selection of output module

• Press 8 (= Binary output) on the "Setting (change)" screen to display the "Binary output" screen. The available output module(s) will be shown. (This differs depending on the relay model; the following is for Models 102 and 202.)

• Press the number corresponding to the selected output module to display the "Binary output" screen.

```
/3 Binary output (IO2)
Select BO (1-13)

Select No. = _
```

Note: The setting is required for all the binary outputs. If any of the binary outputs are not to be used, enter 0 for the logic gates #1 to #6 when assign signals.

Selecting the output relay

• Enter the output relay number and press the (ENTER) key to display the "Setting" screen.

```
/4 Setting (B01 of I02)
1=Logic gate type & delay timer
2=Input to logic gate
```

TOSHIBA

Setting the logic gate type and timer

Press 1 to display the "Logic gate type and delay timer" screen.

/5 Logi	c gate	type &	delay	timer	1 / 2
Logic	1 = 0 R	2 = A N D			1 / 2 1 _
ВОТО	0 = 0 f f	1 = 0 n			1

- Enter 1 or 2 to use an OR gate or AND gate and press the ENTER key.
- Enter 0 or 1 to add 0.2s drop-off delay time to the output relay or not and press the ENTER key.
- Press the END key to return to the "Setting" screen.

Assigning signals

• Press 2 on the "Setting" screen to display the "Input to logic gate" screen.

/ 5	Input	to lo	gic gate	70	1 / 6
Ιn	#1 (0 -	3071):	21 _	
Ιn	#2 (0 -	3071):	4	
Ιn	#3 (0 -	3071):	6 7	
Ιn	#4 (0 -	3071):	0	
Ιn	#5 (0 -	3071):	0	
Ιn	#6 (0 -	3071):	0	

• Assign signals to gates (In #1 to #6) by entering the number corresponding to each signal referring to Appendix B.

Note: If signals are not assigned to all the gates #1 to #6, enter 0 for the unassigned gate(s).

Repeat this process for the outputs to be configured.

4.2.6.10 LEDs

Four LEDs from bottom of the front panel are user-configurable. One of the signals listed in Appendix B can be assigned to each LED as follows:

• Press 9 (= LED) on the "Setting (change)" screen to display the "LED" screen.

/ 2 LED LED1 (LED2 (LED3 (1 / 4
LED1 (0 -	3071):	21 _	
LED2 (0 -	3071):	4	
LED3 (0 -	3071):	6 7	
LED4 (0 -	3071):	0	

• Enter the number corresponding to a signal to assign signals to each LED.

If an LED is not used, enter "0" or the default value will be assigned.

4.2.7 Testing

The sub-menu "Test" provides such functions as setting of testing switches, forced operation of binary outputs, time measurement of the variable setting timer and logic signal observation.

4.2.7.1 Setting the switches

The automatic monitor function (A.M.F.) can be disabled by setting the switch [A.M.F] to "OFF"

Disabling the A.M.F. prevents tripping from being blocked even in the event of a failure in the items being monitored by this function. It also prevents failures from being displayed on the "ALARM" LED and LCD described in Section 4.2.1. No events related to A.M.F. are recorded, either.

Disabling A.M.F. is useful for blocking the output of unnecessary alarms during testing.

Note: Set the switch [A.M.F] to "Off" before applying the test inputs, when the A.M.F is disabled.

The switch [Reset] is used to test the THR and V/F elements. When the switch [Reset] is set to "1", the time counting of inverse time characteristic can be forcibly reset.

While the switch [A.M.F] is set to "0" or [Reset] is set to "1", the red "TESTING" LED is lit for alarm purposes.

Caution: Be sure to restore these switches after the tests are completed.

Disabling automatic monitoring

• Press 5 (= Test) on the top "MENU" screen to display the "Test" screen.

```
/1 Test
1 = Switch
3 = Timer

2 = Binary output
4 = Logic circuit
```

• Press 1 (= Switch) to display the "Switch" screen.

/2 Swit	c h		1 / 3
A. M. F.	0 = 0 f f	1 = 0 n	1 –
Reset	0 = 0 f f	1 = 0 n	0
IECTST	0 = 0 f f	1 = 0 n	1

- Enter 0 for A.M.F to disable the A.M.F. and press the ENTER key.
- Enter 1(=On) for IECTST to transmit 'test mode' to the control system by IEC60870-5-103 communication when testing the local relay, and press the ENTER key.
- Press the (END) key to return to the "Test" screen.

Resetting the time counting of THR and V/F elements

- Enter 1 for Reset to reset the time counting forcibly and press the ENTER key.
- Press the END key to return to the "Test" screen.

4.2.7.2 Binary Output Relay

It is possible to forcibly operate all binary output relays for checking connections with the external devices. Forced operation can be performed on one or more binary outputs at a time for each module.

• Press 2 (= Binary output) on the "Test" screen to display the "Binary output" screen.

The LCD displays the output modules mounted depending on the model.

• Enter the selected number corresponding to each module to be operated. Then the LCD displays the name of the module, the name of the output relay, the name of the terminal block and the terminal number to which the relay contact is connected.

/ 3 B O		(0 = D i s a b l e 1 = E n a b l e)	1/14
I 0 2	B 0 1	: TB3 - A1. A2	1 _
I 0 2	B 0 2	: TB3 - B1. A2	1
I 0 2	B 0 3	: T B 3 - B 2 . A 2	1
I 0 2	B 0 4	: T B 3 - A 3 . B 3	0
I 0 2	B 0 5	: T B 3 - A 4 . B 4	0
I 0 2	B 0 6	: T B 3 - A 5 . B 5	0
I 0 2	B 0 7	: T B 3 - A 6 . B 6	0
I 0 2	B 0 8	: T B 3 - A 7 . B 7	0
I 0 2	B 0 9	: T B 3 - A 8 . B 8	0
I 0 2	B 0 1 0	: T B 3 - A 9 - B 9	0
I 0 2	B 0 1 1	: T B 3 - A 1 0 . B 1 0	0
I 0 2	B 0 1 2	: T B 3 - A 1 1 . B 1 1	0
I 0 2	FAIL	: T B 3 - A 1 2 . B 1 2	0
I 0 2	B O 1 3	: T B 3 - A 1 3 , B 1 3	0

- Enter 1 and press the ENTER key.
- After completing the entries, press the END key. Then the LCD displays the screen shown below.

```
/3 BO
Keep pressing 1 to operate.
Press CANCEL to cancel.
```

- Keep pressing 1 key to operate the output relays forcibly.
- Release the press of 1 key to reset the operation.

4,2.7.3 Timer

The pick-up or drop-off delay time of the variable timer used in the scheme logic can be measured with monitoring jacks A and B. Monitoring jacks A and B are used to observe the input signal and output signal to the timer respectively.

• Press 3 (= Timer) on the "Test" screen to display the "Timer" screen.

```
/2 Timer 1/1
Timer ( 1- 15): 1 _
```

• Enter the number corresponding to the timer to be observed and press the ENTER key. The timers and related numbers are listed in Appendix C.

• Press the (END) key to display the following screen.

```
/2 Timer
Press ENTER to operate.
Press CANCEL to cancel.
```

• Press the (ENTER) key to operate the timer. The "TESTING" LED turns on, and timer is initiated and the following display appears. The input and output signals of the timer can be observed at monitoring jacks A and B respectively. The LEDs above monitoring jacks A or B are also lit if the input or output signal exists.

```
/2 Timer
Operating...
Press END to reset.
Press CANCEL to cancel.
```

- Press the (END) key to reset the input signal to the timer. The "TESTING" LED turns off.
- Press the CANCEL key to test other timers. Repeat the above testing.

4.2.7.4 Logic Circuit

It is possible to observe the binary signal level on the signals listed in Appendix B with monitoring jacks A and B.

• Press 4 (= Logic circuit) on the "Test" screen to display the "Logic circuit" screen.

```
/2 Logic circuit 1/2
Term A ( 0 - 3071): 1 -
Term B ( 0 - 3071): 48
```

- Enter a signal number to be observed at monitoring jack A and press the ENTER key.
- Enter the other signal number to be observed at monitoring jack B and press the ENTER key.

After completing the setting, the signals can be observed by the binary logic level at monitoring jacks A and B or by the LEDs above the jacks.

On screens other than the above screen, observation with the monitoring jacks is disabled.

4.3 Personal Computer Interface

The relay can be operated from a personal computer using an RS-232C port on the front panel. On the personal computer, the following analysis and display of the fault voltage and current are available in addition to the items available on the LCD screen.

• Display of voltage and current waveform: Oscillograph, vector display

• Symmetrical component analysis: On arbitrary time span

• Harmonic analysis: On arbitrary time span

• Frequency analysis: On arbitrary time span

For the details, see the separate instruction manual "PC INTERFACE RSM100".

4.4 Relay Setting and Monitoring System

The Relay Setting and Monitoring (RSM) system is a system that retrieves and analyses the data on power system quantities, fault and event records and views or changes settings in individual relays via a telecommunication network using a remote PC.

For the details, see the separate instruction manual "PC INTERFACE RSM100".

Figure 4.4.1 shows the typical configuration of the RSM system via a protocol converter G1PR2. The relays are connected through twisted pair cables, and the maximum 256 relays can be connected since the G1PR2 can provide up to 8 ports. The total length of twisted pair wires should not exceed 1200 m. Relays are mutually connected using an RS485 port on the relay rear panel and connected to a PC RS232C port via G1PR2. Terminal resistor (150 ohms) is connected the last relay. The transmission rate used is 64 kbits/s.

Figure 4.4.2 shows the configuration of the RSM system with Ethernet LAN (option). The relays are connected to HUB through UTP cable using RJ-45 connector at the rear of the relay. The relay recognizes the transmission speed automatically.

In case of the optional fiber optic interface (option), the relays are connected through graded-index multi-mode $50/125\mu m$ or $62.5/125\mu m$ type optical fiber using ST connector at the rear of the relay.

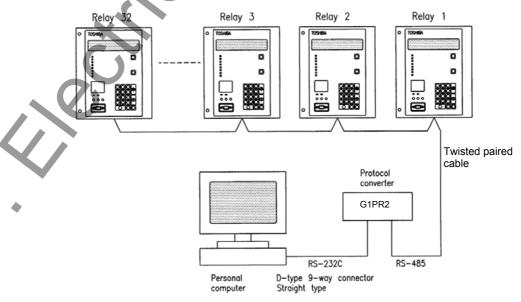


Figure 4.4.1 Relay Setting and Monitoring System (1)

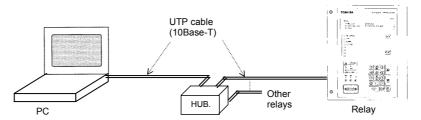


Figure 4.4.2 Relay Setting and Monitoring System (2)

4.5 IEC 60870-5-103 Interface

The GRT100 can support the IEC60870-5-103 communication protocol. This protocol is mainly used when the relay communicates with a control system and is used to transfer the following measurand, status data and general command from the relay to the control system.

- Measurand data: current, voltage, frequency
- Status data: events, fault indications, etc.

The IEC60870-5-103 function in the relay can be customized with the original software "IEC103 configurater". It runs on a personal computer (PC) connected to the relay, and can help setting of Time-tagged messages, General command, Metering, etc. For details of the setting method, refer to "IEC103 configurater" manual. For the default setting of IEC60870-5-103, see Appendix O.

The protocol can be used through the RS485 port on the relay rear panel and can be also used through the optional fibre optical interface. The relay connection is similar to Figure 4.4.1.

The relay supports two baud-rates 9.6kbps and 19.2kbps. The data transfer from the relay can be blocked by the setting. For the settings, see the Section 4.2.6.4.

4.6 Clock Function

The clock function (Calendar clock) is used for time-tagging for the following purposes:

- Event records
- Disturbance records
- Fault records
- Metering
- Automatic supervision
- Display of the system quantities on the digest screen
- Display of the fault records on the digest screen
- Display of the automatic monitoring results on the digest screen

The calendar clock can run locally or be synchronized with the external IRIG-B time standard signal, RSM or IEC clock. This can be selected by setting.

If it is necessary to synchronize with the IRIG-B time standard signal, it is possible to transform GMT to the local time by setting.

When the relays are connected to the RSM system as shown in Figure 4.4.1, the calendar clock of each relay is synchronized with the RSM clock. If the RSM clock is synchronized with the external time standard (GPS clock etc.), then all the relay clocks are synchronized with the external time standard.

5. Installation

5.1 Receipt of Relays

When relays are received, carry out the acceptance inspection immediately. In particular, check for damage during transportation, and if any is found, contact the vendor.

Check that the following accessories are attached.

- 3 pins for the monitoring jack, packed in a plastic bag.
- An optional attachment kit required in rack-mounting. (See Appendix F.)
 - 1 large bracket with 5 round head screws, spring washers and washers $(M4 \times 10)$
 - 1 small bracket with 3 countersunk head screws (M4 \times 6)
 - 2 bars with 4 countersunk head screws (M3 \times 8)

Always store the relays in a clean, dry environment.

5.2 Relay Mounting

Either a rack or flush mounting relay is delivered as designated by the customer. The GRT100 models are housed into type A case. Appendix F shows the case outline.

If the customer requires a rack-mounting relay, support metal fittings necessary to mount it in the 19-inch rack are also supplied with the relay.

When mounting the relay in the rack, detach the original brackets fixed on both sides of the relay and seals on the top and bottom of the relay. Attach the larger bracket and smaller bracket on the left and right side of the relay respectively and the two bars on the top and bottom of the relay.

How to mount the attachment kit, see Appendix F.

Dimension of the attachment kit EP-101 is also shown in Appendix F.

5.3 Electrostatic Discharge

ACAUTION

Do not take out any modules outside the relay case since electronic components on the modules are very sensitive to electrostatic discharge. If it is absolutely essential to take the modules out of the case, do not touch the electronic components and terminals with your bare hands. Additionally, always put the module in a conductive anti-static bag when storing it.

5.4 Handling Precautions

A person's normal movements can easily generate electrostatic potential of several thousand volts. Discharge of these voltages into semiconductor devices when handling electronic circuits can cause serious damage, which often may not be immediately apparent but the reliability of the circuit will have been reduced.

The electronic circuits are completely safe from electrostatic discharge when housed in the case. Do not expose them to risk of damage by withdrawing modules unnecessarily.

Each module incorporates the highest practicable protection for its semiconductor devices.

TOSHIBA

However, if it becomes necessary to withdraw a module, precautions should be taken to preserve the high reliability and long life for which the equipment has been designed and manufactured.

ACAUTION

- Before removing a module, ensure that you are at the same electrostatic potential as the equipment by touching the case.
- Handle the module by its front plate, frame or edges of the printed circuit board. Avoid touching the electronic components, printed circuit board or connectors.
- Do not pass the module to another person without first ensuring you are both at the same electrostatic potential. Shaking hands achieves equipotential.
- Place the module on an anti-static surface, or on a conducting surface which is at the same potential as yourself.
- Do not place modules in polystyrene trays.

It is strongly recommended that detailed investigations on electronic circuitry should be carried out in a Special Handling Area such as described in the IEC 60747.

5.5 External Connections

External connections are shown in Appendix G.



6. Commissioning and Maintenance

6.1 Outline of Commissioning Tests

The GRT100 is fully numerical and the hardware is continuously monitored.

Commissioning tests can be kept to a minimum and need only include hardware tests and conjunctive tests. The function tests are at the user's discretion.

In these tests, user interfaces on the front panel of the relay or local PC can be fully applied.

Test personnel must be familiar with general relay testing practices and safety precautions to avoid personal injuries or equipment damage.

Hardware tests

These tests are performed for the following hardware to ensure that there is no hardware defect. Defects of hardware circuits other than the following can be detected by monitoring which circuits function when the DC power is supplied.

User interfaces
Binary input circuits and output circuits
AC input circuits

Function tests

These tests are performed for the following functions that are fully software-based. Tests of the protection schemes and fault locator require a dynamic test set.

Measuring elements Timers Metering and recording

Conjunctive tests

The tests are performed after the relay is connected with the primary equipment and other external equipment.

The following tests are included in these tests:

On load test: phase sequence check and polarity check Tripping circuit test

6.2 Cautions

6.2.1 Safety Precautions

ACAUTION

• The relay rack is provided with a grounding terminal. Before starting the work, always make sure the relay rack is grounded.

- When connecting the cable to the back of the relay, firmly fix it to the terminal block and attach the cover provided on top of it.
- Before checking the interior of the relay, be sure to turn off the power.

Failure to observe any of the precautions above may cause electric shock or malfunction.

6.2.2 Cautions on Tests

ACAUTION

- While the power is on, do not connect/disconnect the flat cable on the front of the printed circuit board (PCB).
- While the power is on, do not mount/dismount the PCB.
- Before turning on the power, check the following:
 - Make sure the polarity and voltage of the power supply are correct.
 - Make sure the CT circuit is not open.
 - Make sure the VT circuit is not short-circuited.
- Be careful that the transformer module is not damaged due to an overcurrent or overvoltage.
- If settings are changed for testing, remember to reset them to the original settings.

Failure to observe any of the precautions above may cause damage or malfunction of the relay.

Before mounting/dismounting the PCB, take antistatic measures such as wearing an earthed wristband.

6.3 Preparations

Test equipment

The following test equipment is required for the commissioning tests.

- 1 Single-phase voltage source
- 2 Single-phase current sources
- 1 Variable-frequency source
- 1 Combined fundamental and 2nd-harmonic adjustable current supply
- 1 Combined fundamental and 5th-harmonic adjustable current supply
- 1 DC power supply
- 1 DC voltmeter
- 1 AC voltmeter
- 1 Phase angle meter
- 2 AC ammeters
- 1 Frequency meter
- 1 Time counter, precision timer
- 1 PC (not essential)

Relay settings

Before starting the tests, it must be specified whether the tests will use the user's settings or the default settings.

For the default settings, see the following appendixes:

Appendix D Binary Output Default Setting List

Appendix H Relay Setting Sheet

Visual inspection

After unpacking the product, check for any damage to the relay case. If there is any damage, the internal module might also have been affected. Contact the vendor.

Relay ratings

Check that the items described on the nameplate on the front of the relay conform to the user's specification. The items are: relay type and model, AC voltage, current and frequency ratings, and auxiliary DC supply voltage rating.

Local PC

When using a local PC, connect it with the relay via the RS-232C port on the front of the relay. RSM100 software is required to run the PC.

For the details, see the separate instruction manual "PC INTERFACE RSM100".

6.4 Hardware Tests

The tests can be performed without external wiring, but DC power supply and AC voltage and current source are required.

6.4.1 User Interfaces

This test ensures that the LCD, LEDs and keys function correctly.

LCD display

• Apply the rated DC voltage and check that the LCD is off.

Note: If there is a failure, the LCD displays the "Auto-supervision" screen when the DC voltage is applied.

• Press the RESET key for 1 second and check that black dots appear on the whole screen.

LED display

- Apply the rated DC voltage and check that the "IN SERVICE" LED is lit in green.
- Press the RESET key for 1 second and check that seven LEDs under the "IN SERVICE" LED and two LEDs for monitoring jacks A and B are lit in red.

VIEW and RESET keys

- Press the VIEW key when the LCD is off and check that the "Metering" screen is displayed on the LCD.
- Press the RESET key and check that the LCD turns off.

Keypad

- Press any key on the keypad when the LCD is off and check that the LCD displays the "MENU" screen. Press the END key to turn off the LCD.
- Repeat this for all keys.

6.4.2 Binary Input Circuit

The testing circuit is shown in Figure 6.4.1.

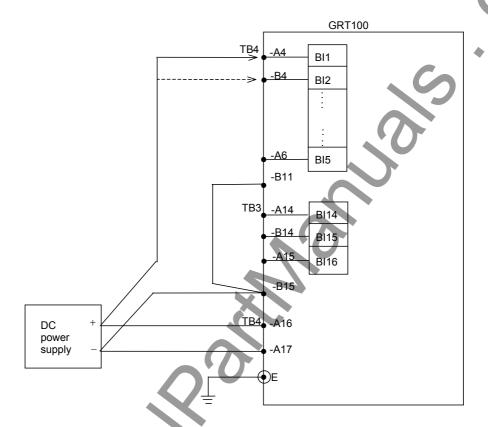


Figure 6.4.1 Testing Binary Input Circuit (Model 100s, 200s)

• Display the "Binary input & output" screen from the "Status" sub-menu.

/2 Binary input &	output				3 /	5
Input (101)	[000]	0 0 0	0 0 0	0 0 0	0]
Input (102)	[000]]
0 u t p u t (I 0 1 - t r i p)	[000]	0 0]
0 u t p u t (I 0 2) 0 u t p u t (I 0 3)	[0 0 0 [0 0 0	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	$\begin{array}{cccccccccccccccccccccccccccccccccccc$	000	0 0]

• Apply the rated DC voltage to terminal A4, B4, ..., A6 of terminal block TB4, and A14, B14 and A15 of terminal block TB3.

Check that the status display corresponding to the input signal changes from 0 to 1. (For details of the binary input status display, see Section 4.2.4.2.)

The user will be able to perform this test for one terminal to another or for all the terminals at once.

6.4.3 Binary Output Circuit

This test can be performed by using the "Test" sub-menu and forcibly operating the relay drivers and output relays. Operation of the output contacts is monitored at the output terminal. The output contact and corresponding terminal number are shown in Appendix G.

• Press 2 (= Binary output) on the "Test" screen to display the "Binary output" screen. The LCD displays the output modules mounted, depending on the model.

• Enter the selected number corresponding to each module to be operated. Then the LCD displays the name of the module, the name of the output relay, the name of the terminal block and the terminal number to which the relay contact is connected.

/ 3 B O	(0 = Disable 1 = Enable)	1 / 1 4
I 0 2	B O 1 : T B 2 - A 1 , A 2	1 _
I 0 2	B O 2 : T B 2 - B 1 , A 2	1
I 0 2	B O 3 : T B 2 - B 2 , A 2	1
I 0 2	B O 4 : T B 2 - A 3 , B 3	0
I 0 2	B O 5 : T B 2 - A 4 , B 4	0
I 0 2	B O 6 : T B 2 - A 5 , B 5	0
I 0 2	B O 7 : T B 2 - (A 6, B 6	0
I 0 2	B 0 8 : T B 2 - A 7 , B 7	0
I 0 2	B09 : TB2 - A8, B8	0
I 0 2	B010 : TB2 - A9, B9	0
I 0 2	B O 1 1 : T B 2 - A 1 O , B 1 O	0
I 0 2	B012 TB2-A11, B11	0
I 0 2	FAIL TB2-A12, B12	0
I 0 2	B 0 1 3 : T B 2 - A 1 3 , B 1 3	0

- Enter 1 and press the ENTER key.
- After completing the entries, press the END key. Then the LCD displays the screen shown below. If 1 is entered for all the output relays, the following forcible operation can be performed collectively.

```
A BO Keep pressing 1 to operate.
Press CANCEL to cancel.
```

- Keep pressing the 1 key to operate the output relays forcibly.
- Check that the output contacts operate at the terminal.
- Release pressing the 1 key to reset the operation.

6.4.4 AC Input Circuits

This test can be performed by applying the checking voltages and currents to the AC input circuits and verifying that the values applied coincide with the values displayed on the LCD screen.

The testing circuit for Model 100 series is shown in Figure 6.4.2. A single-phase voltage source and two single-phase current sources are required. (Test Model 200 series by same testing method of Model 100 series.)

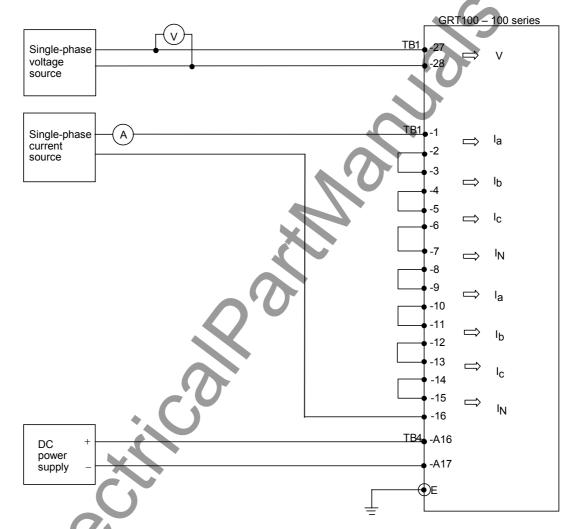


Figure 6.4.2 Testing AC Input Circuit (Model 100s)

• Check that the metering data is set to be expressed as secondary values (Display value = 2) on the "Metering" screen.

"Setting (view)" sub-menu \rightarrow "Status" setting screen \rightarrow "Metering" screen

If the setting is Primary (Display value = 1), change the setting in the "Setting (change)" sub-menu. Remember to reset it to the initial setting after the test is finished.

• Open the "Metering" screen in the "Status" sub-menu.

"Status" sub-menu → "Metering" screen

• Apply the rated AC voltages and currents and check that the displayed values are within \pm 5% of the input values.

6.5 Function Test

6.5.1 Measuring Element

Measuring element characteristics are realized by the software, so it is possible to verify the overall characteristics by checking representative points.

Operation of the element under test is observed by the binary output signal at monitoring jacks A or B or by the LED indications above the jacks. In any case, the signal number corresponding to each element output must be set on the "Logic circuit" screen of the "Test" sub-menu.

```
/2 Logic circuit
Term A ( 0- 333): 1 _
Term B ( 0- 333): 48
```

When a signal number is entered for the TermA line, the signal is observed at monitoring jack A and when entered for the TermB line, observed at monitoring jack B.

Note: The voltage level at the monitoring jacks is $+15V \pm 3V$ for logic level "1" and less than 0.1V for logic level "0".

CAUTION

- Use the testing equipment with more than $1k\Omega$ of internal impedance when observing the output signal at the monitoring jacks.
- Do not apply an external voltage to the monitoring jacks.

In case of a three-phase element, it is enough to test for a representative phase. A-phase element is selected hereafter.

6.5.1.1 Current differential element DIF

The current differential element is checked on the following items

- Operating current value
- Percentage restraining characteristic
- Operating time

Note: Set all the CT ratio matching settings (kct1 to kct3) to "1" and phase angle matching settings (d1 to d3) to "0" in the testing described in 6.5.1.1 to 6.5.1.4, because the operating value depends on the settings.

Operating current value

Minimum operating current value is checked by simulating a one-end infeed. Figure 6.5.1 shows a testing circuit simulating an infeed from a primary winding.

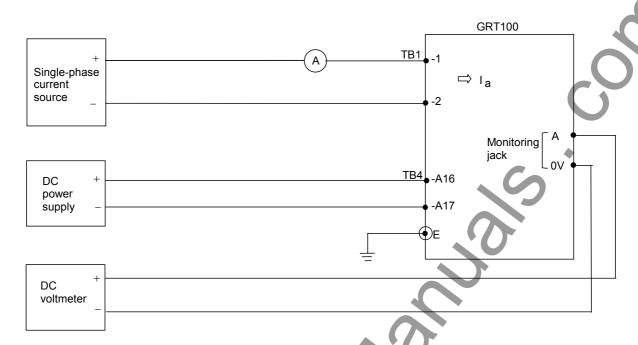


Figure 6.5.1 Operating Current Value Test Circuit (Model 100s, 200s)

The output signal numbers of the DIF elements are as follows:

Element	Signal number
DIF-A	44
DIF-B	45
DIF-C	46

- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number 44 to observe the DIF-A operation at monitoring jack A and press the ENTER key.
- Apply a test current to A-phase current terminals and change the magnitude of the current applied and measure the value at which the element DIF-A operates.
 - Check that the measured value is within 7% of the theoretical operating value.
 - Theoretical operating value = $(CT \text{ secondary rated current}) \times (ik \text{ setting})$

Percentage restraining characteristics

The percentage restraining characteristic is tested on the outflow current (I_{out}) and infeed current (I_{in}) plane as shown in Figure 6.5.2. The characteristic shown in Figure 6.5.2 is equivalent to the one on the differential current (Id) and restraining current (Ir) plane shown in Figure 2.11.1.

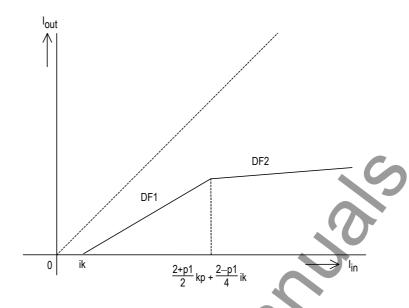


Figure 6.5.2 Current Differential Element (lout - lin Plane)

Figure 6.5.3 shows a testing circuit simulating an infeed from a primary winding and outflow from a secondary winding.

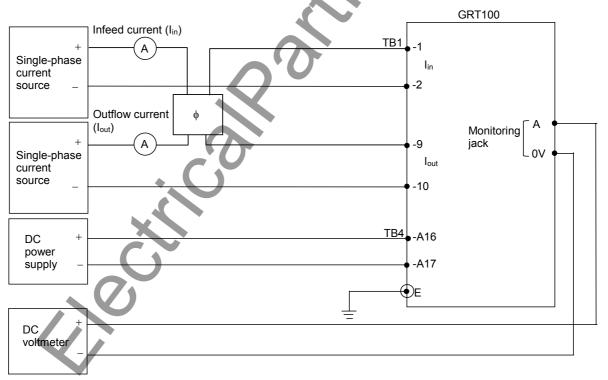


Figure 6.5.3 Percentage Restraining Characteristic Test of DIF (Model 100s, 200s)

• Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.

- Enter a signal number 44 to observe the DIF-A output at monitoring jack A and press the ENTER key.
- Apply an infeed current to terminal TB1-1 and -2.

When the infeed current applied is larger than the setting of ik (pu) and smaller than $kp(2+p_1)/2 + ik(2-p_1)/4$ (pu), characteristic DF1 is checked.

When the infeed current applied is larger than $kp(2+p_1)/2 + ik(2-p_1)/4$ (pu), characteristic DF2 is checked.

Note: When the default settings are applied, the critical infeed current which determines DF1 checking or DF2 checking is 1.56×(CT secondary rated current).

- Apply an outflow current of the same magnitude and counterphase with the infeed current to terminal TB1-9 and 10.
- Decrease the out flow current in magnitude and measure the values at which the element operates.
- Check that the measured values are within 7% of the theoretical values.

For characteristic DF1, the theoretical outflow current is given by the following equation:

$$I_{out} = (2-p_1)(I_{in}-ik)/(2+p_1)$$
 (pu)
where, p_1 = slope setting of DF1
 ik = minimum operating current setting

When the default settings are applied, $I_{out} = [(I_{in}-0.3)/3] \times (CT \text{ secondary rated current}).$

For characteristic DF2, the theoretical outflow current is given by the following equation.

$$I_{out} = [(2-p_2)I_{in} - (2-p_1)ik + 2(p_2-p_1)kp]/(2+p_2) \text{ (pu)}$$
 where, p_2 = slope setting of DF2
 kp = break point of DF1 and DF2

When the default settings are applied, $I_{out} = 0.43 \times (CT \text{ secondary rated current})$.

Operating time

The testing circuit is shown in Figure 6.5.4.

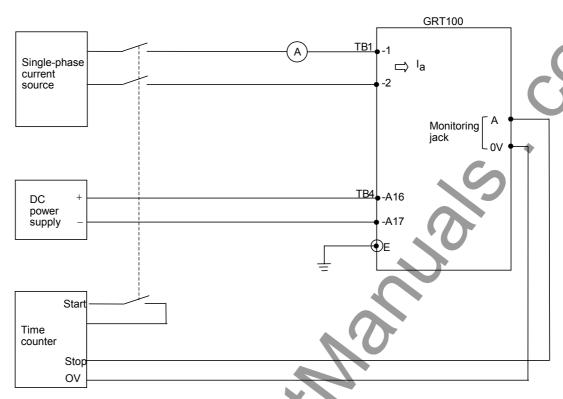


Figure 6.5.4 Operating Time Test (Model 100s, 200s)

- Set a test current to 3 times of DIF operating current (= CT secondary rated current × ik setting).
- Apply the test current and measure the operating time.
- Check that the operating time is 40 ms or less.

6.5.1.2 2F element

The testing circuit is shown in Figure 6.5.5.

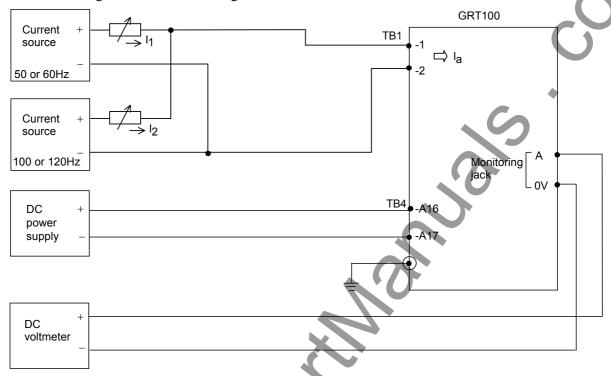


Figure 6.5.5 Testing 2F Element (Model 100s, 200s)

The output signal number of the 2F element is as follows:

Element	Signal number
2F	122

- Set the second harmonic restraint setting k2f to 15%(= default setting).
- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number to observe the 2F output at monitoring jack A and press the ENTER key.
- Set the fundamental frequency current I₁ to 3 times of ik setting. Change the magnitude of the second harmonic current I₂ and measure the value at which the element operates.
- Calculate the percentage of the second harmonic by I_2/I_1 when the element operates. Check that the percentage is within 7% of the k2f setting.

6.5.1.3 5F element

The testing circuit is shown in Figure 6.5.6.

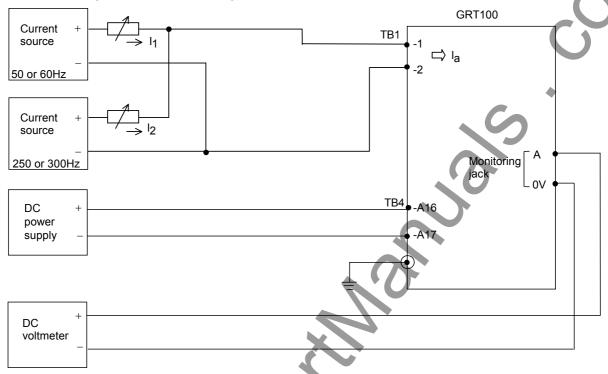


Figure 6.5.6 Testing 5F Element (Model 100s, 200s)

The output signal number of the 5F element is as follows:

Element	Signal number
5F	123

- Set the fifth harmonic restraint setting k5f to 30%.(= default setting)
- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number to observe the 5F output at monitoring jack A and press the ENTER key.
- Set the fundamental frequency current I₁ to 3 times of ik setting. Change the magnitude of the fifth harmonic current I₅ and measure the value at which the element operates.
- Calculate the percentage of the fifth harmonic by I_5/I_1 when the element operates. Check that the percentage is within 7% of the k5f setting.

6.5.1.4 High-set overcurrent element HOC

Operating current value

The testing circuit is shown in Figure 6.5.1.

The output signal numbers of the HOC elements are as follows:

Element	Signal number
HOC-A	41
НОС-В	42
HOC-C	43

- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number 41 to observe the HOC-A output at monitoring jack A and press the ENTER key.
- Apply a test current to A-phase current terminals and change the magnitude of the current applied and measure the value at which the element operates.

 Check that the measured value is within 7% of the following value.

Operating value = $(CT \text{ secondary rated current}) \times (kh \text{ setting})$

Operating time

The testing circuit is shown in Figure 6.5.4

- Set a test current to 2 times of HOC operating current (= CT secondary rated current × kh setting)
- Apply the test current and measure the operating time.
- Check that the operating time is 25 ms or less.

6.5.1.5 Restricted earth fault element REF

The restricted earth fault element is checked on the following items.

- Operating current value
- Percentage restraining characteristic

Note: Set all the CT ratio matching settings (1kct1 - 1kct3 to 3kct1 - 3kct3) to "1", because the operating value depends on the settings.

Operation current value

The testing circuit is shown in Figure 6.5.7.

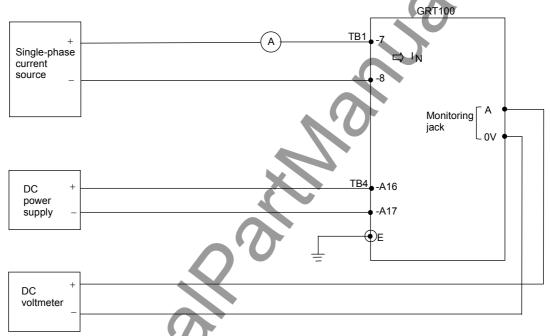


Figure 6.5.7 Operating Current Value Test of REF element (Model 100s, 200s)

The test current input terminal number and output signal number of the REF element is as follows:

Element	Input terminal number	Output signal number
1REF	TB1-7 and –8	71
2REF	TB1-15 and -16	74
3REF	TB1-23 and -24	77

- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit"
- Enter the signal number 71 to observe the 1REF output at monitoring jack A and press the ENTER key.
- Apply a test current to TB1-7 and -8 and change the magnitude of the current applied and measure the value at which the element operates.

Check that the measured value is within 15% of the theoretical operating value. Theoretical operating value = $(CT \text{ secondary rated current}) \times (1 \text{ ik setting})$

Percentage restraining characteristics

The percentage restraining characteristic is tested on the outflow current (l_{out}) and infeed current (l_{in}) plane as shown in Figure 6.5.8. The characteristic shown in Figure 6.5.8 is equivalent to the one on the differential current (ld) and restraining current (lr) plane shown in Figure 2.11.2.

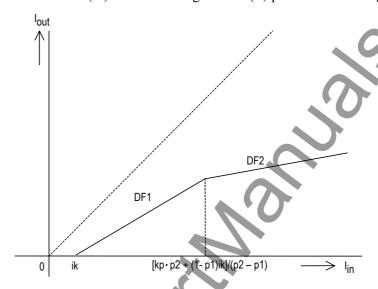


Figure 6.5.8 Restricted Earth Fault Element (Iout - Iin Plane)

Figure 6.5.9 shows a testing circuit simulating infeed from a neutral circuit and outflow from a primary winding.

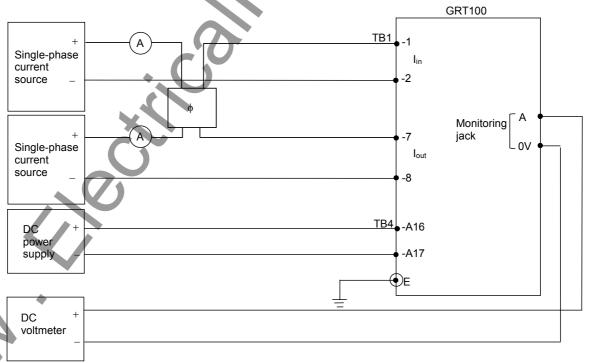


Figure 6.5.9 Testing Restricted Earth Fault Element (Model 100s, 200s)

• Enter a signal number 71 to observe the 1REF output at monitoring jack A and press the ENTER key.

• Apply an infeed current to terminal TB1-1 and -2.

When the infeed current applied is larger than the setting of ik (pu) and smaller than $[kp \cdot p2 + (1-p1)ik]/(p2-p1)$ (pu), characteristic DF1 is checked.

When the infeed current applied is larger than $[kp \cdot p2 + (1-p1)ik]/(p2-p1)$ (pu), characteristic DF2 is checked.

Note: When the default settings are applied, the critical infeed current which determines DF1 checking or DF2 checking is 1.6×(CT secondary rated current).

6 F 2 S 0 7 8 9

- Apply an outflow current of the same magnitude and counterphase with the infeed current, to terminal TB1-7 and -8.
- Decrease the outflow current in magnitude and measure the values at which the element operates.
- Check that the measured values are within 15% of the theoretical values.

For characteristic DF1, the theoretical outflow current is given by the following equation.

$$I_{out} = (1-p_1)(I_{in}-ik) (pu)$$

where,

 p_1 = slope setting of DF1 (= 0.1 fixed)

ik = minimum operating current setting

When the default settings are applied, $I_{out} = 0.9 \times (I_{in} - 0.5) \times (CT \text{ secondary rated current})$. For characteristic DF2, the theoretical outflow current is given by the following equation

$$I_{out} = (1-p_2) I_{in} + p_2 \times kp$$
 (pu)

where,

 p_2 = slope setting of DF2

kp = sensitivity setting of DF2

When the default settings are applied, $I_{out} = 1.0 \times (CT \text{ secondary rated current})$.

6.5.1.6 Definite time overcurrent elements OC, EF

The testing circuit is shown in Figure 6.5.10.

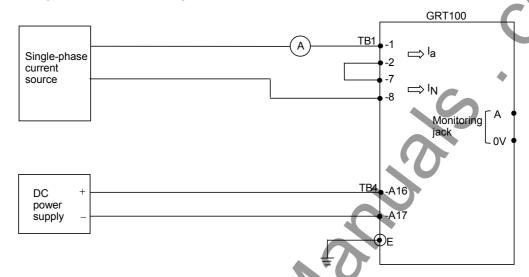


Figure 6.5.10 Testing OC and EF (Model 100s, 200s)

Element	Signal number
10C, 20C, 30C	47, 53, 59
1EF, 2EF, 3EF	72, 75, 78

The testing procedure is as follows:

- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number to observe the OC or EF output at monitoring jack A and press the ENTER key.
- Apply a test current and change the magnitude of the current applied and measure the value at which the element operates.

Check that the measured value is within $\pm 5\%$ of the theoretical operating value..

Theoretical operating value = (CT secondary rated current) \times (OC or EF setting)

6.5.1.7 Inverse time overcurrent elements OCI, EFI

The testing circuit is shown in Figure 6.5.11.

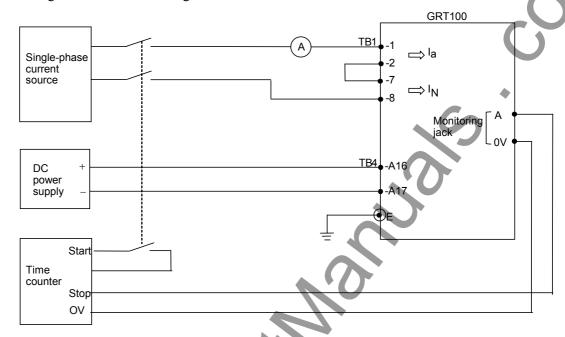


Figure 6.5.11 Testing OCI and EFI (Model 100s, 200s)

One of the four inverse time characteristics can be set, and the output signal numbers are as follows:

Element	Signal number
10CI, 20CI, 30CI	50, 56, 62
1EFI, 2EFI, 3EFI	73, 76, 79

Fix the time characteristic to test by setting the OCI or EFI on the "OC" screen.

"Setting (change)" sub-menu \rightarrow "Protection" screen \rightarrow "Trip" screen \rightarrow "Protection element" screen \rightarrow "OC" screen

The testing procedure is as follows:

- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number to observe the OCI or EFI output at monitoring jack A and press the ENTER key.
- Apply a test current and measure the operating time. The magnitude of the test current should be between $1.2 \times I_S$ to $20 \times I_S$, where $I_S = (CT \text{ secondary rated current}) \times (OCI \text{ or EFI current setting})$.
- Calculate the theoretical operating time using the characteristic equations shown in Section 2.11.4. Check that the measured operating time is within the error mentioned below.

Accuracy: Standard, Very and Long-time inverse: IEC 60255-3 class 5
Extremely inverse: IEC 60255-3 class 7.5

6.5.1.8 Thermal overload element THR

The testing circuit is shown in Figure 6.5.12.

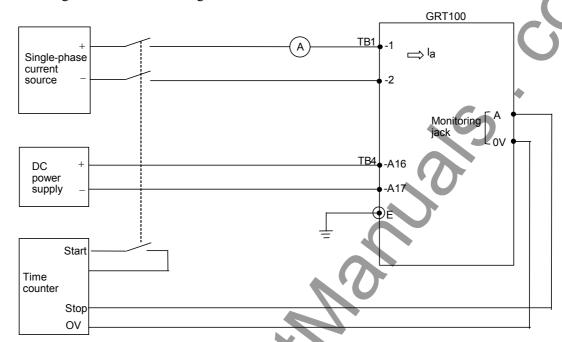


Figure 6.5.12 Testing THR (Model 100s, 200s)

This test is performed using time-shortened output signals because the operating time is in the order of minutes. The operating time of the time-shortened signals is one sixtieth that of the regular signals.

The time-shortened output signal number of the THR element is as follows:

Element	Signal number	Remarks
THR-A_TEST	88	Alarm
THR-S_TEST	84	Trip

The short-time testing procedure is as follows:

- Set the relay : $\tau = 60.0$ min, k = 1.30, $I_B = 1.00$, $I_P = 0.80$, $T_A = 10$ min
- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number to observe the THR short-time output at monitoring jack A and press the ENTER key.
- Apply a test current to 200% of the rated current and measure the operating time.
- Check that the measured operating time is within $\pm 10\%$ of the following value.

Element	Operating time (±10%)	
THR-A	11.5s (10.3s – 12.7s)	
THR-S	22.5s (20.2s - 24.8s)	

6.5.1.9 Frequency element FRQ

The frequency element is checked on the following items

- Operating frequency
- Undervoltage block

Operating frequency test

The testing circuit is shown in Figure 6.5.13.

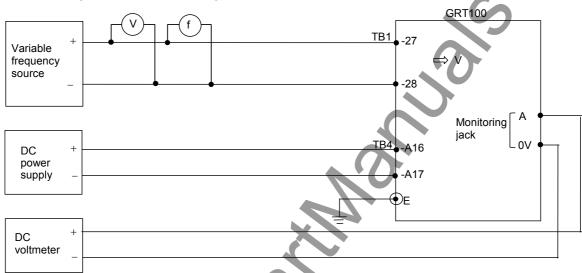


Figure 6.5.13 Testing Frequency Element (Model 100s, 200s)

The output signal numbers of the FRQ elements are as follows:

Element	Signal number	Remarks
81-1	89	Underfrequency tripping
•	91	Overfrequency tripping
81-2	90	Underfrequency alarm
	92	Overfrequency alarm

- Press 4 = Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number to observe the FRQ output at monitoring jack A and press the ENTER key.
- Apply rated voltage and change the magnitude of the frequency applied and measure the value at which the element operates. Check that the measured value is within ± 0.03 Hz of the setting.

Undervoltage block test

- Apply rated voltage and change the magnitude of frequency to operate the element.
- Keep the frequency that the element is operating, and change the magnitude of the voltage applied from the rated voltage to less than UV setting voltage. And then, check that the element resets.

6.5.1.10 Overexcitation element V/F

The overexcitation element is checked on the following items

- Operating value of definite time tripping and alarm characteristic
- Operating time of inverse time tripping characteristic

The output signal numbers of the V/F elements are as follows:

Element	Signal number	Remarks	
V/F	80	Definite time tripping	
	81	Inverse time tripping	
	82	Definite time alarm	

Operating value test for definite time tripping and alarm

The testing circuit is shown in Figure 6.5.14.

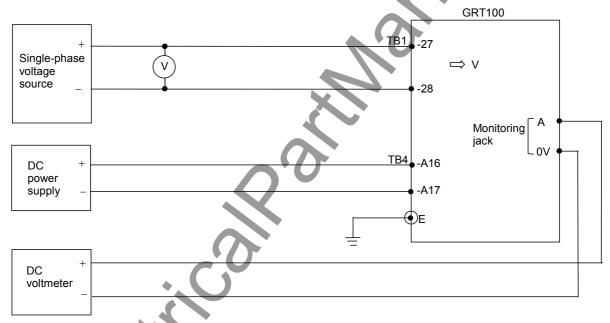


Figure 6.5.14 Operating Value Test of V/F (Model 100s, 200s)

- Set V (rated voltage setting) to 100V.
- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number 80 or 82 to observe the V/F output at monitoring jack A and press the ENTER key.
- Apply a test voltage at rated frequency and increase the magnitude of the voltage applied and measure the value at which an alarm signal or a trip signal is output. Check that the measured values are within 2% of (V setting) × (A setting) for an alarm signal and (V setting) × (H setting) for a trip signal.

Operating time characteristic test

The testing circuit is shown in Figure 6.5.15.

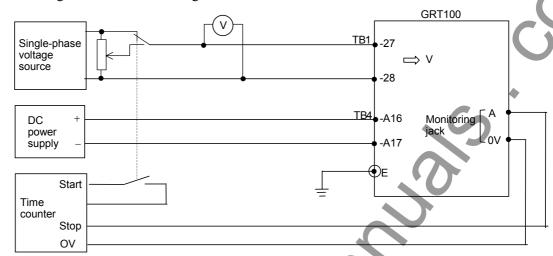


Figure 6.5.15 Operating Time Characteristic Test of V/F (Model 100s, 200s)

The testing procedure is as follows:

- Press 4 (= Logic circuit) on the "Test" sub-menu screen to display the "Logic circuit" screen.
- Enter a signal number 81 to observe the inverse time tripping output at monitoring jack A and press the ENTER key.
- Apply a test voltage at rated frequency and measure the operating time. The magnitude of the test voltage should be between (V setting) × (L setting) and (V setting) × (H setting).
- Calculate the theoretical operating time using the characteristic equations shown in Section 2.11.8 where V is the test voltage. Check that the measured operating time is from +15% to −10% of the calculated value.

6.5.2 Timer Test

The pick-up delay time of the variable timer can be measured by connecting the monitoring jacks A and B to a time counter as shown in Figure 6.5.15. Jacks A and B are used to observe the input signal and output signal of the timer, respectively.

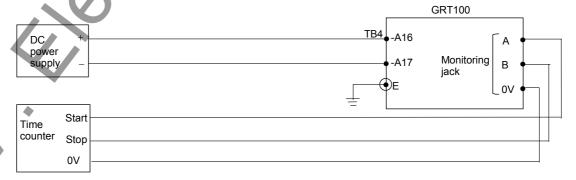


Figure 6.5.16 Testing Variable Timer (Model 100s, 200s)

• Press 3 (= Timer) on the "Test" sub-menu screen to display the "Timer" screen.

• Enter the number corresponding to the timer to be observed. The timers and assigned numbers are listed in Appendix C.

• Press the (END) key to display the following screen.

```
/2 Timer
Press ENTER to operate.
Press CANCEL to cancel.
```

• Press the ENTER key to start measuring the time. The "TESTING" LED turns on, and timer is initiated and the following display appears. The input and output signals of the timer can be observed at monitoring jacks A and B respectively.

Check that the measured time is within \pm 10ms of the setting time.

During the test, the following display appears on the LCD and the LEDs above the jacks are also lit if the input or output signal exists.

```
/2 Timer
Operating.....
Press END to reset.
Press CANCEL to cancel.
```

- Press the END key to reset the input signal to the timer. The "TESTING" LED turns off.
- Press the [CANCEL] key to test other timers. Repeat the above testing.

6.5.3 Protection Scheme

In the protection scheme tests, a dynamic test set is required to simulate power system pre-fault fault and post-fault conditions.

Tripping is observed with the tripping command output relays TRIP-1 to -5. Check that the indications and recordings are correct.

6.5.4 Metering and Recording

The metering function can be checked while testing the AC input circuit. See Section 6.4.4.

Fault recording can be checked while testing the protection schemes. Open the "Fault records" screen and check that the descriptions are correct for the applied fault.

Recording events are listed in Table 3.4.1. The top 8 events are external events and others are internal events. Event recording on the external events can be checked by changing the status of binary input signals. Change the status in the same way as the binary input circuit test (see Section 6.4.2) and check that the description displayed on the "Event Records" screen is correct.

Note: Whether to record or not can be set for each event. Change the status of the binary input signal after confirming that the related event is set to record. (The default setting enables all the events to be recorded.)

Some of the internal events can be checked in the protection scheme tests.

Disturbance recording can be checked while testing the protection schemes. The LCD display only shows the date and time when a disturbance is recorded. Open the "Disturbance records" screen and check that the descriptions are correct.

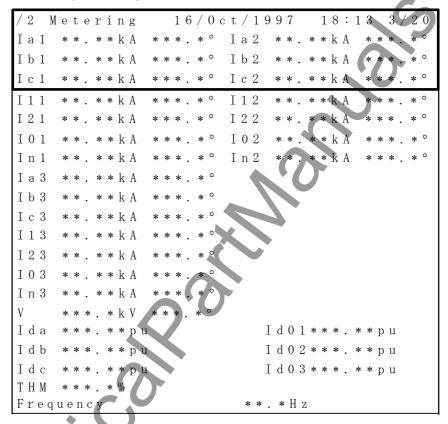
Details can be displayed on the PC. Check that the descriptions on the PC are correct. For details on how to obtain disturbance records on the PC, see the RSM100 Manual.

6.6 Conjunctive Tests

6.6.1 On Load Test

With the relay connected to the line which is carrying a load current, it is possible to check the polarity of the voltage transformer and current transformer and the phase rotation with the metering displays on the LCD screen.

• Open the following "Metering" screen from the "Status" sub-menu.



Note: The magnitude of voltage and current can be set in values on the primary side or on the secondary side by the setting. (The default setting is the primary side.)

Phase angles are expressed taking that of the voltage input as the reference angle.

- Check that the phase rotation is correct.
- Verify the phase relation between voltage and current with a known load current direction.

6.6.2 Tripping Circuit Test

The tripping circuit including the circuit breaker is checked by forcibly operating the output relay and monitoring the breaker that is tripped. Forcible operation of the output relay is performed on the "Binary output" screen of the "Test" sub-menu as described in Section 6.4.3.

Tripping circuit

- Set the breaker to be closed.
- Press 2 (= Binary output) on the "Test" sub-menu screen to display the "Binary output" screen. The LCD displays the output modules mounted.

• Enter 1 to select the IO1 module, then the LCD displays the screen shown below.

/3 B0		(0 = D i s a b l e 1 = E n a b l e)	1 / 5
I 0 1	T P - 1	: T B 4 -A 1 , B 1	0 _
I 0 1	TP-2	: T B 4 -A 2 , B 2	0
I 0 1	T P - 3	: T B 4 -A 3 , B 3	0
I 0 1	T P - 4	: TB4-A12, B12	0
I 0 1	T P - 5	: T B 4 -A 1 3, B 1 3	0

TP-1 to 5 are output relays with one normally open contact.

- Enter 1 for TP-1 and press the ENTER key.
- Press the (END) key. Then the LCD displays the screen shown below.

```
/3 BO
Keep pressing 1 to operate.
Press CANCEL to cancel.
```

- Keep pressing the 1 key to operate the output relay TP-1 and check that the No. 1 breaker is tripped.
- Release pressing the 1 key to reset the operation.
- Repeat the above for other output relays TP-2 to TP-5.

6 F 2 S 0 7 8 9

6.7 Maintenance

6.7.1 Regular Testing

The relay is almost completely self-supervised. The circuits which cannot be supervised are binary input and output circuits and human interfaces.

Therefore regular testing can be minimized to checking the unsupervised circuits. The test procedures are the same as described in Sections 6.4.1, 6.4.2 and 6.4.3.

6.7.2 Failure Tracing and Repair

Failures will be detected by automatic supervision or regular testing.

When a failure is detected by supervision, a remote alarm is issued with the binary output signal of FAIL and the failure is indicated on the front panel with LED indicators or LCD display. It is also recorded in the event record.

Failures detected by supervision are traced by checking the "Auto-supervision "screen on the LCD

If any messages are shown on the LCD, the failed module or failed external circuits can be located by referring to Table 6.7.1.

This table shows the relationship between messages displayed on the LCD and the estimated failure location. Locations marked with (1) have a higher probability than locations marked with (2).

As shown in the table, some of the messages cannot identify the fault location definitely but suggest plural possible failure locations. In these cases, the failure location is identified by replacing the suggested failed modules with spare modules one by one until the "Alarm" LED is turned off.

The replacement or investigation should be performed first for the module or circuit with higher probability in the table.

If there is a failure and the LCD is not working such as a screen is frozen or not displayed, the failure location is either SPM or HMI module.

Table 6.7.1 LCD Message and Failure Location

Message				Failure I	ocation		
	VCT	SPM	IO1	102	IO3	НМІ	AC cable
Checksum err		×					
ROM-RAM err		×					
SRAM err		×					
BU-RAM err		×					10
DPRAM err		×					
EEPROM err		×					(0
A/D err		×					J'
CT1 err	× (2)	× (1)					× (2)
CT2 err	× (2)	× (1)				7	× (2)
CT3 err	× (2)	× (1)					× (2)
Sampling err		×			7		
DIO err		× (2)	× (1)	× (1)	× (1)		
RSM err		× (2)	× (1)				
No-working of LCD		× (2)	\'	U		× (1)	

The location marked with (1) has a higher probability than the location marked with (2).

If no message is shown on the LCD, this means that the failure location is either in the DC power supply circuit or in the microprocessors mounted on the SPM module. Then check the "ALARM" LED. If it is off, the failure is in the DC power supply circuit. If it is lit, open the relay front panel and check the LEDs mounted on the SPM module. If the LED is off, the failure is in the DC power supply circuit. If the LED is lit, the failure is in the microprocessors.

In the former case, check if the correct DC voltage is applied to the relay.

If so, replace the IO1 module mounting the DC/DC converter and confirm that the "ALARM" LED is turned off.

In the latter case, replace the SPM module containing the processors and confirm that the "ALARM" LED is turned off.

When a failure is detected during regular testing, it will not be difficult to identify the failed module to be replaced.

Note: When a failure or an abnormality is detected during the regular test, confirm the following first:

- Test circuit connections are correct.
- Modules are securely inserted in position.
- Correct DC power voltage with correct polarity is applied and connected to the correct terminals.
- Correct AC inputs are applied and connected to the correct terminals.
- Test procedures comply with those stated in the manual.

6.7.3 Replacing Failed Modules

If the failure is identified to be in the relay module and the user has spare modules, the user can recover the protection by replacing the failed modules.

Repair at the site should be limited to module replacement. Maintenance at the component level is not recommended.

Check that the replacement module has an identical module name (VCT, SPM, IO1, IO2, etc.) and hardware type-form as the removed module. Furthermore, the SPM module should have the same software name.

The module name is indicated on the bottom front of the relay case. The hardware type-form is indicated on the module in the following format:

Module name	Hardware type-form
VCT	G1PC2-□□□□
SPM	G1SP∗-□□□□
IO1	G1IO1-□□□□
102	G1102-□□□□
IO3	G1103-□□□□
HMI	

The software name is indicated on the memory device on the module with letters such as GS1TM1-***, GS1TM2-***, etc.

A CAUTION When handling a module, take anti-static measures such as wearing an earthed

wrist band and placing modules on an earthed conductive mat. Otherwise,

many of the electronic components could suffer damage.

CAUTION After replacing the SPM module, check all of the settings including the data

related the PLC and IEC103, etc. are restored the original settings.

The initial replacement procedure is as follows:

• Switch off the DC power supply.

▲ WARNING Hazardo

Hazardous voltage may remain in the DC circuit just after switching off the DC power supply. It takes approximately 30 seconds for the voltage to discharge.

- Disconnect the trip outputs.
- Short circuit all AC current inputs and disconnect all AC voltage inputs.
- Unscrew the relay front cover.

Replacing the Human Machine Interface (HMI) Module (Front Panel)

- Open the front panel of the relay by unscrewing the binding screw located on the left side of the front panel.
- Unplug the ribbon cable on the front panel by pushing the catch outside.
- Remove the two retaining screws and one earthing screw on the relay case side, then detach the front panel from the relay case.
- Attach the replacement module in the reverse procedure.

Replacing the Transformer (VCT) Module

CAUTION Before pulling out the transformer module, pull out all other modules. For the method of pulling out other module, see the section "Replacing other module".

- Open the right-side front panel (HMI module) by unscrewing the two binding screws located on the left side of the panel.
- Open the left-side front panel (blind panel) (*) by unscrewing the two binding screws located on the right side of the panel.
 - (*) This blind panel is attached only to models assembled in the type B case.
- Detach the module holding bar by unscrewing the binding screw located on the left side of the bar.
- Unplug the ribbon cable on the SPM module by nipping the catch.
- Remove the metal cover by unscrewing the binding screw located at the top and bottom of the cover.
- Pull out the module.
- Insert the replacement module in the reverse procedure.

Replacing other modules

- Open the right-side front panel (HMI module) by unscrewing the two binding screws located on the left side of the panel.
- Open the left-side front panel (blind panel) (*) by unscrewing the two binding screws located on the right side of the panel.
 - (*) This panel is attached only to models assembled in the type B case.
- Detach the module holding bar by unscrewing the binding screw located on the left side of the bar.
- Unplug the ribbon cable running among the modules by nipping the catch (in case of black connector) and by pushing the catch outside (in case of gray connector) on the connector.
- Pull out the module by pulling up or down the top and bottom levers.
- Insert the replacement module in the reverse procedure.
- After replacing the SPM module, input the user setting values again.

For failed module tracing and its replacement, see Appendix Q.

6.7.4 Resumption of Service

After replacing the failed module or repairing failed external circuits, take the following procedures for the relay to restore the service.

• Switch on the DC power supply and confirm that the "IN SERVICE" green LED is lit and the "ALARM" red LED is not lit.

Note: Supply DC power after checking that all the modules are in their original positions and the ribbon cables are plugged in.

• Supply the AC inputs and reconnect the trip outputs.

6.7.5 Storage

The spare relay or module should be stored in a dry and clean room. Based on IEC Standard 60255-6 the storage temperature should be -25° C to $+70^{\circ}$ C, but the temperature of 0° C to $+40^{\circ}$ C is recommended for long-term storage.

7. Putting Relay into Service

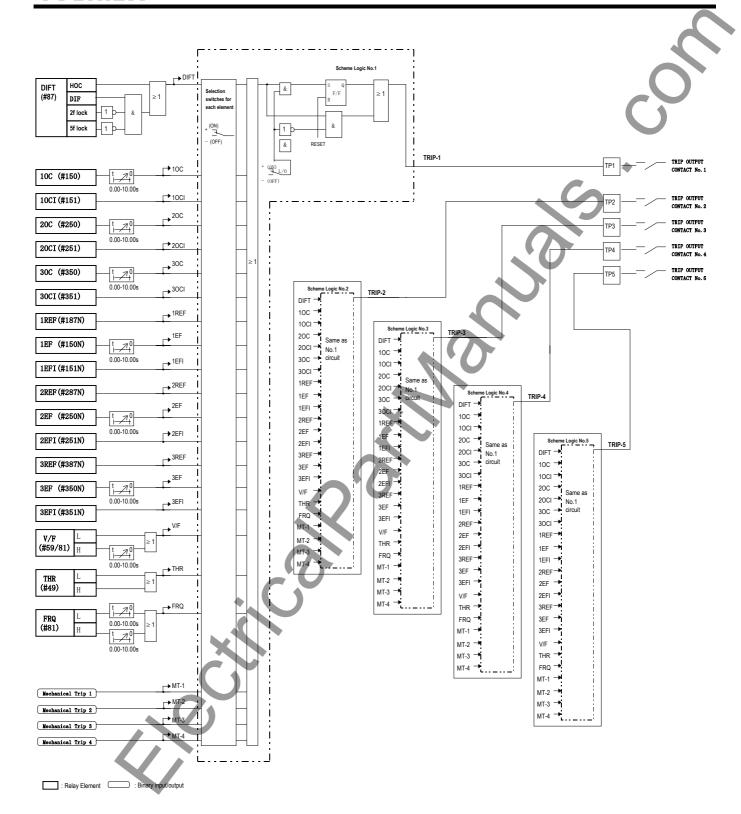
The following procedure must be adhered to when putting the relay into service after finishing commissioning or maintenance tests.

- Check that all external connections are correct.
- Check the setting of all measuring elements, timers, scheme switches, recordings and clock are correct.
 - In particular, when settings are changed temporarily for testing, be sure to restore them.
- Clear any unnecessary records on faults, events and disturbances which are recorded during the tests.
- Press the VIEW key and check that no failure message is displayed on the "Auto-supervision" screen.
- Check that the green "IN SERVICE" LED is lit and no other LEDs are lit on the front panel.



Appendix A

Block Diagram



Block Diagram of Transformer Differential Relay GRT100

Appendix B
Signal List

Signal list					
No.	Signal Name	Contents			
0	MEGUANIIO AL TRIBA	PLANTOLIAN IOAL TRIP ()			
<u>1</u> 2	MECHANICAL TRIP1 MECHANICAL TRIP2	BI (MECHANICAL TRIP 1) BI (MECHANICAL TRIP 2)			
3	MECHANICAL TRIP3	BI (MECHANICAL TRIP 3)			
4	MECHANICAL TRIP4	BI (MECHANICAL TRIP 4)			
5	IND. RESET	BI (lidication reset)			
<u>6</u> 7					
8					
9					
10					
11 12					
13					
14	EVENT1 EVENT2	BI (External event signal)			
15 16	EVENT3	ditto ditto			
17	LVLINIS	ditto			
18					
19					
20 21					
22					
23					
24		A 1/ F			
25 26					
27					
28					
29 30					
31					
32					
33					
34 35					
36		A			
37					
38 39					
40					
41	DIFT HOC-A	Differential relay			
42 43	DIFT HOC-B DIFT HOC-C	ditto			
44	DIFT NOC-C	ditto			
45	DIFT DIF-B	ditto			
46	DIFT DIF-C	ditto			
47 48	10C-A 10C-B	OC relay ditto			
49	10C-C	ditto			
50	10CI-A	Inverse time OC relay			
51 52	10CI-B 10CI-C	ditto ditto			
53	20C-A	OC relay			
54	2OC-B	ditto			
55	20C-C	ditto			
56 57	20Cl-A	Inverse time OC relay ditto			
58	20CI-B 20CI-C	ditto			
59	3OC-A	OC relay			
60	3OC-B	ditto			
61 62	30C-C 30CI-A	ditto Inverse time OC relay			
63	3OCI-B	ditto			
64	3OCI-C	ditto			
	40C-A	OC relay			
	40C-B 40C-C	ditto ditto			
68	4OCI-A	Inverse time OC relay			
69	4OCI-B	ditto			

Signa	al list	
No.	Signal Name	Contents
	1REF	Restricted earth fault relay
	1EF 1EFI	Earth fault relay Inverse time earth fault relay
74	2REF	Restricted earth fault relay
	2EF	Earth fault relay
76 77	2EFI 3REF	Inverse time earth fault relay Restricted earth fault relay
78	3EF	Earth fault relay
	3EFI V/F-H	Inverse time earth fault relay Overexcitation relay
	V/F-T	ditto
_	V/F-A	ditto
83 84	THR-S THR-S (FOR TESTING)	Thermal overload relay ditto
85		
86 87	THR-A	Thermal overload relay
	THR-A (FOR TESTING)	ditto
89	FRQ-L1	Frequency relay
	FRQ-L2 FRQ-H1	ditto
92	FRQ-H2	ditto
93	CTF	CT failure detection
94 95	CTF ALARM	CT failure alarm
96		N'U
97 98		
99		
100		
101 102		
103		
104 105		
106		
107		
108 109		
110		
111 112		
113		
114		
115 116		
117	*	
118 119		
120		
121	DIF TRIP	DIF relay trip
122	2F LOCK 5F LOCK	2F detect 5F detect
124	DIF-T1	DIF relay trip 1
	DIF-T2	DIF relay trip 2 DIF relay trip 3
127	DIF-T3 DIF-T4	DIF relay trip 3 DIF relay trip 4
128	DIF-T5	DIF relay trip 5
129	T1OC 1OC-1	10C relay timer 10C relay trip 1
131	10C-2	1OC relay trip 2
132	10C-3	10C relay trip 3
	10C-4 10C-5	10C relay trip 4 10C relay trip 5
135	10CI-1	1OCI relay trip 1
136	10CI-2 10CI-3	10Cl relay trip 2 10Cl relay trip 3
	10CI-3 10CI-4	10Cl relay trip 4
139	10CI-5	1OCI relay trip 5
140	T2OC	2OC relay timer

Sig	nal	list
0.9		

Signa No.	Signal Name	Contents
141	20C-1	2OC relay trip 1
	20C-2	2OC relay trip 2
	2OC-3	2OC relay trip 3
	20C-4 20C-5	2OC relay trip 4 2OC relay trip 5
	20Cl-1	20Cl relay trip 1
	20CI-2	2OCI relay trip 2
	20CI-3 20CI-4	2OCI relay trip 3 2OCI relay trip 4
150	20CI- 4 20CI-5	20Cl relay trip 5
	T3OC	3OC relay timer
152	3OC-1 3OC-2	3OC relay trip 1 3OC relay trip 2
154	30C-3	3OC relay trip 3
155	3OC-4	3OC relay trip 4
	3OC-5	3OC relay trip 5
	30CI-1 30CI-2	3OCI relay trip 1 3OCI relay trip 2
	3OCI-3	3OCI relay trip 3
	30Cl-4	3OCI relay trip 4
	3OCI-5 T4OC	3OCI relay trip 5 4OC relay timer
	40C-1	4OC relay trip 1
164	4OC-2	4OC relay trip 2
	4OC-3 4OC-4	4OC relay trip 3 4OC relay trip 4
	40C-5	4OC relay trip 4
168	40CI-1	4OCI relay trip 1
	40Cl-2	4OCI relay trip 2
	40Cl-3 40Cl-4	4OCI relay trip 3 4OCI relay trip 4
172	40CI-5	4OCI relay trip 5
	T1REF	1REF relay timer
174 175	T1EF 1REF-1	1EF relay timer 1REF relay trip 1
176	1REF-2	1REF relay trip 2
	1REF-3	1REF relay trip 3
	1REF-4 1REF-5	1REF relay trip 4 1REF relay trip 5
	1EF-1	1EF relay trip 1
	1EF-2	1EF relay trip 2
	1EF-3 1EF-4	1EF relay trip 3 1EF relay trip 4
		1EF relay trip 5
185	1EFI-1	1EF) relay trip 1
	1EFI-2 1EFI-3	1EFI relay trip 2 1EFI relay trip 3
188	1EFI-4	1EFI relay trip 4
	1EFI-5	1EFI relay trip 5
	T2REF T2EF	2REF relay timer 2EF relay timer
192	2REF-1	2REF relay trip 1
193	2REF-2	2REF relay trip 2
	2REF-3 2REF-4	2REF relay trip 3 2REF relay trip 4
196	2REF-5	2REF relay trip 5
197	2EF-1	2EF relay trip 1
198	2EF-2 2EF-3	2EF relay trip 2 2EF relay trip 3
200	2EF-4	2EF relay trip 3
201	2EF-5	2EF relay trip 5
	2EFI-1 2EFI-2	2EFI relay trip 1 2EFI relay trip 2
	2EFI-3	2EFT relay trip 2 2EFT relay trip 3
205	2EFI-4	2EFI relay trip 4
206	2EFI-5	2EFI relay trip 5
207	T3REF T3EF	3REF relay timer 3EF relay timer
209	3REF-1	3REF relay trip 1
210	3REF-2	3REF relay trip 2

Signal	list

Signa	al list	
No.	Signal Name	Contents
211	3REF-3	3REF relay trip 3
	3REF-4	3REF relay trip 4
	3REF-5	3REF relay trip 5
214	3EF-1	3EF relay trip 1
	3EF-2	3EF relay trip 2
	3EF-3	3EF relay trip 3
	3EF-4	3EF relay trip 4
218	3EF-5 3EFI-1	3EF relay trip 5 3EFI relay trip 1
	3EFI-2	3EFI relay trip 2
	3EFI-3	3EFI relay trip 3
	3EFI-4	3EFI relay trip 4
223	3EFI-5	3EFI relay trip 5
224	DIF-T	DIFT relay trip
225	10Cl	10Cl relay trip
226	2OCI	20Cl relay trip
	3OCI	3OCI relay trip
	4OCI	4OCI relay trip
	V/F TRIP	V/F trip
231	FRQ	FRQ trip
232		
233		
234		
	TV/F-H	V/F-H relay timer
236	TV/F-A	V/F-A relay timer
	V/F-1	V/F relay trip 1
	V/F-2	V/F relay trip 2
	V/F-3	V/F relay trip 3
	V/F-4	V/F relay trip 4
	V/F-5 V/F-ALARM	V/F relay trip 5
	THR-1	V/F relay alarm THR relay trip 1
	THR-2	THR relay trip 2
	THR-3	THR relay trip 3
	THR-4	THR relay trip 4
	THR-5	THR relay trip 5
	THR-ALARM	THR relay alarm
	TFRQ-L	FRQ-L relay timer
	TFRQ-H	FRQ-H relay timer
	TFRQ-A	FRQ-A relay timer
	FRQ-1 FRQ-2	FRQ relay trip 1 FRQ relay trip 2
	FRQ-3	FRQ relay trip 3
	FRQ-4	FRQ relay trip 4
	FRQ-5	FRQ relay trip 5
257	FRQ-A	FRQ relay alarm
258	MECHANICAL TRIP1-1	Machanical trip 1
259	MECHANICAL TRIP1-2	ditto
260	MECHANICAL TRIP1-3	ditto
	MECHANICAL TRIP1-4	ditto
	MECHANICAL TRIP1-5	ditto
	MECHANICAL TRIP2-1 MECHANICAL TRIP2-2	Machanical trip 2
	MECHANICAL TRIP2-2 MECHANICAL TRIP2-3	ditto
	MECHANICAL TRIP2-3	ditto
	MECHANICAL TRIP2-5	ditto
	MECHANICAL TRIP3-1	Machanical trip 3
269	MECHANICAL TRIP3-2	ditto
270	MECHANICAL TRIP3-3	ditto
271	MECHANICAL TRIP3-4	ditto
	MECHANICAL TRIP3-5	ditto
	MECHANICAL TRIP4-1	Machanical trip 4
	MECHANICAL TRIP4-2	ditto
	MECHANICAL TRIP4-3	ditto
	MECHANICAL TRIP4-4 MECHANICAL TRIP4-5	ditto
	WINDING1 RELAY OR-1	ditto Element for trip 1
	WINDING! RELAY OR-1	ditto
		ditto

Signa	al list	
No.	Signal Name	Contents
	WINDING4 RELAY OR-1	ditto
	MECHANICAL TRIP OR-1 ELEMENT OR-1	ditto
	TRIP-1	Trip O/P-1
285	WINDING1 RELAY OR-2	Element for trip 2
286 287	WINDING2 RELAY OR-2 WINDING3 RELAY OR-2	ditto
288	WINDING4 RELAY OR-2	ditto
	MECHANICAL TRIP OR-2	ditto
	ELEMENT OR-2 TRIP-2	ditto Trip O/P-2
292	WINDING1 RELAY OR-3	Element for trip 3
	WINDING2 RELAY OR-3 WINDING3 RELAY OR-3	ditto ditto
	WINDINGS RELAY OR-3 WINDING4 RELAY OR-3	ditto
296	MECHANICAL TRIP OR-3	ditto
	ELEMENT OR-3 TRIP-3	ditto Trip O/P-3
	WINDING1 RELAY OR-4	Element for trip 4
300	WINDING2 RELAY OR-4	ditto
	WINDING3 RELAY OR-4 WINDING4 RELAY OR-4	ditto ditto
303	MECHANICAL TRIP OR-4	ditto
	ELEMENT OR-4	ditto
	TRIP-4 WINDING1 RELAY OR-5	Trip O/P-4 Element for trip 5
307	WINDING2 RELAY OR-5	ditto
	WINDING RELAY OR-5	ditto
	WINDING4 RELAY OR-5 MECHANICAL TRIP OR-5	ditto ditto
	ELEMENT OR-5	ditto
	TRIP-5 TRIP	Trip O/P-5 Trip signal shot
314	TRIP-DETOR	Trip O/P OR
315		
316 317		
318		
319 320		
321		
322 323		
324		
325		. 0
326 327		
328		
329 330		
331		*
332		
333		
335		
336		
337 338	\\	
339		
340 341		
342		
343		
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1238		
1238		
1240		

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Signa	al list	
No.	Signal Name	Contents
	IEC_MDBLK	monitor direction blocked
	IEC TESTMODE	IEC60870-5-103 testmode
	GROUP1_ACTIVE	group1 active
1244	GROUP2_ACTIVE GROUP3 ACTIVE	group2 active group3 active
	GROUP4 ACTIVE	group4 active
	GROUP5 ACTIVE	group5 active
1248	GROUP6_ACTIVE	group6 active
1249	GROUP7_ACTIVE	group7 active
	GROUP8_ACTIVE	group8 active
1251	RLY_FAIL RLY_OP_BLK	RELAY FAILURE RELAY OUTPUT BLOCK
1253	A.M.F. OFF	SV BLOCK
1254		
1255		
1256 1257		
	RELAY FAIL-A	RELAY FAILURE (only alarm)
1259		
1260		
	TRIP-H	Trip signal hold
1262		
1263 1264		
1265		. (/>
1266		
1267	CT1_ERR	CT failure
	CT2_ERR	ditto
	CT3_ERR	ditto
	CT4_ERR CT ERR	ditto
1272	CT LIKE	unto
1273		
1274		
1275		
1276 1277		A'U'
1278		
1279	GEN PICKUP	General start/pick-up
	GEN_TRIP	General trip
1281 1282		
1283		
1284		\
1285		
1286		
1287		
1288 1289		
1290		
1291		
1292		
1293		
1294 1295		
1295	17 ⁴	
1297	V	
1298		
1299		
1300 1301		
1302		
1303		
1304		
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1398		
1399		
1400		

Signa	l list	
No.	Signal Name	Contents
	LOCAL_OP_ACT	local operation active
	REMOTE_OP_ACT	remote operation active
	NORM_LED_ON	IN-SERVICE LED ON
1404	ALM_LED_ON	ALARM LED ON
1405	TRIP_LED_ON	TRIP LED ON
	TEST_LED_ON	TEST LED ON
1407 1408		
	LED_RESET	TRIP LED RESET
1410	EED_NESET	TIMI LEDINEGET
1411		
1412		(0)
1413	PROT_COM_ON	IEC103 communication command
	PRG_LED1_ON	PROGRAMMABLE LED1 ON
	PRG_LED2_ON	PROGRAMMABLE LED2 ON
	PRG_LED3_ON	PROGRAMMABLE LED3 ON
	PRG_LED4_ON	PROGRAMMABLE LED4 ON
1418 1419		
1419		
1420		
1422		
1423		
1424		
1425		
1426		
1427		
1428 1429		
1430		
1431		
1432		
1433		
	F.Record_DONE	fault location completed
	F.Record_CLR	Fault record clear
	E.Record_CLR D.Record_CLR	Event record clear Disturbance record clear
1438	D.Record_CER	Disturbance record clear
1439		
1440		
1441		
1442		
1443 1444		· ()
	PLC_data_CHG	PLC data change
1446	I LO_uata_OHG	i Lo data Grange
1447		
	Sys.set_change	System setting change
1449	Rly.set_change	Relay setting change
	Grp.set_change	Group setting change
1451 1452		
1452		
1454		
1455	. (/1	
1456	KEY-VIEW	VIEW key status (1:pressed)
	KEY-RESET	RESET key status (2:pressed)
	KEY-ENTER	ENTER key status (3:pressed)
	KEY-END	END key status (4:pressed) CANCEL key status (5:pressed)
1460	KEY-CANCEL	CANCEL REY SIGIUS (3.PIESSEU)
1462		
1463		
1464	,	
1465		
1466		
1467		
1468 1469		
1469		

Sign	al list	
No.	Signal Name	Contents
1471		
1472 1473	SUM_err	Program ROM checksum error
1474	SRAM err	SRAM memory monitoring error
1475	BU-RAM err	BU-RAM memory monitoring error
1476	DP-RAM_err EEPROM_err	DP-RAM memory monitoring error EEPROM memory monitoring error
1478	SUB-CPU err	Sub-CPU stopped
1479	AD_err	A/D accuracy checking error
1480 1481)	
1482	2	(0)
1483	3	
1484	DIO_err	DIO card connection error
1486	LCD err	LCD panel connection error
1487	7	
1488 1489	3	
1490		
1491		
1492 1493	<u> </u>	
1494		
1495	5	
1496 1497	7	
1498	3	
1499 1500		
1501		
1502	2	
1503 1504	3	
1505	5	
1506	6	A-0
1507 1508	3	
1509		
1510		
1511 1512	2	
1513	3	
1514 1515		
1516		
1517		
1518 1519		
1520		
1521		
1522 1523		
1524		
1525		
1526 1527		
1528	3	
1529 1530		
1531		
1532	2	
1533 1534		
1535		
$\sqrt{}$		
13		
1534 1538		
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Ciana	d liet	
Signa		
No.	Signal Name	Contents
1536		
1537 1538		
1539		
:		
:		
:		
2601 2602		
2602		
2604		
2605		
2606		
2607		
2608		
2609 2610		A V
2610		
2612		
2613		
2614		
2615		
2616		
2617 2618		N.O.
2619		
2620		
2621		
2622		
2623		
2624 2625		
2626		
2627		
2628		
2629		
2630		
2631	D.RECORD1	Disturbance record stored command 1
	D.RECORD2	2
	D.RECORD3	3
2635	D.RECORD4	4
2636		
2637		—
2638 2639		
	SET.GROUP1	Active setting group changed command (Change to group1)
2641	SET.GROUP2	2
2642	SET.GROUP3	3
2643	SET.GROUP4	4
2644	SET.GROUPS	5
2645	SET.GROUP6 SET.GROUP7	6 7
2647	SET.GROUP8	8
2648		
2649		
2650		
2651	V	
2652 2653	*	
2653		
2655	P	
2656		
2657		
2658		
2659		
2660		

Signa	al list	
No.	Signal Name	Contents
2661		
2662		
2663 2664		
2665		
2666		
2667		
2668		
2669 2670		
2671		
2672		
2673 2674		
2675		
2676		
2677		
2678 2679		
2680		
2681		
2682		
2683 2684		
2685		N
2686	PROT_COM_RECV	protection inactivate command received
2687		
	TPLED_RST_RCV	TRIP LED RESET command received
2689 2690		
2691		
2692		
2693 2694		
2695		<u> </u>
2696		
2697		
2698 2699		
2700		
2701		
2702		
2703 2704	*	
2704		
2706		
2707	X	
2708 2709		
2710		
2711		
2712	. (/)	
2713 2714	. V	
:		
4		
:		
2798 2799	Y	
2800		
2801		
2802		
2803 2804		
2804		
2806		
2807		
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3018 TEMP203 3019 TEMP204 3020 TEMP205

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2955	TEMP140	
2956	TEMP141	
2957	TEMP142	
2958	TEMP143	
2959	TEMP144	
2960	TEMP145	

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2959 TEMP144	
2960 TEMP145	
2961 TEMP146	
2962 TEMP147	
2963 TEMP148	
2964 TEMP149	
2965 TEMP150	
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2977 TEMP 162 2978 TEMP 163	
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2992 TEMP177	
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2997 TEMP182	
2998 TEMP183	
2999 TEMP184	
3000 TEMP185	
3001 TEMP186	
3002 TEMP187	
3003 TEMP188	
3004 TEMP189	
3005 TEMP190	
3006 TEMP191	†
3007 TEMP192	

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No.	Signal Name	Contents
	TEMP206	
	TEMP207	
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	TEMP209	
	TEMP210	
	TEMP211	
	TEMP212	
	TEMP213	
	TEMP214	
	TEMP215	
	TEMP216	
	TEMP217	
3033	TEMP218	
3034	TEMP219	
	TEMP220	
3036	TEMP221	
	TEMP222	
3038	TEMP223	
	TEMP224	
3040	TEMP225	
	TEMP226	
3042	TEMP227	
3043	TEMP228	
3044	TEMP229	
3045	TEMP230	
	TEMP231	
	TEMP232	
	TEMP233	
	TEMP234	
	TEMP235	
	TEMP236	A'U
3052	TEMP237	
	TEMP238	
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	TEMP240	
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	TEMP244	
	TEMP245 TEMP246	
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	TEMP250	
	TEMP251	
	TEMP252	
3068	TEMP253	
3069	TEMP254	
	TEMP255	
	TEMP256	

Appendix C

Variable Timer List

Variable Timer List

Timer	Timer No.	Contents
T10C	1	10C TRIP TIMER
T2OC	2	20C TRIP TIMER
T3OC	3	3OC TRIP TIMER
(T4OC)	4	(40C TRIP TIMER)
T1REF	5	1REF TRIP TIMER
T1EF	6	1EF TRIP TIMER
T2REF	7	2REF TRIP TIMER
T2EF	8	2EF TRIP TIMER
T3REF	9	3REF TRIP TIMER
T3EF	10	3EF TRIP TIMER
TVFH	11	V/F-H TRIP TIMER
TVFA	12	V/F-A ALARM TIMER
TFRQL	13	FRQ-L TRIP TIMER
TFRQH	14	FRQ-H TRIP TIMER
TFRQA	15	FRQ-A ALARM TIMER

Appendix D

Binary Output Default Setting List

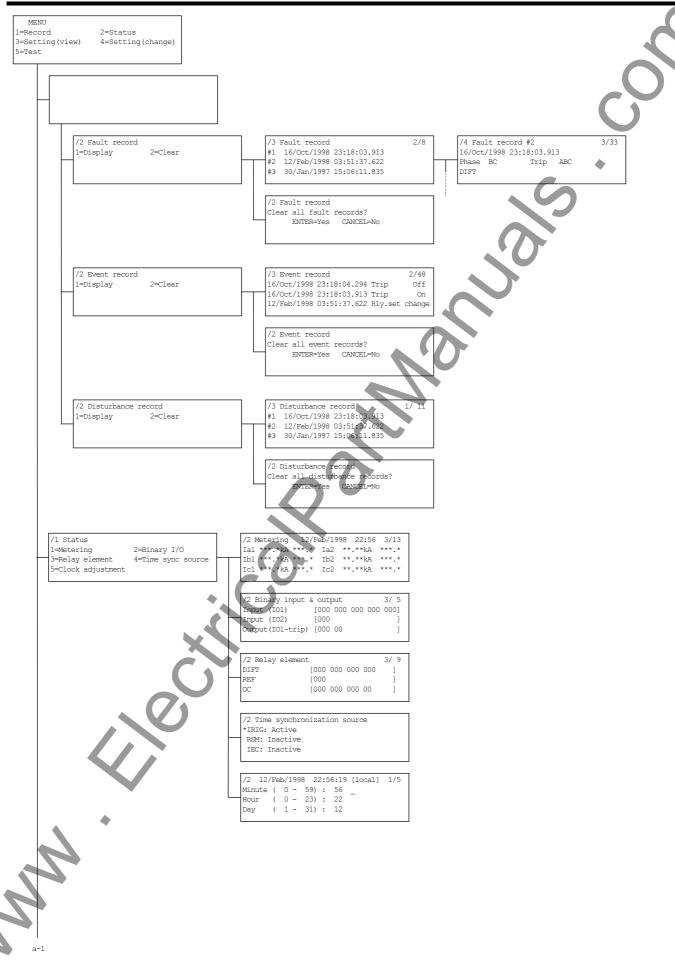
Binary Output Default Setting List

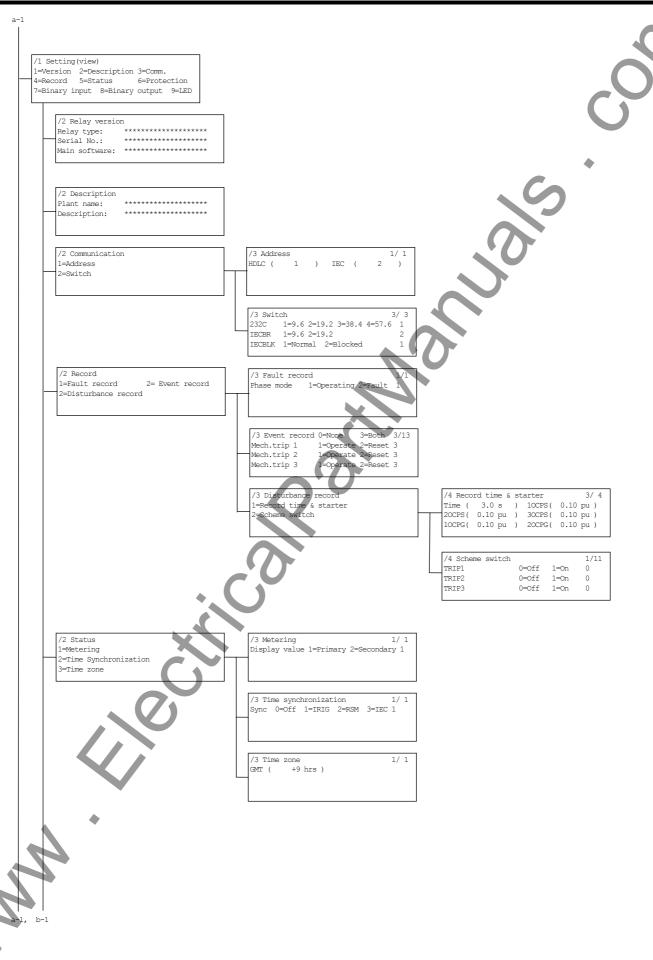
Relay	Module	BO No.	Terminal	Signal Name	Contents		Setting	
Model	Name		No.			Signal No.	Logic	Timer
							(OR: 1, AND:	(OFF: 0, ON: 1)
							2)	
GRT100			TB3:				•	
-101	IO2	BO1	A2-A1	TRIP-1	TRIP First	284	1	1
		BO2	A2-B1	TRIP-2	TRIP Second	291		1
		BO3	A2-B2	DIFT	DIFT relay operating	224		1
		BO4	A3-B3	10C, 10Cl	1OC or 1OCI relay operating	129, 225	1	1
		BO5	A4-B4	20C, 20Cl	2OC or 2OCI relay operating	140, 226	1	1
		BO6	A5-B5	1REF, 1EF, 1EFI	1REF, 1EF or 1EFI relay operating	173, 174, 73	1	1
		BO7	A6-B6	2REF, 2EF, 2EFI	2REF, 2EF or 2EFI relay operating	190, 191, 76	1	1
		BO8	A7-B7	FRQ	FRQ relay operating	230	1	1
		BO9	A8-B8	V/F	V/F-L, H relay operating	229	1	1
		BO10	A9-B9	V/F-A	V/F-A relay operating	242	1	1
		BO11	A10-B10	THR	THR-L, H relay operating	83	1	1
		BO12	A11-B11	THR-A	THR-A relay operating	248	1	1
		BO13	A13-B13	M. TRIP-OR	Mechanical relay trip	1, 2, 3, 4	1	1
GRT100			TB3:					
-102	IO2	BO1	A2-A1	TRIP-1	TRIP First	284	1	1
		BO2	A2-B1	TRIP-2	TRIP Second	291	1	1
		BO3	A2-B2	DIFT	DIFT relay operating	224	1	1
		BO4	A3-B3	10C, 10Cl	1OC or 1OCI relay operating	129, 225	1	1
		BO5	A4-B4	2OC, 2OCI	2OC or 2OCI relay operating	140, 226	1	1
		BO6	A5-B5	1REF	1REF relay operating	173	1	1
		BO7	A6-B6	2REF	2REF relay operating	190	1	1
		BO8	A7-B7	1EF, 1EFI	1EF or 1EFI relay operating	174, 73	1	1
		BO9	A8-B8	2EF, 2EFI	2EF or 2EFI relay operating	191, 76	1	1
		BO10	A9-B9	FRQ	FRQ relay operating	230	1	1
		BO11	A10-B10	V/F-T	V/F-T relay operating	81	1	1
		BO12	A11-B11	V/F-H	V/F-H relay operating	235	1	1
		BO13	A13-B13	V/F-A	V/F-A relay operating	242	1	1
			TB2:					
	IO3	BO1	A2-A1	THR	THR-L, H relay operating	83	1	1
		BO2	A2-B1	THR-A	THR-A relay operating	248	1	1
	1	BO3	A2-B2	TRIP-1	TRIP First	284	1	1
		BO4	A3-B3	TRIP-2	TRIP Second	291	1	1
	1	BO5	A4-B4	TRIP-1	TRIP First	284	1	1
	1	BO6	A5-B5	TRIP-2	TRIP Second	291	1	1
		B07	A6-B6	MEC. TRIP-1	Mechanical relay trip 1	1	1	1
		BO8	A7-B7	MEC. TRIP-2	Mechanical relay trip 2	2	1	1
	1	ВО9	A8-B8	MEC. TRIP-3	Mechanical relay trip 3	3	1	1
		BO10	A9-B9	MEC. TRIP-4	Mechanical relay trip 4	4	1	1

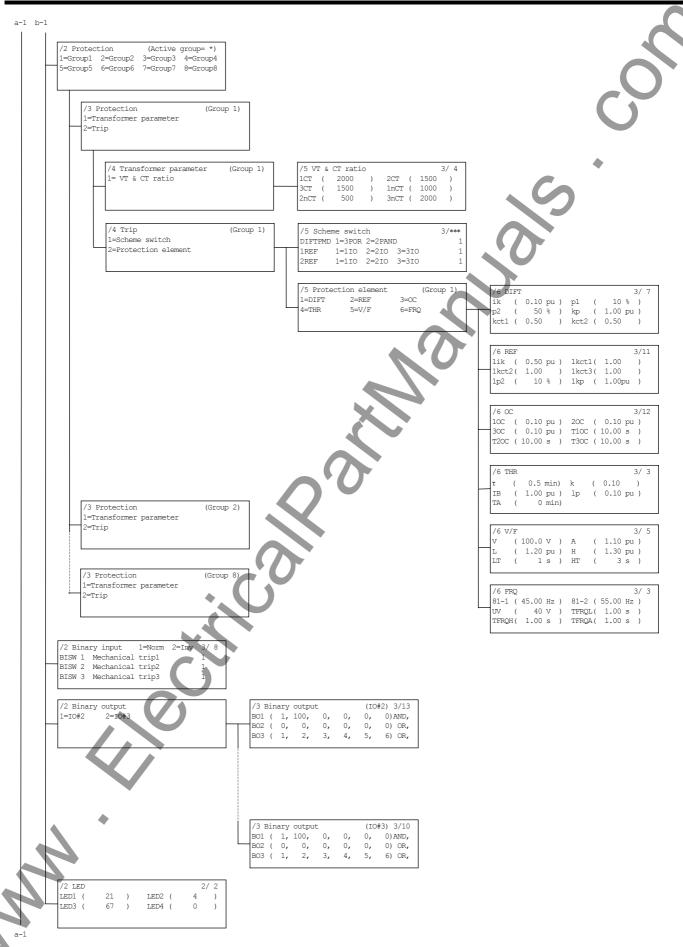
Model	Name	1		•				
			No.			Signal No.	Logic	Timer
							(OR: 1, AND:	(OFF: 0, ON: 1)
							2)	
GRT100			TB3:				•	
-201	IO2	BO1	A2-A1	TRIP-1	TRIP First	284	1	1
		BO2	A2-B1	TRIP-2	TRIP Second	291		1
		BO3	A2-B2	TRIP-3	TRIP Third	298	1	1
		BO4	A3-B3	DIFT	DIFT relay operating	224	1	1
		BO5	A4-B4	10C, 10Cl, 1REF, 1EF,	1OC, 1OCI, 1REF, 1EF or 1EFI relay	129, 225, 173, 174,	1	1
				1EFI	operating	73		
		BO6	A5-B5	20C, 20Cl, 2REF, 2EF,	2OC, 2OCI, 2REF, 2EF or 2EFI relay	140, 226, 190, 191,	1	1
				2EFI	operating	76		
		BO7	A6-B6	3OC, 3OCI, 3REF, 3EF,	3OC, 3OCI, 3REF, 3EF or 3EFI relay	151, 227, 207, 208,	1	1
				3EFI	operating	79		
		BO8	A7-B7	FRQ	FRQ relay operating	230	1	1
		BO9	A8-B8	V/F	V/F-L, H relay operating	229	1	1
		BO10	A9-B9	V/F-A	V/F-A relay operating	242	1	1
		BO11	A10-B10	THR	THR-L, H relay operating	83	1	1
		BO12	A11-B11	THR-A	THR-A relay operating	248	1	1
		BO13	A13-B13	M. TRIP-OR	Mechanical relay trip	1, 2, 3, 4	1	1
GRT100			TB3:					
-202	102	BO1	A2-A1	TRIP-1	TRIP First	284	1	1
		BO2	A2-B1	TRIP-2	TRIP Second	291	1	1
		BO3	A2-B2	TRIP-3	TRIP Third	298	1	1
		BO4	A3-B3	DIFT	DIFT relay operating	224	1	1
		BO5	A4-B4	10C, 10Cl	10C or 10Cl relay operating	129, 225	1	1
		BO6	A5-B5	2OC, 2OCI	2OC or 2OCI relay operating	140, 226	1	1
		BO7	A6-B6	3OC, 3OCI	3OC or 3OCI relay operating	151, 227	1	1
		BO8	A7-B7	1REF	1REF relay operating	173	1	1
		BO9	A8-B8	2REF	2REF relay operating	190	1	1
		BO10	A9-B9	3REF	3REF relay operating	207	1	1
		BO11	A10-B10	1EF, 1EFI	1EF or 1EFI relay operating	174, 73	1	1
		BO12	A11-B11	2EF, 2EFI	2EF or 2EFI relay operating	191, 76	1	1
		BO13	A13-B13	3EF, 2EFI	3EF or 3EFI relay operating	208, 79	1	1
•			TB2:					
	103	BO1	A2-A1	FRQ	FRQ relay operating	230	1	1
	100	BO2	A2-B1	V/F-T	V/F-T relay operating	81	1	1
		BO2 BO3	A2-B1 A2-B2	V/F-H	V/F-H relay operating	235	1	1
		BO4	A3-B3	V/F-A	V/F-A relay operating	242	1	1
		BO4 BO5	A3-B3 A4-B4	THR	THR-L, H relay operating	83	1	1
		BO5 BO6	A5-B5	THR-A	THR-L, H relay operating THR-A relay operating	248	1	1
		BO7	A5-B5 A6-B6	MEC. TRIP-1	Mechanical relay trip 1	2 4 6 1	1	1
					- '	2	1	1
		BO8 BO9	A7-B7 A8-B8	MEC. TRIP-2 MEC. TRIP-3	Mechanical relay trip 2 Mechanical relay trip 3	3	1	1
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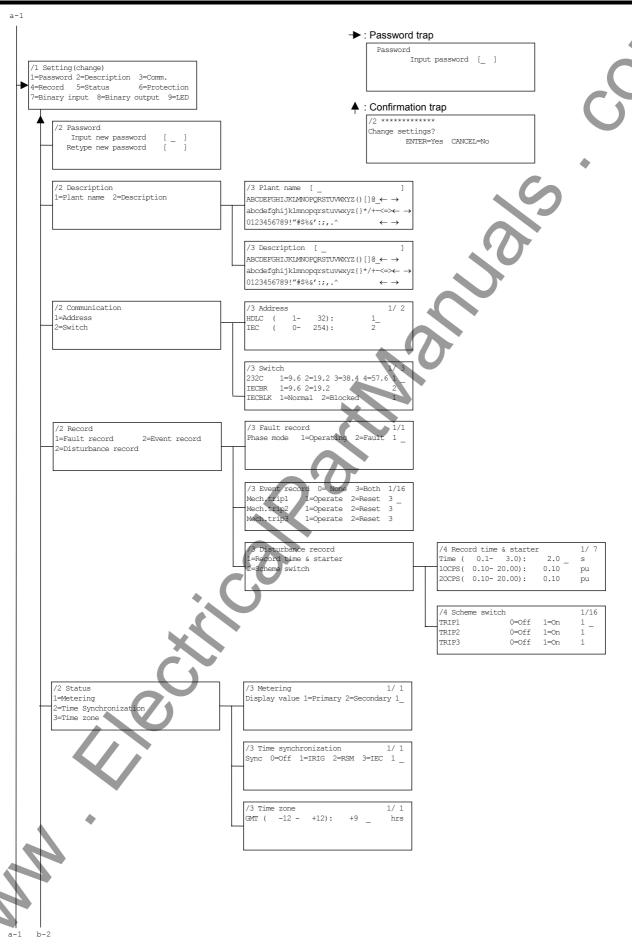
Appendix E

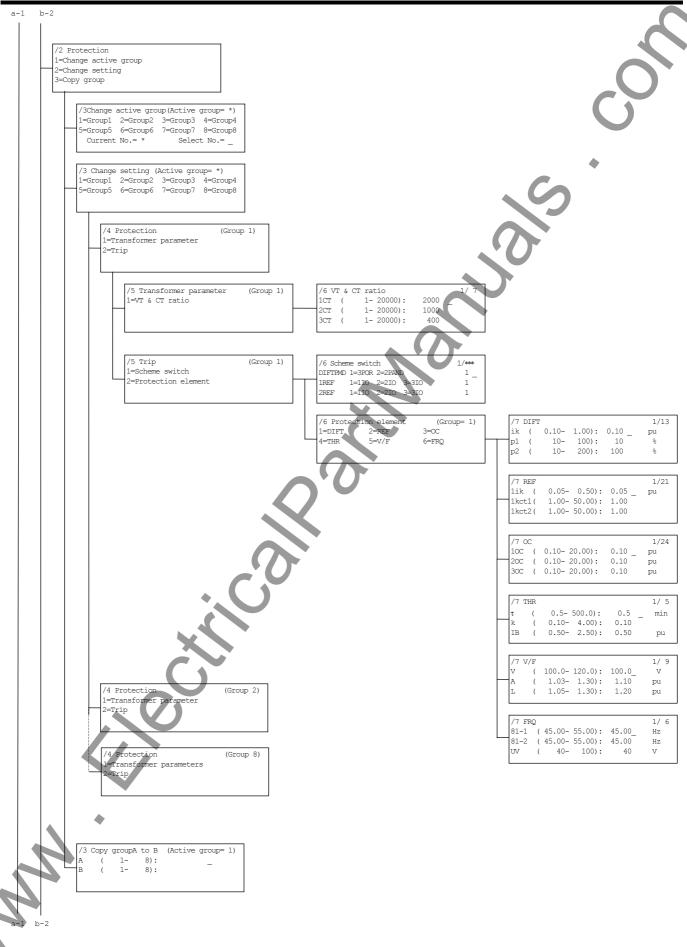
Details of Relay Menu and LCD and Button Operation

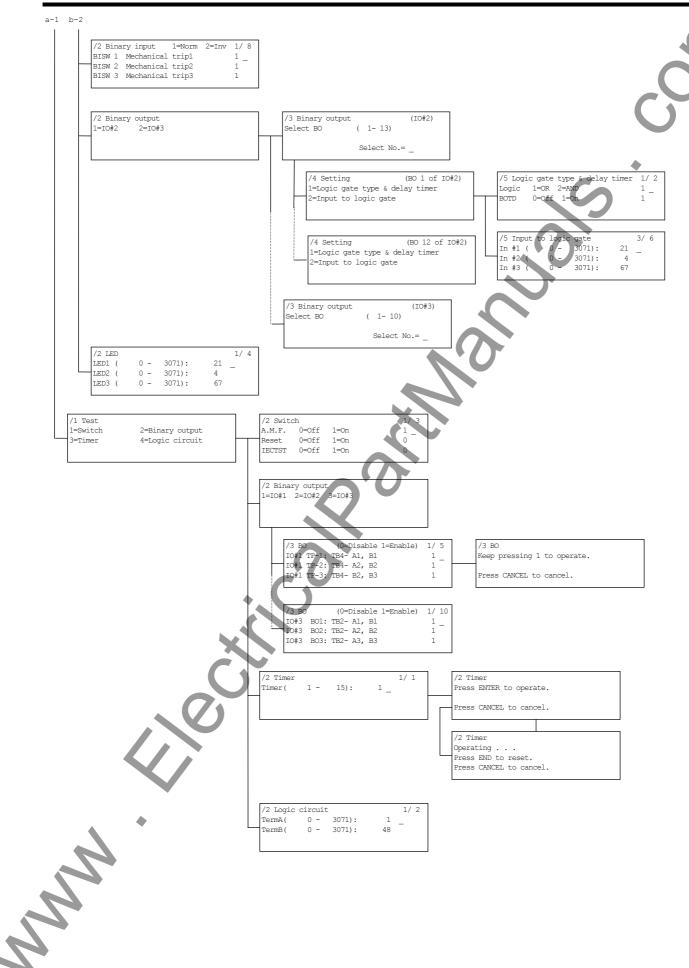










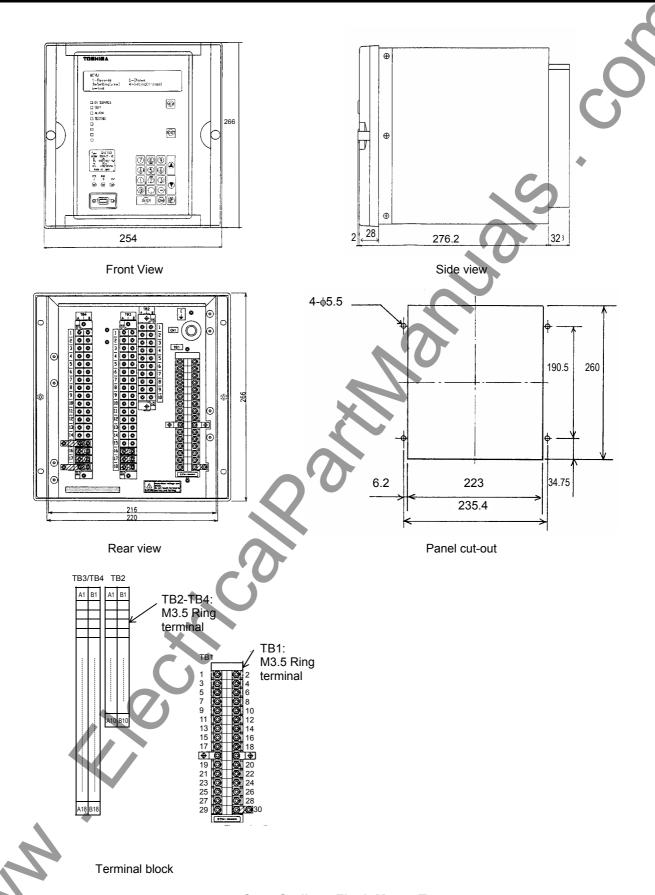


LCD AND BUTTON OPERATION INSTRUCTION **MANUAL MODE** 1. PRESS ARROW KEY TO MOVE TO EACH DISPLAYED ITEMS NORMAL 2. PRESS "END" KEY TO BACK TO PREVIOUS SCREEN (DISPLAY OFF) 1=RECORD PRESS ANY BUTTON EXCEPT FOR "VIEW" AND "RESET" MENU - ► 1=FAULT RECORD VIEW (DISPLAY ON) - →2=EVENT RECORD - →3=DISTURBANCE RECORD =METERING 1 (DISPLAY ON) 2=STATUS RESET VIEW - - ► 1=METERING ▶2=BINARY INPUT&OUTPUT AUTO-→3=RELAY ELELMENT **METERING 2** (DISPLAY ON) MODE 1 4=TIME SYNC SOURCE TRIP OUTPUT ISSUED! ►5=CLOCK ADJUSTMENT VIEW RESET 3=SETTING (VIEW) TRIP (LED ON) - ▶1=RELAY VERSION - ►2=DESCRIPTION LATEST FAULT * **AUTO-**(DISPLAY ON) - →3=RSM COMMUNICATION MODE 2 - →4=RECORD RELAY FAILED! - →5=STATUS VIEW RESET ALARM - ▶6=PROTECTION (LED ON) - →7=BINARY INPUT - ▶8=BINARY OUTPUT AUTO SUPERVISON * - **→**9=LED (DISPLAY ON) *. "LATEST FAULT" AND "AUTO SUPERVISION" SCREEN IS DISPLAYED ONLY IF DATA IS STORED 4=SETTING (CHANGE) Same as SETTING (VIEW) menu 5=TEST - ▶ 1=SWITCH - ▶2=BINARY OUTPUT - **→**3=TIMER - - →4=LOGIC CIRCUIT

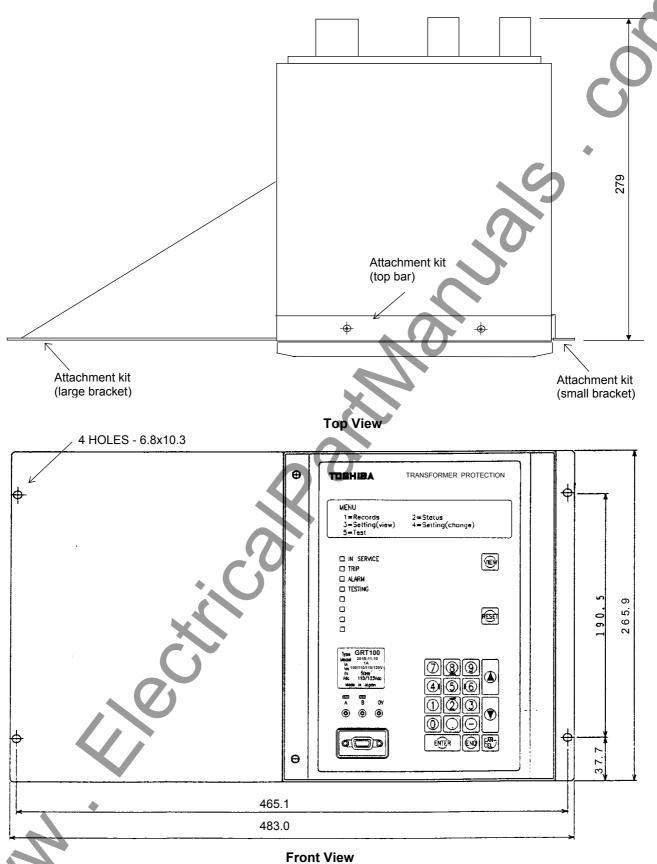
Appendix F

Case Outline

- Flush Mount Type
- Rack Mount Type

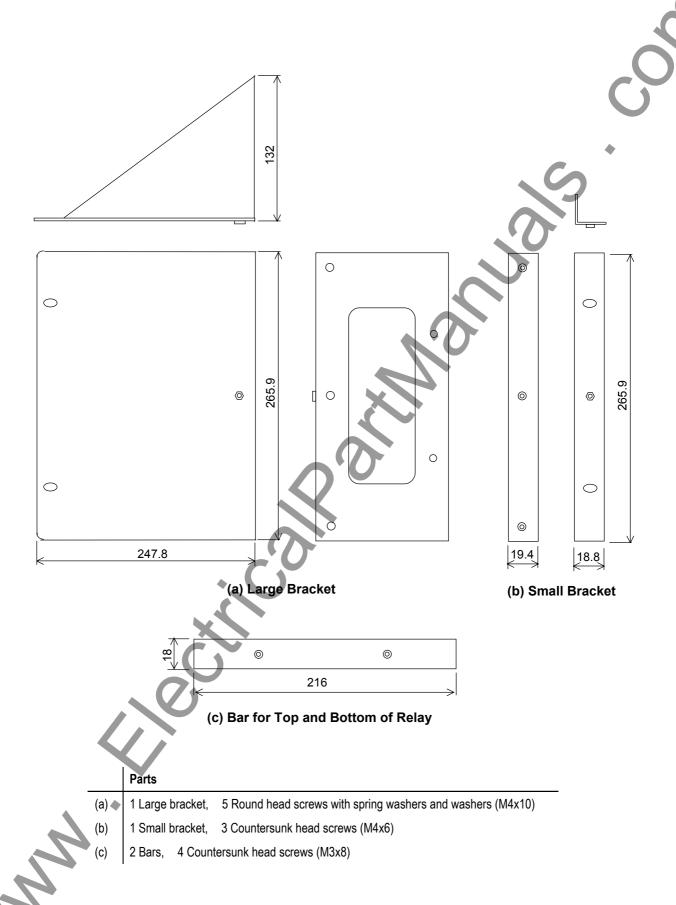


Case Outline: Flush Mount Type



Case Outline: Rack Mount Type

TOSHIBA

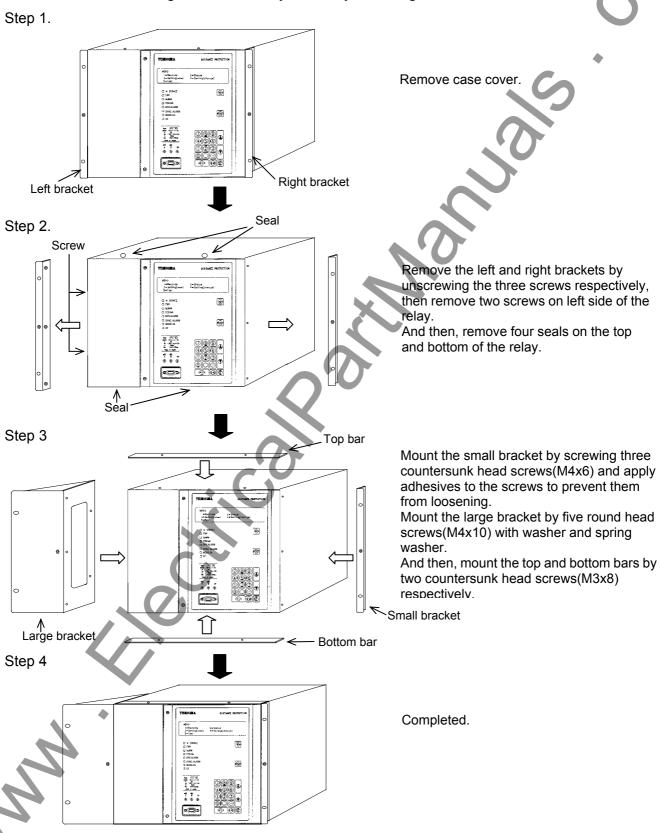


Dimensions of Attachment Kit EP-101

How to Mount Attachment Kit for Rack-Mounting

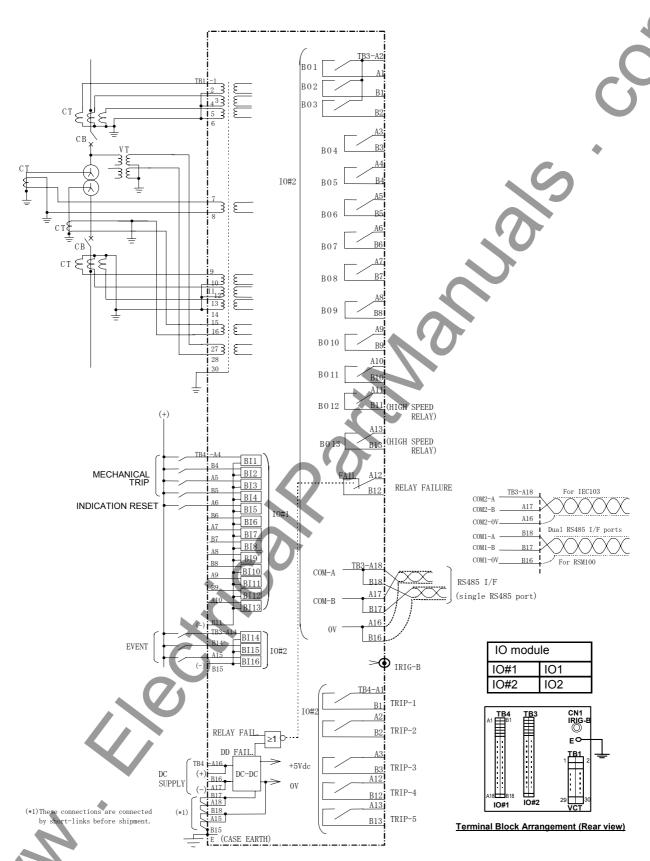
Caution: Be careful that the relay modules or terminal blocks, etc., are not damage while mounting.

Tighten screws to the specified torque according to the size of screw.



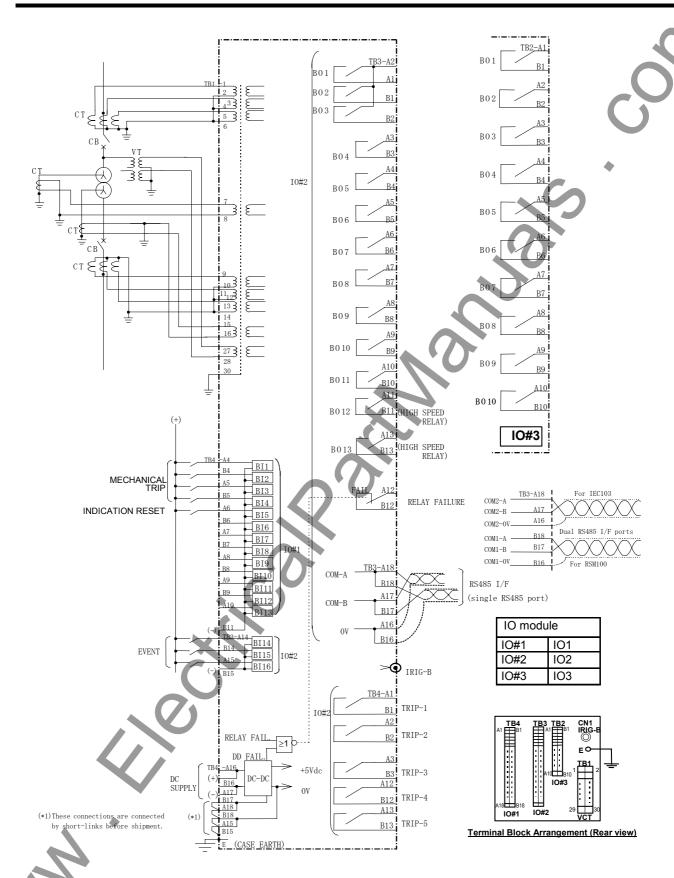
Appendix G

External Connections

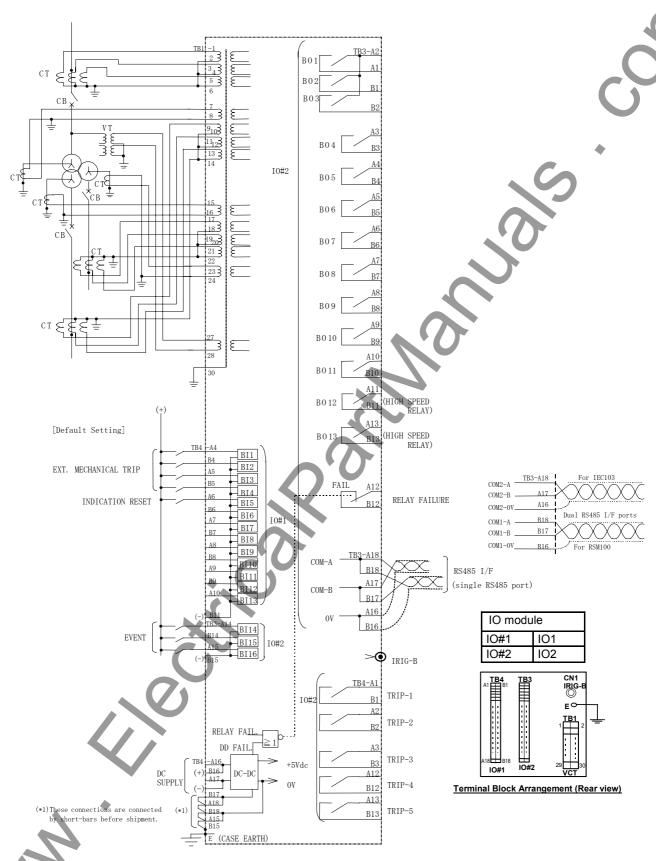


Typical External Connection of Model 101

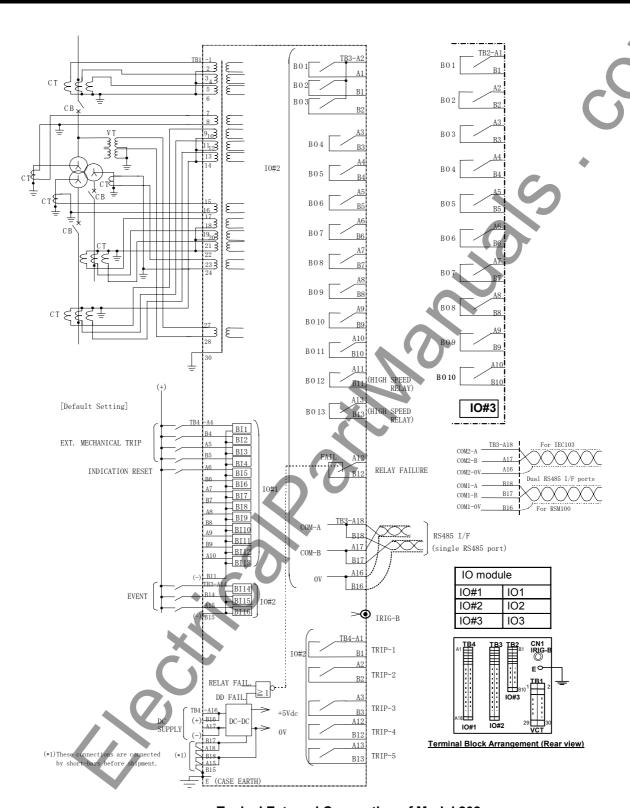
TOSHIBA



Typical External Connection of Model 102



Typical External Connection of Model 201



Typical External Connection of Model 202

Appendix H

Relay Setting Sheet

- 1. Relay Identification
- 2. Contacts Setting
- 3. Relay and Protection Scheme Setting Sheet

Relay Setting Sheets

1.	Relay Identification			Date:
	Relay type		Serial Number	
	Frequency		CT rating	
	VT rating		dc supply voltage	
	Password		_	
	Active setting group		_	5
2.	Contacts Setting			
	(1) IO#2 BO1			
	BO2			
	BO3			
	BO4			
	BO5			
	BO6		No	
	BO7			
	BO8			
	BO9			
	BO10			
	BO11			
	BO12		, –	
	BO13			
	(2) IO#3 BO1		*	
	BO2			
	BO3	. (+		
	BO4			
	BO5			
	BO6	<u> </u>		
	BO7)		
	BO8			
	В09			
	BO10			

3. Relay and Protection Scheme Setting Sheet

		Standard			Default Setting of Rela	y Series (50Hz / 60Hz)	
Nº	Name	Range	Units	Contents	2-Winding	3-Winding	User Setting
		50Hz 60Hz			101 102	201 202	
1	Active group	1 - 8	_	Active setting group	1		
2	1CT	1 - 20000	_	CT ratio	200		
3	2CT	1 - 20000	_	ditto	200		
4	3CT	1 - 20000	_	ditto		2000	
5	1nCT	1 - 20000	_	ditto	200		
6	2nCT	1 - 20000	-	ditto	40		-
7	3nCT	1 - 20000	_	ditto		400	*
8	VT	1 - 20000	_	VT ratio	40		
9	DIFTPMD	3POR - 2PAND	_	DIF trip mode	3P(JR .	
10	1REF	110 - 210	_	Transformer type for REF	110	410	
11	2REF	110 - 210 - 310 110 - 210	_	ditto	 1I0	110	
	ZNEF	110 - 210		ditto		110	
12	3REF	110 - 210 - 310	_	ditto		110	
13	M1OCI	Long - Std - Very - Ext	_	OCI back-up trip	St		
14	M2OCI	Long - Std - Very - Ext	_	ditto	St		
15	M3OCI	Long - Std - Very - Ext	_	ditto	- 🔺	Std	
16	M1EFI	Long - Std - Very - Ext	_	EFI back-up trip	St		
17	M2EFI	Long - Std - Very - Ext	_	ditto	St		
18	M3EFI	Long - Std - Very - Ext	_	ditto	0.	Std	
19	L/O	Off - On	_	Trip signal lock out	O		
20	2F-LOCK	Off - On	_	2F restraint	0		
21	5f-LOCK	Off - On	_	5F restraint	0		
22	DIF1	Off - On	_	Current differential trip	0		
23	DIF2	Off - On	_	ditto	0		
24	DIF3	Off - On	_	ditto	Off	On	
25	DIF4	Off - On	_	ditto	Of		
26	DIF5	Off - On	_	ditto	Of	f	
27	1REF1	Off - On	_	Restricted earth fault trip	0		
28	1REF2	Off - On	_	ditto	0	n	
29	1REF3	Off - On	_	ditto	0	n	
30	1REF4	Off - On	_	ditto	Of	f	
31	1REF5	Off - On	_	ditto	Of	f	
32	1001	Off - On	_	OC trip	0	n	
33	10C2	Off - On	_	ditto	Of	f	
34	10C3	Off - On	_	ditto	Of	ff	
35	10C4	Off - On	_	ditto	Ot	ff	
36	1OC5	Off - On	_	ditto	Ot	ff	
37	10CI1	Off - On	_	OCI trip	0	n	
38	10CI2	Off - On	_	ditto	Of		
39	10CI3	Off - On	_	ditto	01	ff	
40	10CI4	Off - On	_	ditto	Ot		
41	10CI5	Off - On	_	ditto	Of		
42	1EF1	Off - On	- /	EF trip	0		
43	1EF2	Off - On	- 1	ditto	Ot		
44	1EF3	Off - On		ditto	Ot		
45	1EF4	Off - On	_	ditto	01		
46	1EF5	Off - On	_	ditto	01		
47	1EFI1	Off - On		EFI trip	0		
48	1EFI2	Off - On		ditto	01		
49	1EFI3	Off On	7	ditto	01		
50	1EFI4	Off - On	_	ditto	01		
51	1EFI5	Off - On Off - On		ditto	01		
52	2REF1		_	Restricted earth fault trip	0		
53 54	2REF2 2REF3	Off - On Off - On	_	ditto ditto	0		
55	2REF3	Off - On	_	ditto	Of		
56	2REF5	Off - On	_	ditto	Of		
57	20C1	Off - On	_	OC trip	Of		
58	2002	Off - On	_	ditto	0		
59	20C2 20C3	Off - On	_	ditto	Of		
60	20C4	Off - On	_	ditto	Of		
61	20C5	Off - On	_	ditto	Of		
62	20CI1	Off - On	_	OCI trip	Of		
63	20CI2	Off - On	_	ditto	0		
64	20CI2 20CI3	Off - On	_	ditto	Of		
65	20CI3	Off - On	_	ditto	Of		
66	20CI4 20CI5	Off - On	_	ditto	Of		
67	2EF1	Off - On	_	EF trip	Of		
68	2EF2	Off - On	_	ditto	0		
69	2EF3	Off - On	_	ditto	Of		
70	2EF4	Off - On	_	ditto	Of		
71	2EF5	Off - On	_	ditto	Of		
					Ŭ.		

			Standard			Default Setting of Rela	v Series (50Hz / 60Hz)	
2 2 2 2 2 1 1 1 1 1	Nο	Name		Units	Contents			User Setting
72 REFIT OFF On Eft trop OFF 73 REFIE OFF On distrop On 74 REFIS OFF On distrop OFF 75 REFIS OFF On distrop OFF 76 REFIS OFF On distrop OFF 77 REFIS OFF On distrop On 78 REFIS OFF On distrop On 80 REFIS OFF On distrop On 81 REFIS OFF On distrop OFF 82 REFIS OFF On distrop OFF 83 REFIS OFF On distrop OFF 84 REFIS OFF On DISTRIPT OFF ON 85 REFIS OFF ON DISTRIPT OFF ON 86 ROCK OFF ON DISTRIPT OFF ON 86 ROCK OFF ON DISTRIPT OFF ON 87 REFIS OFF ON DISTRIPT OFF ON 88 ROCK OFF ON DISTRIPT OFF ON 88 ROCK OFF ON DISTRIPT OFF ON 89 ROCK OFF ON DISTRIPT OFF ON 80 ROCK OFF ON OFF ON OFF ON 80 ROCK OFF ON OFF		Hame		Office	Contents			ouch octains
73	72	2FFI1		_	FFI trin			
74				_				
Tell				_				
78				_				
77	_							_
78 SREF2 OFF-On — date — On On — Part of SREF3 OFF-On — date — On On — On — On — On — On — On — On								
78 3REF3 Off - On								
88 387EF4 Off - On								
SI SREF OFF - ON								
BE 30C Off On - OC file - Off								
88 30C2								
84 30C3	_							
See SOC-4				_				
Section Sect								
87 30CIT	_			_				
88 8 30Ci2	86		Off - On	_	ditto	-		
88 30,C13	87	3OCI1	Off - On	_	OCI trip		Off	
90 30CL4	88	3OCI2	Off - On	-	ditto	1	Off	
91 SOCIS 20 3EF1 Off - On	89	3OCI3	Off - On	-	ditto	-	On	
SEFT Off-On — EF trip — Off	90	3OCI4	Off - On	_	ditto	-	Off	
SEF1				-		- 🔺	Off	
SEF2				_		-		
94 SEF3 Off-On — ditto — ditto — On Off 95 SEF5 Off-On — ditto — Off 97 3EF1 Off-On — ditto — Off 98 3EF1 Off-On — ditto — Off 99 3EF12 Off-On — ditto — Off 99 3EF13 Off-On — ditto — Off 99 3EF13 Off-On — ditto — Off 99 3EF14 Off-On — ditto — Of				_				
98				_)	
SEF5						4 7		
SEFI1	_							
SEF12								
SEFI3								
OB 3EFI4								
SEPIS								
102 FRQ-UF1						-		
103								
FRQ1	_							
05 FRQ2 Off-On — ditto On 06 FRQ3 Off-On — ditto Off I On 07 FRQ4 Off-On — ditto Off Off Off 08 FRQA Off-On — ditto On Off On Off 10 VF1 Off-On — ditto On								
OE FRQ3 Off-On — ditto Off I On 07 FRQ4 Off-On — ditto Off Off 08 FRQ5 Off-On — ditto Off Off 09 FRQA Off-On — ditto On Off 10 V/F1 Off-On — ditto On On 11 V/F2 Off-On — ditto On On 12 V/F3 Off-On — ditto Off On 13 V/F4 Off-On — ditto Off Off 14 V/F5 Off-On — ditto Off Off 14 V/F5 Off-On — ditto On Off 15 V/FA Off-On — ditto On Off 16 THR1 Off-On — ditto On Off 19 THR2 Off-On — ditto Off Off 20 THR5 Off-On								
OFF	_							
OB			Off - On	_	ditto	Off	On	
OFFICIAL		FRQ4	Off - On	_	ditto			
OFF	80	FRQ5	Off - On	_	ditto	0	off	
11	09	FRQA	Off - On	ı	ditto	0)n	
12	10	V/F1	Off - On	_	V/F trip	0)n	
13	11	V/F2	Off - On	_	ditto	0)n	
14 V/F5	12	V/F3	Off - On	_	ditto	Off	On	
15	13	V/F4	Off - On	_	ditto	0)ff	
THR1	14	V/F5	Off - On	- '	ditto	0	off	
THR1	15	V/FA	Off - On	_	ditto	0)n	
THR2	_	THR1	Off - On	- 4	THR trip	0)n	
THR3				-/				
THR4				4				
THR5				_				
THRA								
M.T1-1								
M.T1-2								
24 M.T1-3 Off - On — ditto Off On 25 M.T1-4 Off - On — ditto Off 26 M.T1-5 Off - On — ditto Off 27 M.T2-1 Off - On — Mechanical trip2 On 28 M.T2-2 Off - On — ditto On 29 M.T2-3 Off - On — ditto Off 30 M.T2-4 Off - On — ditto Off 31 M.T2-5 Off - On — ditto Off 32 M.T3-1 Off - On — ditto On 33 M.T3-2 Off - On — ditto On 34 M.T3-3 Off - On — ditto Off 36 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto On 38 M.T4-2 Off - On — ditto Off 39 M.T4-3 Off - On — ditto Off				-	·			
25 M.T1-4 Off - On — ditto Off 26 M.T1-5 Off - On — ditto Off 27 M.T2-1 Off - On — Mechanical trip2 On 28 M.T2-2 Off - On — ditto On 29 M.T2-3 Off - On — ditto Off 30 M.T2-4 Off - On — ditto Off 31 M.T2-5 Off - On — ditto Off 32 M.T3-1 Off - On — ditto On 34 M.T3-2 Off - On — ditto On 34 M.T3-3 Off - On — ditto Off 35 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — ditto On 38 M.T4-2 Off - On — ditto Off 40 M.T4-4 Off - On — ditto Off								
26 M.T1-5 Off - On — ditto Off 27 M.T2-1 Off - On — Mechanical trip2 On 28 M.T2-2 Off - On — ditto On 29 M.T2-3 Off - On — ditto Off 30 M.T2-4 Off - On — ditto Off 31 M.T2-5 Off - On — ditto Off 32 M.T3-1 Off - On — Mechanical trip3 On 33 M.T3-2 Off - On — ditto On 34 M.T3-3 Off - On — ditto Off 35 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — ditto On 38 M.T4-2 Off - On — ditto Off 39 M.T4-3 Off - On — ditto Off 40 M.T4-4 Off - On — ditto Off				_				
27 M.T2-1 Off - On — Mechanical trip2 On 28 M.T2-2 Off - On — ditto On 29 M.T2-3 Off - On — ditto Off 30 M.T2-4 Off - On — ditto Off 31 M.T2-5 Off - On — ditto Off 32 M.T3-1 Off - On — Mechanical trip3 On 33 M.T3-2 Off - On — ditto On 34 M.T3-3 Off - On — ditto Off 35 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — Mechanical trip4 On 38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off								
28 M.T2-2 Off - On — ditto On 29 M.T2-3 Off - On — ditto Off — On 30 M.T2-4 Off - On — ditto Off 31 M.T2-5 Off - On — ditto Off 32 M.T3-1 Off - On — Mechanical trip3 On 33 M.T3-2 Off - On — ditto On 34 M.T3-3 Off - On — ditto Off 35 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — Mechanical trip4 On 38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off								
29 M.T2-3 Off - On — ditto Off On 30 M.T2-4 Off - On — ditto Off 31 M.T2-5 Off - On — ditto Off 32 M.T3-1 Off - On — Mechanical trip3 On 33 M.T3-2 Off - On — ditto On 34 M.T3-3 Off - On — ditto Off On 35 M.T3-4 Off - On — ditto Off Off 36 M.T3-5 Off - On — ditto Off On 37 M.T4-1 Off - On — Mechanical trip4 On On 38 M.T4-2 Off - On — ditto On On 39 M.T4-3 Off - On — ditto Off Off 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off								
M.T2-4								
M.T2-5								
32 M.T3-1 Off - On — Mechanical trip3 On 33 M.T3-2 Off - On — ditto On 34 M.T3-3 Off - On — ditto Off 35 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — Mechanical trip4 On 38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off								
33 M.T3-2 Off - On — ditto On 34 M.T3-3 Off - On — ditto Off — On 35 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — Mechanical trip4 On 38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off On 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off								
34 M.T3-3 Off - On — ditto Off On 35 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — Mechanical trip4 On 38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off On 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off								
35 M.T3-4 Off - On — ditto Off 36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — Mechanical trip4 On 38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off Image: On 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off								
36 M.T3-5 Off - On — ditto Off 37 M.T4-1 Off - On — Mechanical trip4 On 38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off Inch on 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off								
37 M.T4-1 Off - On — Mechanical trip4 On 38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off On 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off		M.T3-4			ditto			
38 M.T4-2 Off - On — ditto On 39 M.T4-3 Off - On — ditto Off On 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off	36	M.T3-5	Off - On	_	ditto	0)ff	
39 M.T4-3 Off - On — ditto Off On 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off	37	M.T4-1	Off - On	L-	Mechanical trip4	0)n	
39 M.T4-3 Off - On — ditto Off On 40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off	38	M.T4-2	Off - On	_	ditto	0)n	
40 M.T4-4 Off - On — ditto Off 41 M.T4-5 Off - On — ditto Off				_				
41 M.T4-5 Off - On — ditto Off				_				
				-				

			Standard	_		Default Setting of	Delay	Sarias (50Hz / 60Hz)	
Nº	Na	me	Range	Units	Contents	2-Winding	Relay .		Vinding	User Setting
			50Hz 60Hz			101 102		201	202	
143	DIFT	ik	0.10 - 1.00	pu	Minimum operating current		0.30			
144		p1	10 - 100	%	% slope of small current region		100			
145		p2	10 - 200	%	% slope of large current region		200			
146		kp ket1	1.00 - 20.00	pu	Break point of DIF characteristic		1.00			
147 148		kct1 kct2	0.05 - 50.00 0.05 - 50.00	_	CT ratio ditto		1.00			
149		kct3	0.05 - 50.00	\vdash	ditto		1.00		1.00	
150		d1	0 - 11	_	Phase angle		0		1.00	
151		d2	0 - 11	_	ditto		0			
152		d3	0 - 11	_	ditto				0	
153		k2f	10 - 50	%	2f restraint		15			·
154		k5f	10 - 100	%	5f restraint		30			
155	DEE	kh	2.00 - 20.00	pu	HOC operaing current		2.00			
156 157	REF	1ik	0.05 - 0.50 1.00 - 50.00	pu	Minimum sensitivity for 1REF		0.50 1.00	_		
158		1kct1 1kct2	1.00 - 50.00	-	CT ratio for 1REF ditto		1.00			
159		1kct3	1.00 - 50.00	_	ditto		1.00		1.00	
160		1p2	50 - 100	%	Percent slope for 1REF		100		100	
161		1kp	0.50 - 2.00	pu	DF2 sensitivity		1.00			
162		2ik	0.05 - 0.50	pu	Minimum sensitivity for 2REF		0.50			
163		2kct1	1.00 - 50.00	_	CT ratio for 2REF		1.00	P		
164		2kct2	1.00 - 50.00	_	ditto		1.00			
165		2kct3	1.00 - 50.00	_	ditto				1.00	
166		2p2	50 - 100	%	Percent slope for 2REF		100			
167		2kp	0.50 - 2.00	pu	DF2 sensitivity		1.00			
168		3ik	0.05 - 0.50	pu	Minimum sensitivity for 3REF		>		0.50	
169		3kct1	1.00 - 50.00	_	CT ratio for 3REF				1,00	
170		3kct2	1.00 - 50.00	_	ditto		_		1,00	
171 172		3kct3 3p2	1.00 - 50.00 50 - 100	— %	ditto Percent slope for 3REF				1.00	
173		3kp	0.50 - 2.00	pu	DF2 sensitivity				1.00	
174		T1REF	0.00 - 10.00	S	1REF delay trip timer		0.00		1.00	
175		T2REF	0.00 - 10.00	s	2REF delay trip timer		0.00			
176		T3REF	0.00 - 10.00	s	3REF delay trip timer				0.00	
177	OC	10C	0.10 - 20.00	pu	OC element		2.00			
178		20C	0.10 - 20.00	pu	ditto		2.00			
179		3OC	0.10 - 20.00	pu	ditto				2.00	
180		T1OC	0.00 - 10.00	S	OC delay trip timer		1.00			
181		T2OC	0.00 - 10.00	S	ditto		1.00			
182		T3OC	0.00 - 10.00	S	ditto		1 00		1.00	
183		10CI	0.10 - 5.00	pu	OCI element		1.00			
184		2OCI 3OCI	0.10 - 5.00 0.10 - 5.00	pu	ditto		1.00		1.00	
185 186		T10CI	0.10 - 3.00	pu —	OCI delayed tripping timer		1.00		1.00	
187		T2OCI	0.05 - 1.00	_	ditto		1.00			
188		T3OCI	0.05 - 1.00	_	ditto		1		1.00	
189		1EF	0.10 - 20.00	pu	EF element		2.00			
190		2EF	0.10 - 20.00	pu	ditto		2.00			
191		3EF	0.10 - 20.00	pų	ditto				2.00	
192		T1EF	0.00 - 10.00	s	EF delay trip timer		1.00			
193		T2EF	0.00 - 10.00	S	ditto		1.00			
194		T3EF	0.00 - 10.00	S	ditto				1.00	
195		1EFI	0.10 - 5.00		EFI element		1.00			
196 197		2EFI	0.10 - 5.00	pu	ditto		1.00		4.00	
197		3EFI	0.10 - 5.00	pu	dittp		1.00		1.00	
198 199		T1EFI T2EFI	0.05 - 1.00 0.05 - 1.00		EFI delayed tripping timer ditto		1.00			
			0.03 - 1.00			_	1.00		1.00	
			0.05 - 1.00	_						
200	THR	T3EFI	0.05 - 1.00 0.5 - 500.0	— min	ditto Time constant		60 O		1.00	
200 201	THR	T3EFI t	0.05 - 1.00 0.5 - 500.0 0.10 - 4.00	min	Time constant Constant		60.0		1.00	
200	THR	T3EFI	0.5 - 500.0	min	Time constant		60.0 1.30 1.00		1.00	
200 201 202	THR	T3EFI t k	0.5 - 500.0 0.10 - 4.00	min —	Time constant Constant		1.30		1.00	
200 201 202 203	THR	T3EFI t k IB	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50	min — pu	Time constant Constant Basic current		1.30 1.00		1.00	
200 201 202 203 204 205 206	THR V/F	t k IB Ip TA	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50 0.00 - 1.00 0 - 10	min — pu pu	Time constant Constant Basic current Pre-load current		1.30 1.00 0.00		1.00	
200 201 202 203 204 205 206 207		t k IB Ip TA V A	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50 0.00 - 1.00 0 - 10 100.0 - 120.0 1.03 - 1.30	min — pu pu min	Time constant Constant Basic current Pre-load current Time for alarming Voltage Alarm level		1.30 1.00 0.00 10 100.0 1.03)	1100	
200 201 202 203 204 205 206 207		t k IB Ip TA V A L	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50 0.00 - 1.00 0 - 10 100.0 - 120.0 1.03 - 1.30 1.05 - 1.30	min pu pu min V pu pu	Time constant Constant Basic current Pre-load current Time for alarming Voltage Alarm level Low level		1.30 1.00 0.00 10 100.0 1.03		1100	
200 201 202 203 204 205 206 207 208 209		T3EFI t k IB Ip TA V A L	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50 0.00 - 1.00 0 - 10 100.0 - 120.0 1.03 - 1.30 1.05 - 1.30 1.10 - 1.40	min pu pu min V pu pu pu	Time constant Constant Basic current Pre-load current Time for alarming Voltage Alarm level Low level High level		1.30 1.00 0.00 10 100.0 1.03 1.05	0	1100	
200 201 202 203 204 205 206 207		T3EFI t k IB Ip TA V A L H LT	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50 0.00 - 1.00 0 - 10 100.0 - 120.0 1.03 - 1.30 1.10 - 1.40 1 - 600	min pu pu min V pu pu pu pu pu s	Time constant Constant Basic current Pre-load current Time for alarming Voltage Alarm level Low level High level Inverce time delay for high level		1.30 1.00 0.00 10 100.0 1.03 1.05 1.40	0	1100	
200 201 202 203 204 205 206 207 208 209 210 211		t k IB Ip TA V A L H LT HT	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50 0.00 - 1.00 0 - 10 100.0 - 120.0 1.03 - 1.30 1.05 - 1.30 1.10 - 1.40 1 - 600 1 - 600	min pu pu min V pu pu pu pu s s	Time constant Constant Basic current Pre-load current Time for alarming Voltage Alarm level Low level High level Inverce time delay for high level Inverce time delay fir low level		1.30 1.00 0.00 10 100.0 1.03 1.05 1.40 600			
200 201 202 203 204 205 206 207 208 209		T3EFI t k IB Ip TA V A L H LT HT RT	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50 0.00 - 1.00 0 - 10 100.0 - 120.0 1.03 - 1.30 1.05 - 1.30 1.10 - 1.40 1 - 600 60 - 3600	min — pu pu min V pu pu pu pu s s s	Time constant Constant Basic current Pre-load current Time for alarming Voltage Alarm level Low level High level Inverce time delay for high level Inverce time delay fir low level Radiant heat time		1.30 1.00 0.00 10 100.0 1.03 1.05 1.40 600 1			
200 201 202 203 204 205 206 207 208 209 210 211		t k IB Ip TA V A L H LT HT	0.5 - 500.0 0.10 - 4.00 0.50 - 2.50 0.00 - 1.00 0 - 10 100.0 - 120.0 1.03 - 1.30 1.05 - 1.30 1.10 - 1.40 1 - 600 1 - 600	min pu pu min V pu pu pu pu s s	Time constant Constant Basic current Pre-load current Time for alarming Voltage Alarm level Low level High level Inverce time delay for high level Inverce time delay fir low level		1.30 1.00 0.00 10 100.0 1.03 1.05 1.40 600			

215 216 217 218	FRQ 81-1		ge	Units	Contents	2-Winding	3-Winding	User
216 217	-RU X1-1	50Hz 45.00 - 55.00	60Hz 54.00 - 66.00	L-1	Fraguency	101 102	201 202	
217	81-2	45.00 - 55.00 45.00 - 55.00	54.00 - 66.00	Hz Hz	Frequency ditto		7 / 59.00	
	UV	45.00 - 55.00					40	
	TFRQL	0.00 - 6		V S	Voltage TRIP delay timer for low level		0.0	
	TFRQL	0.00 - 6					0.0	
219 220	TFRQA	0.00 - 6		S	TRIP delay timer for high level		0.0	
				S	TRIP delay timer for alarm level			
221	BISW1	Norm -		_	Binary input		orm	
222	BISW2	Norm -		_	ditto		orm	
223	BISW3	Norm -		_	ditto		orm	
224	BISW4	Norm -		_	ditto		orm	4
225	BISW5	Norm -		_	ditto		orm	
226	BISW14	Norm -		_	ditto		orm	
227	BISW15	Norm -		_	ditto		orm	
228	BISW16	Norm -		_	ditto		orm	
229	LED1	O - 3		_	Configrable LEDs		0	
230	LED2	O - 3		_	ditto		0	
231	LED3	O - 3		_	ditto		0	
232	LED4	0 - 3	333	_	ditto		O V	
233	Plant name	Specified	by user	_	Plant name	Specifie	ed by user	
234	Description	ditto	0	-	Memorandum for user	Specifie	ed by user	
235	Address-HDLC	1 - 3	32	-	Relay ID No. for RSM		1 1	
236	Address-IEC	1 - 2	:54	_	Relay ID No. for IEC103		2	
237	232C	9.6 - 19.2 - 3		_	Comm. speed for RSM		9.6	
238	IECBR	9.6 - 1		_			9.2	
239	IECBLK	Normal -		_			ormal	
240	Phase mode	Operating		_	Phase indication of Fault recording		erating	_
241	Mech.trip1	None - Operating		_	Event record trigger		Both	
241	Mech.trip1	None - Operate -		_			Both	
					ditto			
243	Mech.trip3	None - Operate -		_	ditto		Both	
244	Mech.trip4	None - Operate -		-	ditto		Both	
245	Trip	None - Operate -		_	ditto		Both	
246	Ind.Reset	None - Operate -		_	ditto		Both	
247	Relay fail	None - Operate -	- Reset - Both	_	ditto	В	Both	
248	CT1 err	None - Operate -	- Reset - Both	_	ditto	В	Both	
249	CT2 err	None - Operate -	- Reset - Both	_	ditto	В	Both	
250	CT3 err	None - Operate -	- Reset - Both	_	ditto		Both	
251	Ev ent1	None - Operate -	- Reset - Both	_	ditto	В	Both	
201		None - Operate -	- Reset - Both	_	ditto	В	Both	
252	Ev ent2							
_			- Reset - Both	_	ditto	В	Both	
252 253	Ev ent3	None - Operate -		-	ditto ditto			
252	Event3 Sys. Set change	None - Operate - None - O	perate	-	ditto ditto ditto	Ор	erate	
252 253 254	Ev ent3	None - Operate -	perate perate		ditto	Op Op		
252 253 254 255	Ev ent3 Sys. Set change Rly. Set change	None - Operate - None - O None - O	Operate Operate Operate	_ _	ditto ditto	Op Op Op	perate perate	
252 253 254 255 256	Event3 Sys. Set change Rly. Set change Grp. Set change	None - Operate - None - O None - O None - O	Operate Operate Operate 3.0	_ _ _	ditto ditto ditto	Op Op Op	erate erate erate	
252 253 254 255 256 257	Event3 Sys. Set change Rly. Set change Grp. Set change Time	None - Operate - None - O None - O None - O	Operate Operate 3.0 20.00		ditto ditto ditto Disturbance record	Op Op Op	perate perate perate 1.0	
252 253 254 255 256 257 258	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS	None - Operate - None - O None - O None - O None - O O 1 - 0.10 - 2	Operate Operate 3.0 20.00		ditto ditto ditto Disturbance record OC element for disturbance	Op Op Op	perate perate perate 1.0 .00	
252 253 254 255 256 257 258 259	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS	None - Operate - None - O None - O None - O O - 10 - 2 0.10 - 2	Operate Operate Operate 3.0 20.00 20.00 20.00		ditto ditto ditto Disturbance record OC element for disturbance	Op Op Op 	erate erate erate 1.0 .00	
252 253 254 255 256 257 258 259 260 261	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG	None - Operate - None - O None - O None - O Onl - O	Operate Operate Operate 3.0 20.00 20.00 20.00 20.00	s pu pu pu	ditto ditto ditto Disturbance record OC element for disturbance	Op Op Op 1 1 	erate	
252 253 254 255 256 257 258 259 260 261 262	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG	None - Operate - None - O None - O None - O O 0.1 - 0.10 - 2 0.10 - 2 0.10 - 2 0.05 - 2	Operate Operate Operate 3.0 20.00 20.00 20.00 20.00 20.00	s pu pu pu pu	ditto ditto ditto Disturbance record OC element for disturbance	Op Op Op 1 1 	erate erate erate 1.0 .00 .00 .00 .00 .00 .00	
252 253 254 255 256 257 258 259 260 261 262	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG	None - Operate - None - O None - O None - O On - O	Operate Operate Operate 3.0 20.00 20.00 20.00 20.00 20.00 20.00 20.00 20.00	s pu pu pu	ditto ditto ditto Disturbance record OC element for disturbance recorder initiation	Op Op Op 1 1 1 	perate per	
252 253 254 255 256 257 258 259 260 261 262 263 264	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1	None - Operate - None - O None - O None - O None - O On -	Operate Operat	s pu pu pu pu pu pu	ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger	Op Op Op 1 1 	perate per	
252 253 254 255 256 257 258 259 260 261 262 263 264 265	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2	None - Operate - None - O None - O None - O None - O O.1 - O.10 - 2 O.10 - 2 O.10 - 2 O.05 - 2 O.05 - 2 O.05 - 2 Off - Off -	Operate Operat	s pu pu pu pu	ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger diffo	Op Op Op 	perate perate perate perate 1.0 .00 .00 1.00 .00 .00 1.00 .00 .00 1.00 0n 0n	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3	None - Operate - None - O None - O None - O On - O	Operate Operate Operate 3.0 20.00 20.00 20.00 20.00 20.00 20.00 00 00 00 00 00	s pu pu pu pu pu pu	ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto ditto	Op Op Op Op 	rerate rerate rerate rerate rerate resource rerate rerate resource resource resource resource resource rerate resource r	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4	None - Operate - None - O None - O None - O On - O	Operate Operate Operate Operate 03.0 20.00 20.00 20.00 20.00 20.00 00 00 00 00 00 00		ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto ditto ditto ditto	Op Op Op Op 	perate pe	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 30CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5	None - Operate - None - O None - O None - O None - O On -	Operate Operat	s pu pu pu pu pu	ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto ditto ditto ditto	Op Op Op Op 1 1 	perate perate perate perate perate 1.0 0.00 0.00 1.00 0.00 0.00 0.00 0.00	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269	Event3 Sys. Set change Riy. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP2 TRIP3 TRIP4 TRIP5 10CPS	None - Operate - None - O None - O None - O None - O On -	Operate Operat		ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger difto ditto ditto ditto ditto ditto	Op Op Op Op 1 1 	perate perate perate perate perate 1.0 .00 .00 .00 .00 .00 .00 .00 .00 .00	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269 270	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS	None - Operate - None - O None - O None - O On - O	Operate Operat	s pu pu pu pu pu	ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto ditto ditto ditto ditto ditto ditto	Op Op Op Op 	perate perate perate perate perate perate perate 1.0 .00 .00 .00 .00 .00 .00 .00 .00 .00	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269 270 271	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS	None - Operate - None - O None - O None - O On - O	Operate Operate Operate Operate Operate Operate 3.0 20.00 20.00 20.00 20.00 00 00 00 00 00 00 00 00 00 00 00 00		ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op 	perate perate perate perate 1.0 .00 .00 .00 1.00 .00 1.00 On	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269 270 271	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS	None - Operate - None - O O.1 O.10 - 2 O.10 - 2 O.05 - 2 O.05 - 2 Off -	Operate Operat	s pu pu pu pu pu -	ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op 1 1 (Off Off ((Off	perate perate perate perate 1.0 0.00 0.00 1.00 0.00 0.00 0.00 0.00	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269 270 271 272	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 30CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG 30CPG 30CPG 30CPG 30CPG 30CPG 40CPG 40CPG 40CPG 40CPG 40CPG	None - Operate - None - O Of - O Off - O O O O O O O O O O O O O O O O O O O	Operate Operat		ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op Op 1 1 1 Off Off Off Off Off Off Off Off Off	perate pe	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269 270 271 272 273	Event3 Sys. Set change Riy. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS 20CPS 30CPS	None - Operate - None - O None - O None - O None - O On -	Operate Operat		ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger difto ditto	Op Op Op Op 1 1 1 Off Off (((((perate pe	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 270 271 272 273 274 275	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 20CPS 30CPG 20CPS 30CPG 20CPG 30CPG 20CPG 30CPG 20CPS 30CPG 20CPS 30CPG 20CPG 30CPG	None - Operate - None - O None - O None - O None - O O - O - O - O - O - O - O - O - O	Operate Operat		ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op Op Of Of Off	perate pe	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 270 271 272 273 274 275 276	Event3 Sys. Set change Rly. Set change Grp. Set change 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS 30CPS 20CPS 30CPS 20CPS 30CPS 50CPS 30CPS 50CPS 5F	None - Operate - None - O None - O None - O On - O	Operate Operat		ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op Op 1 1 1 Off Off	Perate Pe	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 270 271 272 273 274 275	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 20CPS 30CPG 20CPS 30CPG 20CPG 30CPG 20CPG 30CPG 20CPS 30CPG 20CPS 30CPG 20CPG 30CPG	None - Operate - None - O None - O None - O None - O O - O - O - O - O - O - O - O - O	Operate Operat		ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op Op 1 1 1 Off Off	perate pe	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 270 271 272 273 274 275 276	Event3 Sys. Set change Rly. Set change Grp. Set change 10CPS 20CPS 30CPS 10CPG 20CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS 30CPS 20CPS 30CPS 20CPS 30CPS 50CPS 30CPS 50CPS 5F	None - Operate - None - O None - O None - O On - O	Operate Operate Operate Operate Operate Operate 3.0 20.00 20.00 20.00 20.00 20.00 20.00 On		ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op Op 1 1 1 1 0 Off Off Off Off Off Off Off Off Off O	Perate Pe	
252 253 254 255 256 257 258 260 261 262 263 264 265 266 267 268 270 271 272 272 273 274 275 276 277	Event3 Sys. Set change Rly. Set change Time 10CPS 20CPS 30CPS 30CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 20CPS 30CPS TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 20CPS 30CPS 5FE EVENT1	None - Operate - None - O On O	Operate Operat		ditto ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op Op 1 1 1 1 Off Off Off Off Off Off Off Off Off	Perate Pe	
252 253 254 255 256 257 258 260 261 262 263 264 265 266 267 268 269 270 271 272 273 274 275 275 276 277 278	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPG 30CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS 20CPS 30CPS 20CPS 30CPS 20CPS 30CPS 50CPS 50CPS 50CPG 20CPG 30CPG 20CPG 30CPG 20CPG	None - Operate - None - O None - O None - O On - 2	Operate Operat		ditto ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger difto ditto	Op Op Op Op Op 1 1 1 Off Off (0 (0 (0 (0 (0 (0 (Perate Pe	
252 253 254 255 256 257 258 259 260 261 262 263 264 265 267 270 271 272 273 274 275 276 277 277 278 279 279 279 279 279 279 279 279 279 279	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPS 30CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS 30CPS 50CPS 30CPS 50CPS	None - Operate - None - O None - O None - O None - O On -	Operate Operat		ditto ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger ditto	Op Op Op Op Op Op Op 1 1 1 1 0 Off Off Off Off Off Off Off Off Off O	Perate Pe	
252 253 254 255 256 257 258 260 261 262 263 264 265 266 267 271 272 273 274 275 276 277 278 279	Event3 Sys. Set change Rly. Set change Grp. Set change Time 10CPS 20CPS 30CPG 30CPG 30CPG TRIP1 TRIP2 TRIP3 TRIP4 TRIP5 10CPS 20CPS 30CPS 20CPS 30CPS 20CPS 30CPS 20CPS 30CPS 50CPS 50CPS 50CPG 20CPG 30CPG 20CPG 30CPG 20CPG	None - Operate - None - O None - O None - O On - 2	Operate Operat		ditto ditto ditto ditto ditto ditto Disturbance record OC element for disturbance recorder initiation Disturbance trigger difto ditto	Op Op Op Op Op 1 1 1 1 0 Off Off Off Off Off Off Off Off Off O	Perate Pe	

PLC default setting

	Output			Tim	ing		Lo	gic ex	pression			De	lay Tim	e / Flip I	Flop			
				Cycle							Flip I				Timer			
Nº	Signal	1	30	90	User	Turn	Model	100s	Model 200s	Norm	Back Up	Release Signal	Off Delay	On Delay	One Shot	Time	Value	None
1536	EXT MEC.TP1		Х				[513]	IBI1 (COMMAND			<u> </u>						X
1537	EXT MEC.TP2		Х				[514]	BI2 (COMMAND									Х
1538	EXT MEC.TP3		X				[515]	BI3 (COMMAND									Х
1539	EXT MEC.TP4		Х				[516]	BI4 (COMMAND									X
1540	IND.RESET		X				[517]	BI5 C	COMMAND									X
1541																		
1542																		
1543													_					İ
1544																		
1545																		
1546		▮┡																
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1548		▮┡											- 1					ļ
1549		▍┝										4						ļ
1550		l																İ
1551	EV/ENIT1	ı⊢	$\overline{}$				[EOG1	DI14	COMMAND				P					~
1002	EVENT1		X				[525]	D114	COMMAND				-					X
1553	EVENT2 EVENT3		X						COMMAND COMMAND									X
1554	EVENIO	l H	Х				[328]	סווס	COMMINIAND			4						X
1556		▍┢									-							
1557		▍┢																
1558		▍┢								_								
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1561									_	-								
1562									-									
1563									,									
1564																		
1565																		
1566																		
1567																		
	PROT BLOCK						[518]	BI6 (COMMAND									Χ
	DIF BLOCK																	
1570	1REF BLOCK																	
1571	10C BLOCK	▮┕																
	10CI BLOCK	!																
	1EF BLOCK	▮┡																ļ
15/4	1EFI BLOCK	! ⊢					-	~										ļ
	2REF BLOCK 2OC BLOCK	I						_		-								
1577	20CI BLOCK	▍├	\dashv					-	-									1
1572	2EF BLOCK	▍┢																
1570	2EFI BLOCK	1 📙	-+					F										l l
	3REF BLOCK	1 🖯	+					_										
	3OC BLOCK	1																
	3OCI BLOCK	1	\dashv															l
	3EF BLOCK	1 t																1
1584	3EFI BLOCK	1																
1585	4OC BLOCK				P													
1586	4OCI BLOCK			K														i
1587	FRQ BLOCK																	
1588	FRQ-A BLOCK				Y													
1589	V/F BLOCK																	
1590	V/F-A BLOCK																	
	THR BLOCK																	
	THR-A BLOCK			4														
1593	MEC.TP1 BLOCK																	
	MEC.TP2 BLOCK								·									
	MEC.TP3 BLOCK																	
	MEC.TP4 BLOCK																	
1597																		
1598																		
1599		J/L																

	Output			Tim	ing	1	<u>Log</u> ic ex	pression				lay Tim	<u>e / F</u> lip	Flop			
N	Cianal			Cycle		Turn	Madal 100a	Model 200s		Flip		0"		Timer		1	Name
N:	º Signal		30	90	User	Turn	Model 100s	Model 200s	Norm	Back Up	Release Signal	Off Delay	On Delay	One Shot	Time \	Value	None
160	00 TP1 DELAY		Χ				[315]TP1		Op	Olgital	Х	Doiay	CHOC	200	ms	
160	01 TP2 DELAY		X				[316	TP2				X			200	ms	
160	02 TP3 DELAY 03 TP4 DELAY		X				[317]TP3]TP4				X			200	ms ms	
160	04 TP5 DELAY		X				[310	TP5				X			200	ms	
160							1010	1110					_		200	1110	
160																	
_ :																	
<u>:</u> 179	20																
179	91																
179	92 IO#1-TP1		Х				[284]	RIP-1									Χ
179	93 IO#1-TP2		Χ				[291]	TRIP-2			4						X
179	94 IO#1-TP3		X				[298]	TRIP-3									X
178	95 IO#1-TP4 96 IO#1-TP5		X				[305]	TRIP-4 TRIP-5									X
179	9010#1-175		^				[312]	KIP-5									^
179																	
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262	23	- 								1							
262	24 F.RECORD1																
262	25 F.RECORD2							,		7							
<u>262</u>	26 F.RECORD3 27 F.RECORD4									_							
262 262	27 F.RECURD4																
262	29																
263	30																
263	31																
263	D.RECORD1							W/F									
<u>20</u> ,	33 D.RECORD2 34 D.RECORD3																
263	35 D.RECORD4																
263	36																
263	37																
260																	
260 264	40 SET.GROUP1																
26 ²	41 SET.GROUP2																
264	12 SET.GROUP3																
264	43 SET.GROUP4																
264	44 SET.GROUP5 45 SET.GROUP6				9												
	46 SET.GROUP7																
26 ²	47 SET.GROUP8			<u>.</u>	4				1								
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268	34		V					 									
268 268	35 B6 PROT COM R	ECV						 	-				-				
268	37 COIVI R	LOV															
	B8 TPLED RST F	RCV	•					1	1								
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Appendix I

Commissioning Test Sheet (sample)

- 1. Relay identification
- 2. Preliminary check
- 3. Hardware test
 - 3.1 User interface check
 - 3.2 Binary input/Binary output circuit check
 - 3.3 AC input circuit check
- 4. Function test
 - 4.1 Percentage current differential element DIF test
 - 4.2 2F-lock element check
 - 4.3 5F-lock element check
 - 4.4 High-set overcurrent element HOC test
 - 4.5 Restricted earth fault element REF test
 - 4.6 Overcurrent element test
 - 4.7 Thermal overload element THR test
 - 4.8 Frequency element FRQ test
 - 4.9 Overexcitation element V/F test
- 5. Protection scheme test
- Metering and recording check
- 7. Conjunctive test

1. Relay identification	
Туре	Serial number
Model	System frequency
Station	Date
Circuit	Engineer
Protection scheme	Witness
Active settings group number	_
2. Preliminary check	
Ratings	
CT shorting contacts	
DC power supply	
Power up	
Wiring	
Relay inoperative alarm contact	
Calendar and clock	10.
3. Hardware check	
3.1 User interface check	
3.2 Binary input/Binary output circuit chec	ck
Binary input circuit	
Binary output circuit	

3.3 AC input circuit check

4. Function test

4.1 Percentage current differential element DIF test

(1) Minimum operating value test

Tap setting	Measured current

(2) Percentage restraining characteristic test

Tap setting	I ₁	Measured current (I ₂)
	× I _k	
	× I _k	

(3) Operating time test

Tap setting	Test current	Measured time

4.2 2F-lock element check



- 4.4 High-set overcurrent element HOC test
- (1) Minimum operating value test

Tap setting	Measured current

(2) Operating time test

Tap setting	Test current	Measured time

4.5 Restricted earth fault element REF test

Tap setting	l _a	Measured current (I _n)
	× I _k	
	× I _k	

4.6 Overcurrent element test

(1) OC element

Element	Tap setting	Measured current
ОС		

(2) EF element

Element	Tap setting	Measured current
EF		

(3) OCI element

Element	Test current	Measured operating time
OCI	2×I _S	
	20 × I _S	. (7)

I_S: Setting value

(4) EFI element

Element	Test current	Measured operating time
EFI	$2 \times I_{S}$	
	20×1 _s	

4.7 Thermal overload element THR test

Element	Test current	Measured operating time
THR		

4.8 Frequency element FRQ test

(1) Frequency

Element	Setting	Measured frequency
FRQ-L1		
FRQ-L2		
FRQ-H1		
FRQ-H2		

(2) Undervoltage block

Setting	Measured voltage

4.9 Overexcitation element V/F test

(1) Operating value test

Element	Setting	Measured voltage
V/F		

(2) Operating time test

Test voltage	Measured operating time

5. Protection scheme test

Scheme	Results

- 6. Metering and recording check
- 7. Conjunctive test

Scheme	Results
On load	
Tripping circuit	

Appendix J
Return Repair Form

TOSHIBA

RETURN / REPAIR FORM

Please fill in this form and return it to Toshiba Corporation with the GRT100 to be repaired.

TOSHIBA CORPORATION Fuchu Complex

1, Toshiba-cho, Fuchu-shi, Tokyo, Japan

For: Power Systems Protection & Control Department

Quality Assurance Section

Туре:_	GRT100	Model:_			
(Exam	ple: Type:	GRT100	Model:	101B- 22-10)	
Date:					
1. W	hy the relay mal-opera does not o increased investigat others	operate error	ed?		

2. Fault records, event records or disturbance records stored in the relay and relay settings are very helpful information to investigate the incident.

So please inform us the information concerned in the incident with Floppy Disk, or filling up the Fault Record sheet and Relay Setting sheet attached.

TOSHIBA

Fault	Record	ţ
-------	--------	---

Date/Month/Year Time / / / : : . . (Example: 04/ Nov./ 1997 15:09:58.442)

Faulty phase:

 I_{n3} :

I_{dc}:

Prefault values	(CT ratio:	kA/:	A, VT ratio:	kV/: V)
I _{a1} :	kA or A∠	0	I _{a2} :	kA or A \angle °
I _{b1} :	kA or A∠	0	I _b 2:	kA or A∠
I _{c1} :	kA or A∠	0	I _{c2} :	kA or A∠ ◆
I ₁₁ :	kA or A∠	0	I _{12:}	kA or A∠ °
I _{21:}	kA or A∠	0	I ₂₂ :	kA or A∠ °
I ₀₁ :	kA or A∠	0	I_{02} :	kA or A∠ °
I_{n1} :	kA or A∠	0	I_{n2} :	kA or A \angle °
I _a 3:	kA or A∠	0		
Ih3:	kA or $A \angle$	0		

I_a3: kA or A∠
I_b3: kA or A∠
I_c3: kA or A∠
I₁3: kA or A∠
I₁3: kA or A∠
I₂3: kA or A∠
I₂3: kA or A∠

kA or A∠

Fault values (CT ratio: A, VT ratio: kV/: kA or A∠ Ia1: Ia2: kA or $A \angle$ kA or A∠ kA or $A\angle$ I_{b1}: I_b2: I_{c1} : kA or $A\angle$ I_{c2} : kA or A∠ kA or A∠ kA or $A \angle$ I₁₁: I₁₂: kA or A∠ kA or A∠ I₂₁: I₂₂: kA or A kA or A∠ 0 I01: I₀₂: kA or A kA or $A \angle$ I_{n1} : I_{n2} :

kA or A

 I_{d02} : kA or A kA or A

kA or A

3.	What was the message on the LCD display at the time of the incident.
	•
	. 6
4.	Please write the detail of the incident.
5.	Date of the incident occurred.
5.	Day/ Month/ Year: // /
	(Example: 10/ July/ 1998)
	(Endiple: 18/ valy/ 1998)
6.	Please write any comments on the GRT100, including the document.
	.VO
4	

Customer	
Name: Company Name: Address:	
Telephone No.: Facsimile No.: Signature:	

Appendix K

Technical Data

TECHNICAL DATA

Ratings	
-	1A or 5A
AC current	
AC voltage	100V, 110V, 115V, 120V
Frequency	50Hz or 60Hz
DC power supply	110Vdc/125Vdc (Operative range: 88 to 150Vdc)
	220Vdc/250Vdc (Operative range: 176 to 300Vdc)
	48Vdc/54Vdc/60Vdc (Operative range: 38.4 to 72Vdc)
40 to less B0 e el 150 00055 44	24Vdc/30Vdc (Operative range: 19.2 to 36Vdc)
AC ripple on DC supply IEC 60255-11	maximum 12%
DC supply interruption IEC 60255-11	~ 0
Permissive duration of DC supply voltage interruption to maintain normal operation	maximum 50ms at 110Vdc
Restart time	less than 10s
Binary input circuit DC voltage	110Vdc/125Vdc (Operative range: 88 to 150Vdc)
	220Vdc/250Vdc (Operative range: 176 to 300Vdc)
	48Vdc/54Vdc/60Vdc(Operative range: 38.4 to 72Vdc)
0	24Vdc/30Vdc (Operative range: 19.2 to 36Vdc)
Overload rating	
AC current input	4 times rated continuous
	100 times rated for 1s
AC voltage input	2 times rated continuous
	2.5 times rated for 1s
Burden	
AC current circuit	0.3VA per phase (at rated 5A)
	0.4VA at zero sequence circuit (at rated 5A)
	0.1VA per phase (at rated 1A)
~ 0	0.3VA at zero sequence circuit (at rated 1A)
AC voltage circuit	0.1VA (at rated voltage)
DC power supply	less than 14W (quiescent)
	less than 25W(operation)
Binary input circuit	0.5W/input at 110Vdc
Current differential protection	
Minimum operate current (ik)	0.10 to 1.00pu in 0.01pu steps
Slope 1 (p1)	10 to 100% in 1% steps
Slope 2 (p2)	50 to 200% in 1% steps
kp	1.00 to 10.00pu in 0.01pu steps
Vector group compensation (Winding 1 to 3) (d1 – d3)	0 to 11 (0 to 330deg in 30deg steps)
CT ratio correction (Winding 1 to 3) (kct1 – kct3)	0.05 to 50.00 in 0.01 steps
Inrush setting (2nd harmonic ratio) (k2f)	10 to 50% in 1% steps
Overexcitation setting (5th harmonic ratio) (k5f)	10 to 100% in 1% steps
Operating time	typical 35ms
High-set differential overcurrent protection	
Overcurrent (kh)	2.00 to 20.00pu in 0.01pu steps
Operating time	typical 20ms
	,,

Minimum operating current	0.054.050
	0.05 to 0.50pu in 0.01pu steps
Slope 1 (p1)	10 %
Slope 2 (p2)	50 to 100% in 1% steps
kp	0.50 to 2.00pu in 0.01pu steps
CT ratio correction (kct)	1.00 to 50.00 in 0.01 steps
Operating time	typical 35ms
Time-overcurrent protection	
High-set overcurrent element	
Pick up level (OC, EF)	0.10 to 20.00pu in 0.10pu steps
Delay time (TOC, TEF)	0.00 to 10.00s in 0.01s steps
Operating time	typical 30ms (without delay time)
Inverse time overcurrent element	
Pick up level (OCI, EFI)	0.10 to 5.00pu in 0.01pu steps
Time multiplier (TOCI, TEFI)	0.05 to 1.00 in 0.01 steps
Characteristic	Three IEC standard 60255-3 (Standard inverse, Very in
	Extremely inverse), or a Long-time inverse *Refer to Appendix P.
Thermal evalued protection	Relei to Appendix F.
Thermal everload protection	0.5 to 500.0min in 0.1min steps
Thermal time constant (τ)	
Comptant (Is)	
Constant (k)	0.10 to 4.00 in 0.01 steps
Basic current (IB)	0.50 t0 2.50pu in 0.01pu steps
Basic current (IB) Special load current before overload (Ip)	0.50 t0 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA)	0.50 t0 2.50pu in 0.01pu steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection	0.50 t0 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA)	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay)
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency	0.50 t0 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay)
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection	0.50 t0 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay)
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay)
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time	0.50 t0 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking	0.50 t0 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection Pickup voltage	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection Pickup voltage	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection Pickup voltage Alarm level (A) High level (H) Low level (L)	0.50 t0 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps 100.0 to 120.0V in 0.1V steps 1.03 to 1.30pu in 0.01pu steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection Pickup voltage Alarm level (A) High level (H)	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps 100.0 to 120.0V in 0.1V steps 1.03 to 1.30pu in 0.01pu steps 1.10 to 1.40pu in 0.01pu steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection Pickup voltage Alarm level (A) High level (H) Low level (L)	0.50 t0 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps 1.03 to 1.30pu in 0.01pu steps 1.05 to 1.30pu in 0.01pu steps 1.05 to 1.30pu in 0.01pu steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection Pickup voltage Alarm level (A) High level (H) Low level (L) LT (Definite time)	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps 100.0 to 120.0V in 0.1V steps 1.03 to 1.30pu in 0.01pu steps 1.05 to 1.30pu in 0.01pu steps 1 to 600s in 1s steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection Pickup voltage Alarm level (A) High level (H) Low level (L) LT (Definite time) HT (Definite time)	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps 1.00 to 120.0V in 0.1V steps 1.10 to 1.40pu in 0.01pu steps 1.05 to 1.30pu in 0.01pu steps 1 to 600s in 1s steps 1 to 600s in 1s steps
Basic current (IB) Special load current before overload (Ip) Time for alarming (TA) Frequency protection Overfrequency Underfrequency Delay time Start time Undervoltage blocking Overexitation protection Pickup voltage Alarm level (A) High level (H) Low level (L) LT (Definite time) HT (Definite time) TVFH (Definite time)	0.50 to 2.50pu in 0.01pu steps 0.00 to 1.00pu in 0.01 steps 0 to 10min in 1min steps 50.00 to 55.00Hz in 0.01Hz steps (50Hz relay) 60.00 to 66.00Hz in 0.01Hz steps (60Hz relay) 45.00 to 50.00Hz in 0.01Hz steps (50Hz relay) 54.00 to 60.00Hz in 0.01Hz steps (60Hz relay) 0.00 to 60.00s in 0.01s steps less than 100ms 40 to 100V in 1V steps 1.03 to 1.30pu in 0.01pu steps 1.05 to 1.30pu in 0.01pu steps 1 to 600s in 1s steps 1 to 600s in 1s steps 1 to 600s in 1s steps 1 to 600s in 1s steps

Accuracy	
Current differential element: pick-up	±5%
reset	±5%
Time-overcurrent protection: pick-up	±5%
Inverse time overcurrent characteristics:	
Standard inverse, Very and long-time inverse	IEC60255-3 class 5
Extremely inverse	IEC60255-3 class 7.5
Thermal overload protection: pick-up	±10%
Frequency protection: pick-up	±0.03Hz
Overexitation protection	±2% of pick-up voltage (frequency range ±2%)
Disturbance record initiation	
Overcurrent element	0.10 to 20.00pu in 0.01pu steps
Earth fault	0.05 to 20.00pu in 0.01pu steps
Pre-fault time	0.3s (fixed)
Post-fault time	0.1 to 3.0s in 0.1s steps
Communication port	
Front communication port (local PC)	. (/)
Connection	Point to point
Cable type	Multi-core (straight)
Cable length	15m (max.)
Connector	RS232C 9-pin D-subminiature connector female
Rear communication port (remote PC)	
RS485 I/F:	
Transmission data rate for RSM system	64kbps
Connection	Multidrop mode (max. 32 relays)
Connector	Screw terminals
Cable and length	Twisted pair cable, max. 1200m
Isolation	2kVac for 1min.
IRIG-B port	
Connection	BNC connector
Cable type	50 ohm coaxial cable
Binary inputs	
Operating voltage	Typical 74Vdc(min. 70Vdc) for 110V/125Vdc rating
	Typical 138Vdc(min. 125Vdc) for 220V/250Vdc rating
	Typical 31Vdc(min. 28Vdc) for 48V/54V/60Vdc rating
Contact ratings	
Trip contacts	
Make and carry	5A continuously,
	30A, 290Vdc for 0.5s (L/R=10ms)
Break	0.15A, 290Vdc (L/R=40ms)
Auxiliary contacts	
Make and carry	4A continuously,
	10A, 220Vdc for 0.5s (L/R≧5ms)
Break	0.1A, 220Vdc (L/R=40ms)
Durability	
Make and carry	10,000 operations minimum
Break	100,000 operations minimum

TOSHIBA 6 F 2 S 0 7 8 9

Mechanical design		
Weight	12kg	
Case color	Munsell No. 10YR8/0.5	
Installation	Flush mounting or rack mounting	

CT requirement

The CT knee point voltage Vk is required as follows:

The CT should not be saturated by maximum through fault current.

 $Vk \ge (RCT + R1 + Vb/n^2) \cdot Ifm/N$

Ifm: Maximum through fault current

N: CT ratio

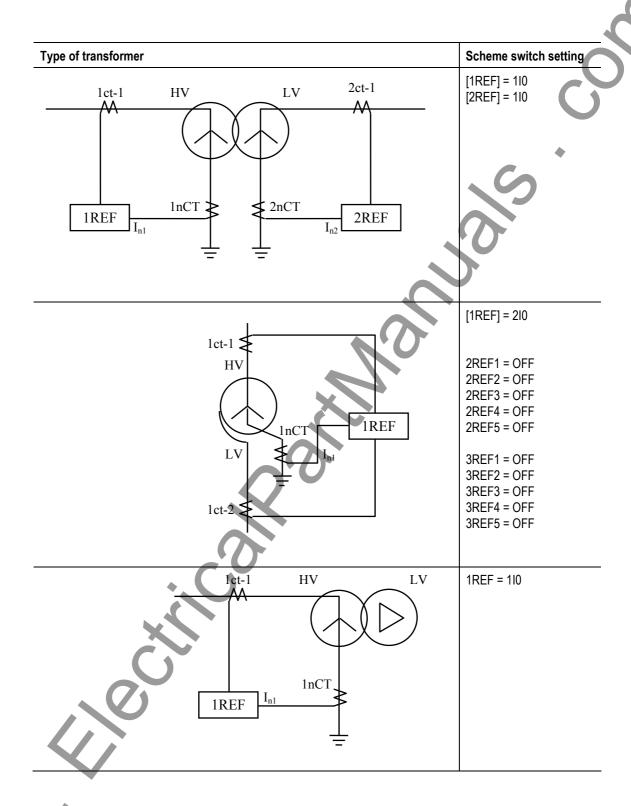
RCT: CT secondary resistanceR1: CT cable resistanceVb: Relay burden

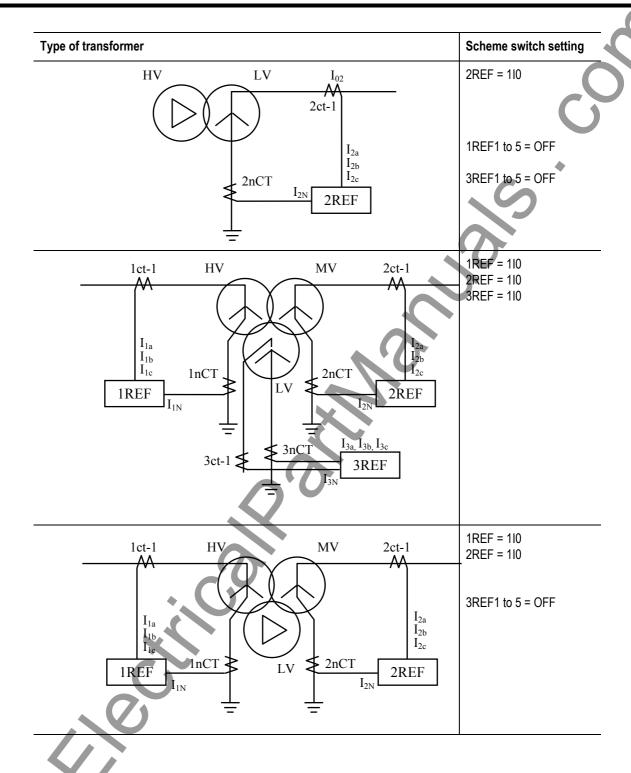
n: CT secondary rating

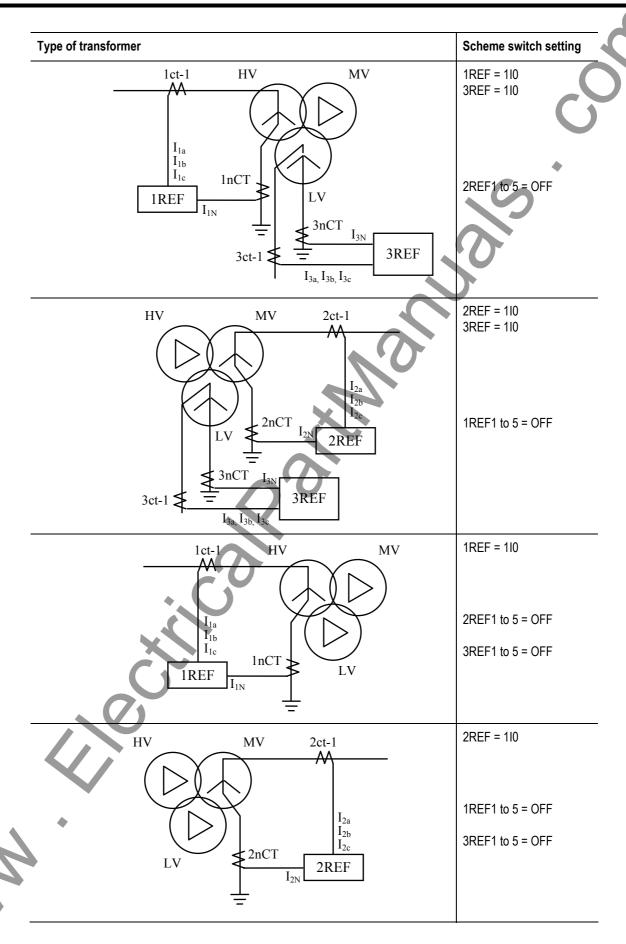
ENVIRONMENTAL PERFORMANCE CLAIMS

Test	Standards	Details
Atmospheric Environment	t	
Temperature	IEC60068-2-1/2	Operating range: -10°C to +55°C.
		Storage / Transit: -25°C to +70°C.
Humidity	IEC60068-2-78	56 days at 40°C and 93% relative humidity.
Enclosure Protection	IEC60529	IP51 (Rear: IP20)
Mechanical Environment		
Vibration	IEC60255-21-1	Response - Class 1 Endurance - Class 1
Shock and Bump	IEC60255-21-2	Shock Response Class 1
		Shock Withstand Class 1
		Bump Class 1
Seismic	IEC60255-21-3	Class 1
High Voltage Environment		NO
Dielectric Withstand	IEC60255-5	2kVrms for 1 minute between all terminals and earth.
		2kVrms for 1 minute between independent circuits.
		1kVrms for 1 minute across normally open contacts.
High Voltage Impulse	IEC60255-5	Three positive and three negative impulses of 5kV(peak), $1.2/50\mu s$, $0.5J$ between all terminals and between all terminals and earth.
Electromagnetic Environn	nent	
High Frequency	IEC60255-22-1 Class 3	1MHz 2.5kV applied to all ports in common mode.
Disturbance		1MHz 1.0kV applied to all ports in differential mode.
Electrostatic Discharge	IEC60255-22-2 Class 3	6kV contact discharge.
	. ()	8kV air discharge.
Radiated RF	IEC60255-22-3	Field strength 10V/m for frequency sweeps of 80MHz to
Electromagnetic Disturbance	X	1GHz. Additional spot tests at 80, 160, 450, 900 and 1890MHz.
Fast Transient	IEC60255-22-4 Class 4	4kV, 2.5kHz, 5/50ns applied to all inputs.
Disturbance		

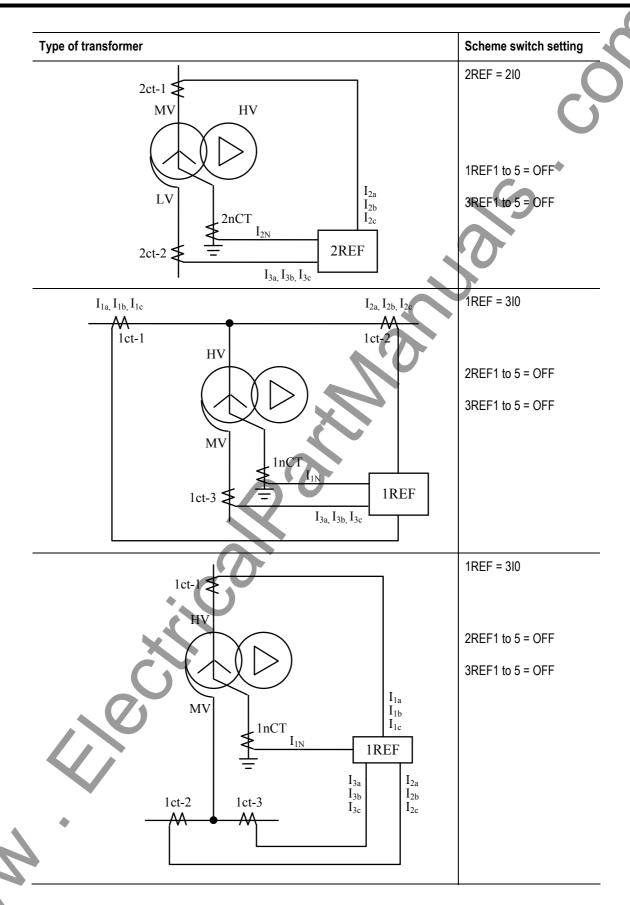
Appendix L
Setting of REF Element







Type of transformer	Scheme switch setting
HV MV	3REF = 110
(\triangleright)	G
	1REF1 to 5 = OFF
	3REF1 to 5 = OFF
$\begin{array}{c c} LV & \stackrel{\textstyle \searrow}{=} 3nCT \\ I_{3N} & 2DEE \end{array}$	
$3ct-1 = 3REF$ $I_{3a, I_{3b, I_{3c}}}$	
$\overline{\qquad \qquad \qquad }$ $\overline{\qquad \qquad }$	1REF = 210 3REF = 110
53d, 73U, 75U	
	2REF1 to 5 = OFF
$\begin{array}{c c} LV & & I_{3N} & 3REF & I_{1b} \\ \hline & & & I_{1c} \\ \end{array}$	
$=\frac{I_{1N}}{I_{1N}}$	
I_{2a} , I_{2b} , I_{2c}	
1ct-1	1REF = 2I0
HV	
	2REF1 to 5 = OFF
$\begin{array}{c c} I_{1a} & I_{1b} \\ I_{1c} & I_{1c} \end{array}$	3REF1 to 5 = OFF
$I_{\text{ct-2}}$ = I_{IN} 1REF	
$I_{2a,}I_{2b,}I_{2c}$	
	1REF = 1I0
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	2REF = 2I0
1ct-1	
InCT	3REF1 to 5 = OFF
$\begin{array}{c c} InCT & I_{2a} \\ \hline I_{N} & 1REF & I_{2b} \\ \hline I_{2c} & I_{2c} \end{array}$	
$2ct-2 = \frac{I_{2N}}{I_{2N}}$ $2REF$	
I_{3a} , I_{3b} , I_{3c}	



Appendix M

Symbols Used in Scheme Logic

Symbols used in the scheme logic and their meanings are as follows:

Signal names

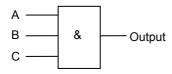
Marked with _____ : Measuring element output signal

Marked with (): Binary signal input from or output to the external equipment

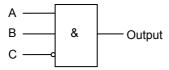
Marked with []: Scheme switch

Marked with " " : Scheme switch position
Unmarked : Internal scheme logic signal

AND gates



A	ВС	Output
1	1 1	1
Ot	ther cases	0

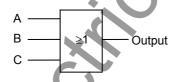


Α	В	С	Output
1	1	0	1
Otl	her cas	es	0

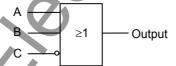


Α	В	С	Output
1	0	0 0	1
Of	ther cas	0	

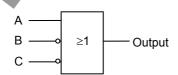
OR gates



A	В	Output	
0	0	0	0
Ot	her cas	1	

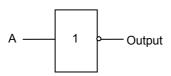


Α	В	С	Output
0	0	1	0
01	ther cas	es	1



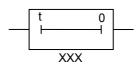
Α	В	С	Output
0	1	1	0
Ot	her cas	es	1

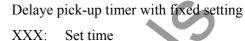
Signal inversion

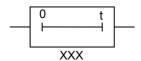


Α	Output
0	1
1	0

Timer





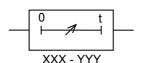


Delayed drop-off timer with fixed setting



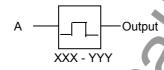


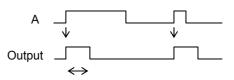
Delaye pick-up timer with variable setting XXX - YYY. Setting range



Delayed drop-off timer with variable setting XXX - YYY: Setting range

One-shot timer





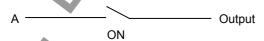
XXX - YYY: Setting range

Flip-flop

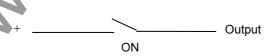


S	R	Output
0	0	No change
1	0	1
0	1	0
1	1	0

Scheme switch



A	Switch	Output
1	ON	1
Oth	er cases	0



Switch	Output
ON	1
OFF	0

Appendix N

Implementation of Thermal Model to IEC60255-8

Implementation of Thermal Model to IEC60255-8

Heating by overload current and cooling by dissipation of an electrical system follow exponential time constants. The thermal characteristics of the electrical system can be shown by equation (1).

$$\theta = \frac{I^2}{I_{AOL}^2} \left(1 - e^{-t/\tau} \right) \times 100\%$$
 (1)

where:

 θ = thermal state of the system as a percentage of allowable thermal capacit

I = applied load current,

 I_{AOL} = allowable overload current of the system,

 τ = thermal time constant of the system.

The thermal state θ is expressed as a percentage of the thermal capacity of the protected system, where 0% represents the cold state and 100% represents the thermal limit, that is the point at which no further temperature rise can be safely tolerated and the system should be disconnected. The thermal limit for any given electrical plant is fixed by the thermal setting I_{AOL} . The relay gives a trip output when $\theta = 100\%$.

If current I is applied to a cold system, then θ will rise exponentially from 0% to $(I^2/I_{AOL}^2 \times 100\%)$, with time constant τ , as in Figure N-1. If $\theta = 100\%$, then the allowable thermal capacity of the system has been reached.

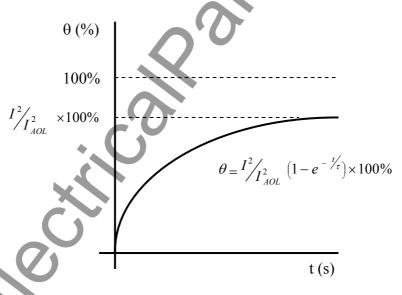


Figure N-1

A thermal overload protection relay can be designed to model this function, giving tripping times according to the IEC60255-8 'Hot' and 'Cold' curves.

$$t = \tau \cdot Ln \left[\frac{I^2}{I^2 - I_{AOL}^2} \right]$$

$$t = \tau \cdot Ln \left[\frac{I^2}{I^2 - I_{AOL}^2} \right]$$
 (1) ····· Cold curve
$$t = \tau \cdot Ln \left[\frac{I^2 - I_{P}^2}{I^2 - I_{AOL}^2} \right]$$
 (2) ····· Hot curve

where:

 I_P = prior load current.

In fact, the cold curve is simply a special case of the hot curve where prior load current $I_P = 0$, catering for the situation where a cold system is switched on to an immediate overload.

Figure N-2 shows a typical thermal profile for a system which initially carries normal load current, and is then subjected to an overload condition until a trip results, before finally cooling to ambient temperature.

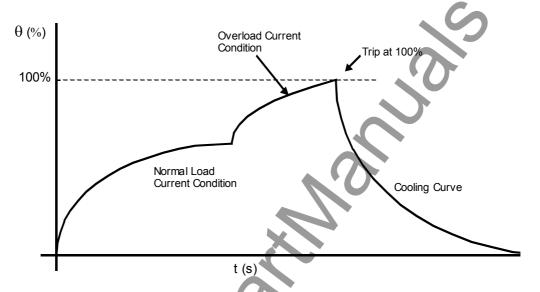


Figure N-2 (1) Thermal Curve without Prior Load Current

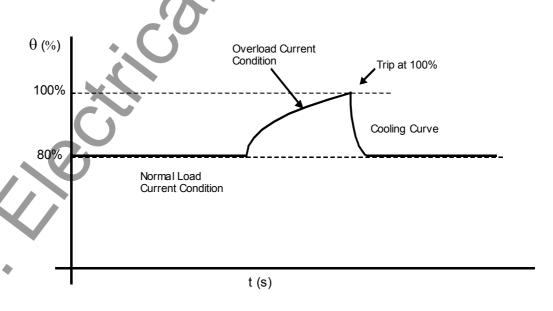


Figure N-2 (2) Thermal curve with Prior Load Current (θ=80%)

Appendix O

IEC60870-5-103: Interoperability and Troubleshooting

TOSHIBA

IEC60870-5-103 Configurator

IEC103 configurator software is included in a same CD as RSM100, and can be installed easily as follows:

Installation of IEC103 Configurator

Insert the CD-ROM (RSM100) into a CDROM drive to install this software on a PC.

Double click the "Setup.exe" of the folder "\IEC103Conf" under the root directory, and operate it according to the message.

When installation has been completed, the IEC103 Configurator will be registered in the start menu.

Starting IEC103 Configurator

Click [Start] \rightarrow [Programs] \rightarrow [IEC103 Configurator] \rightarrow [IECConf] to the IEC103 Configurator software.

Note: The instruction manual of IEC103 Configurator can be viewed by clicking [Help]→[Manual] on IEC103 Configurator.

IEC60870-5-103: Interoperability

1. Physical Layer

1.1 Electrical interface: EIA RS-485

Number of loads, 32 for one protection equipment

1.2 Optical interface

Glass fibre (option)

ST type connector (option)

1.3 Transmission speed

User setting: 9600 or 19200 bit/s

2. Application Layer

COMMON ADDRESS of ASDU

One COMMON ADDRESS OF ASDU (identical with station address)

3. List of Information

The following items can be customized with the original software tool "IEC103 configurator". (For details, refer to "IEC103 configurator" manual No.6F2S0812.)

- Items for "Time-tagged message": Type ID(1/2), INF, FUN, Transmission condition(Signal number), COT
- Items for "Time-tagged measurands": INF, FUN, Transmission condition(Signal number), COT, Type of measurand quantities
- Items for "General command": INF, FUN, Control condition(Signal number)
- Items for "Measurands": Type ID(3/9), INF, FUN, Number of measurand, Type of measurand quantities
- Common setting
 - Transmission cycle of Measurand frame

- FUN of System function
- Test mode, etc.

CAUTION: To be effective the setting data written via the RS232C, turn off the DC supply of the relay and turn on again.

3.1 IEC60870-5-103 Interface

3.1.1 Spontaneous events

The events created by the relay will be sent using Function type (FUN) / Information numbers (INF) to the IEC60870-5-103 master station.

3.1.2 General interrogation

The GI request can be used to read the status of the relay, the Function types and Information numbers that will be returned during the GI cycle are shown in the table below.

For details, refer to the standard IEC60870-5-103 section 7.4.3

3.1.3 Cyclic measurements

The relay will produce measured values using Type ID=3 or 9 on a cyclical basis, this can be read from the relay using a Class 2 poll. The rate at which the relay produces new measured values can be customized.

3.1.4 Commands

The supported commands can be customized. The relay will respond to non-supported commands with a cause of transmission (COT) of negative acknowledgement of a command.

For details, refer to the standard IEC60870-5-103 section 7.4.4.

3.1.5 Test mode

In test mode, both spontaneous messages and polled measured values, intended for processing in the control system, are designated by means of the CAUSE OF TRANSMISSION 'test mode'. This means that CAUSE OF TRANSMISSION = 7 'test mode' is used for messages normally transmitted with COT=1 (spontaneous) or COT=2 (cyclic).

For details, refer to the standard IEC60870-5-103 section 7.4.5.

3.1.6 Blocking of monitor direction

If the blocking of the monitor direction is activated in the protection equipment, all indications and measurands are no longer transmitted.

For details, refer to the standard IEC60870-5-103 section 7.4.6.

3.2 List of Information

The followings are the default settings.

List of Information

				IE	C103 Conf	figurator D	Default set	tina	
INF	Description	Contents	GI	Type		FUN		PI	
	·			; ID			Signal No.	OFF	ON
Stan	andard Information numbers in monitor direction								•
Syste	em Function								
0	End of General Interrogation	Transmission completion of GI items.	1	8	10	255		1) !
0	Time Synchronization	Time Synchronization ACK.	1	6	8	255		1	-
2	Reset FCB	Reset FCB(toggle bit) ACK	1	5	3	176		4	1
3	Reset CU	Reset CU ACK	1	5	4	176	-	1	-
4	Start/Restart	Relay start/restart	-	5	5	176		-	
5	Power On	Relay power on.		-	Not supported				
Statu	s Indications								
16	Auto-recloser active	If it is possible to use auto-recloser, this item is set active, if impossible, inactive.				Not supporte	d		
17	Teleprotection active	If protection using telecommunication is available, this item is set to active. If not, set to inactive.				Not supporte	d		
18	Protection active	If the protection is available, this item is set to active. If not, set to inactive.	GI	1	1, 7, 9, 12, 20, 21	176	1413	1	2
19	LED reset	Reset of latched LEDs	-	1	1, 7, 11, 12, 20, 21	176	1409	-	2
20	Monitor direction blocked	Block the 103 transmission from a relay to control system. IECBLK: "Blocked" settimg.	GI	1	9, 11	176	1241	1	2
21	Test mode	Transmission of testmode situation froma relay to control system. IECTST "ON" setting.	GI	7	9, 11	176	1242	1	2
22	Local parameter Setting	When a setting change has done at the local, the event is sent to control system.				Not supported	t supported		
23	Characteristic1	Setting group 1 active	Gl	1	1, 7, 9, 11, 12, 20, 21	176	1243	1	2
24	Characteristic2	Setting group 2 active	Gl	1	1, 7, 9, 11, 12, 20, 21	176	1244	1	2
25	Characteristic3	Setting group 3 active	GI	1	1, 7, 9, 11, 12, 20, 21	176	1245	1	2
26	Characteristic4	Setting group 4 active	GI	1	1, 7, 9, 11, 12, 20, 21	176	1246	1	2
27	Auxiliary input1					No			
28	Auxiliary input2					No			
29	Auxiliary input3					No			
30	Auxiliary input4					No			
Supe	rvision Indications								
32	Measurand supervision I	Zero sequence current supervision	GI	1	1, 7, 9	176	1271	1	2
33	Measurand supervision V	Zero sequence voltage supervision				Not supported	d		
35	Phase sequence supervision	Negative sequence voltage supevision				Not supported	d		
36	Trip circuit supervision	Output circuit supervision				Not supported	d		
37	I>>backup operation					Not supported	d		
38	VT fuse failure	VT failure				Not supported	d		
39	Teleprotection disturbed	CF(Communication system Fail) supervision				Not supported	d		
46	Group warning	Only alarming	GI	1	1, 7, 9	176	1258	1	2
47	Group alarm	Trip blocking and alarming	GI	1	1, 7, 9	176	1252	1	2
Earth	Fault Indications								
48	Earth Fault L1	A phase earth fault				No			
49	Earth Fault L2	B phase earth fault				No			
50	Earth Fault L3	C phase earth fault				No			
51	Earth Fault Fwd	Earth fault forward	Not supported						
52	Earth Fault Rev	Earth fault reverse				Not supported	d		

				15.0	100.0	· · -			
	D		<u> </u>			figurator D			
INF	Description	Contents	GI	Туре	COT	FUN		DPI	
F ""	P. 0			ID			Signal NO	. OFF	ON
Fault Ir	ndications Start/pick-up L1	A phase, A-B phase or C-A phase element pick-up				No			-
65						No			
	Start/pick-up L2	B phase, A-B phase or B-C phase element pick-up				***			
66	Start/pick-up L3	C phase, B-C phase or C-A phase element pick-up				No			
67	Start/pick-up N	Earth fault element pick-up				No		-	
68	General trip	Any trip	-	2	1, 7	176	1280		2
69	Trip L1	A phase, A-B phase or C-A phase trip				No			
70	Trip L2	B phase, A-B phase or B-C phase trip				No			
71	Trip L3	C phase, B-C phase or C-A phase trip				No			
72	Trip I>>(back-up)	Back up trip				Not supporte	1		
73	Fault location X In ohms	Fault location (prim. [ohm] / second. [ohm] / km selectable by IECFL)			4	Not supporte	d		
74	Fault forward/line	Forward fault				Not supporte	d		
75	Fault reverse/Busbar	Reverse fault				Not supporte	b		
76	Teleprotection Signal transmitted	Carrier signal sending		4		Not supporte	d		
77	Teleprotection Signal received	Carrier signal receiving				Not supporte	d		
78	Zone1	Zone 1 trip				Not supported	b		
79	Zone2	Zone 2 trip	1			Not supported	b		
80	Zone3	Zone 3 trip				Not supported	b		
81	Zone4	Zone 4 trip				Not supporte	d		
82	Zone5	Zone 5 trip				Not supporte	d		
83	Zone6	Zone 6 trip				Not supporte	d		
84	General Start/Pick-up	Any elements pick-up				No			
85	Breaker Failure	CBF trip or CBF retrip				Not supporte	d		
86	Trip measuring system L1					No			
87	Trip measuring system L2					No			
88	Trip measuring system L3					No			
89	Trip measuring system E					No			
90	Trip I>	Inverse time OC trip				No			
91	Trip I>>	Definite time OC trip				No			
92	Trip IN>	Inverse time earth fault OC trip				No			
93	Trip IN>>	Definite time earth fault OC trip				No			
Autore	close indications								
128	CB 'ON' by Autoreclose	CB close command output				Not supporte	d		
129	CB 'ON' by long-time Autoreclose					Not supporte	t		
130	Autoreclose Blocked	Autoreclose block				Not supporte	d		

			IFC	103 coi	ofigurato	r Defaul	t setting
INIE	Decemention	Cantanta					
INF	Description	Contents	GI	Туре	COT	FUN	Max. No.
				ID			
Measu	rands						
144	Measurand I	<meaurand i=""></meaurand>			No		0
145	Measurand I,V	lb1, Vab measurand <meaurand l=""></meaurand>		3.2	2, 7	176	2
146	Measurand I,V,P,Q	<meaurand i=""></meaurand>			No		0
147	Measurand IN,VEN	<meaurand i=""></meaurand>			No		0
148	Measurand IL1,2,3, VL1,2,3, P,Q,f	la1, lb1, lc1, f measurand <meaurand ii=""></meaurand>		9	2, 7	176	9
Generi	c Function						
240	Read Headings				Not supp	orted	
241	Read attributes of all entries of a group				Not supp	orted	
243	Read directory of entry				Not supp	orted	
244	Real attribute of entry		Not supported				
245	End of GGI				Not supp	orted	
249	Write entry with confirm				Not supp	orted	
250	Write entry with execute			,	Not supp	orted	
251	Write entry aborted				Not supp	orted	

Details of MEA settings in IEC103 configurator

INF	MEA	Tb1	Offset	Data type	Limit		Co eff	
					Lower	Upper		
145	lb1	1	28	short	0	4096	1.706666	
	Vab	1	12	short	0	4096	3.413333	
148	la1	1	24	short	0	4096	1.706666	
	la2	1	28	short	0	4096	1.706666	
	la3	1	32	short	0	4096	1.706666	
		1/7						
		* .						
	f	2	28	short	0	4096	0.0000833	

		Description Contents		Configura	itor Defau	ılt setting		
INF	Description			Type ID	COT	FUN		
Select	tion of standard information	numbers in control direction						
Systen	n functions							
0	Initiation of general interrogation			7	9	255		
0	Time synchronization			6	8	255		
Genera	al commands							
16	Auto-recloser on/off			Not su	pported			
17	Teleprotection on/off			Not su	pported			
18	Protection on/off	(*1)	ON/OFF	20	20	176		
19	LED reset	Reset indication of latched LEDs.	ON	20	▶ 20	176		
23	Activate characteristic 1	Setting Group 1	ON	20	20	176		
24	Activate characteristic 2	Setting Group 2	ON	20	20	176		
25	Activate characteristic 3	Setting Group 3	ON	20	20	176		
26	Activate characteristic 4	Setting Group 4	ON	20	20	176		
Generi	c functions		·					
240	Read headings of all defined groups		•	Not su	pported			
241	Read values or attributes of all entries of one group			Not su	pported			
243	Read directory of a single entry			Not su	pported			
244	Read values or attributes of a single entry	Not supporte						
245	General Interrogation of generic data	Not supported						
248	Write entry	Not supported						
249	Write entry with confirmation		Not supported					

^(*1) Note: While the relay receives the "Protection off" command, " IN SERVICE LED" is off.

Details of Command settings in IEC103 configurator

INF	DCO							
	Sig off	Sig on	Rev	Valid time				
18	2686	2686		0				
19	0	2688		200				
23	0	2640		1000				
24	0	2641)	1000				
25	0	2642		1000				
26	0	2643		1000				

✓ : signal reverse

Description	Contents	GRT100 supported	Comment
Basic application functions			
Test mode		Yes	
Blocking of monitor direction		Yes	
Disturbance data		No	
Generic services		No	
Private data		Yes	
/liscellaneous			160
Measurand		Max. MVAL = rated value times	
Current L1	la	Configurable	
Current L2	lb	Configurable	
Current L3	lc	Configurable	
Voltage L1-E	Va	No	
Voltage L2-E	Vb	No	
Voltage L3-E	Vc	No	
Active power P	Р	No	
Reactive power Q	Q	No	
Frequency f		Configurable	
Voltage L1 - L2	Vab	Configurable	

Details of Common settings in IEC103 configurator

GRT100_1.00 - Setting file's remark:

- Remote operation valid time [ms]: 4000

4000 - Local operation valid time [ms]:

- Measurand period [s]:

176 - Function type of System functions: - Signal No. of Test mode: 1242

- Signal No. for Real time and Fault number: 1279

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[Legend]

GI: General Interrogation (refer to IEC60870-5-103 section 7.4.3)

Type ID: Type Identification (refer to IEC60870-5-103 section 7.2.1)

- 1: time-tagged message
- 2: time-tagged message with relative time
- 3: measurands I
- 4: time-tagged measurands with relative time
- 5: identification
- 6: time synchronization
- 8 : general interrogation termination
- 9: measurands II
- 10: generic data
- 11: generic identification
- 20: general command
- 23: list of recorded disturbances
- 26: ready for transmission for disturbance data
- 27: ready for transmission of a channel
- 28: ready for transmission of tags
- 29: transmission of tags
- 30: transmission of disturbance values
- 31: end of transmission

COT: Cause of Transmission (refer to IEC60870-5-103 section 7.2.3)

- 1: spontaneous
- 2: cyclic
- 3: reset frame count bit (FCB)
- 4: reset communication unit (CU)
- 5: start / restart
- 6: power on
- 7: test mode
- 8: time synchronization
- 9: general interrogation
- 10: termination of general interrogation
- 11: local operation
- 12: remote operation
- 20: positive acknowledgement of command
- 21: negative acknowledgement of command
- 31: transmission of disturbance data
- 40: positive acknowledgement of generic write command
- 41: negative acknowledgement of generic write command
- 42: valid data response to generic read command
- 43: invalid data response to generic read command
- 44: generic write confirmation

FUN: Function type (refer to IEC60870-5-103 section 7.2.5.1)

DPI: Double-point Information (refer to IEC60870-5-103 section 7.2.6.5)

DCO: Double Command (refer to IEC60870-5-103 section 7.2.6.4)

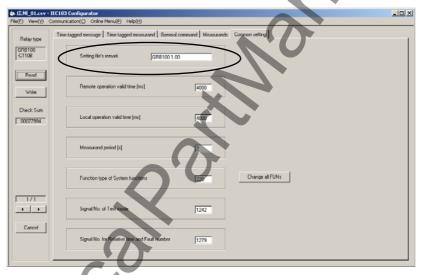
TOSHIBA

IEC103 setting data is recommended to be saved as follows:

(1) Naming for IEC103setting data

The file extension of IEC103 setting data is ".csv". The version name is recommended to be provided with a revision number in order to be changed in future as follows:

The name "*****" is recommended to be able to discriminate the relay type such as GRZ100 or GRL100, etc. The setting files remark field of IEC103 is able to enter up to 12 one-byte characters. It is utilized for control of IEC103 setting data.



(2) Saving theIEC103 setting data

The IEC103 setting data is recommended to be saved in external media such as FD (floppy disk) or CD-R, not to remain in the folder.

Troubleshooting

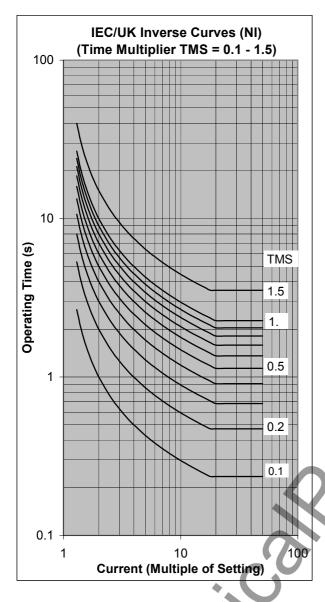
No.	Phenomena	Supposed causes	Check / Confirmation				
			Object	Procedure			
1	Communication	Address setting is incorrect.	BCU	Match address setting between BCU and relay.			
	trouble (IEC103 communication is		RY	Avoid duplication of address with other relay.			
	not available.)	Transmission baud rate setting is incorrect.	BCU RY	Match transmission baud rate setting between BCU and relay.			
		Start bit, stop bit and parity settings of data that BCU transmits to relay is incorrect.	BCU	Go over the following settings by BCU. Relay setting is fixed as following settings. - Start bit: 1bit - Stop bit: 1bit - Parity setting: even			
		The PRTCL1 setting is incorrect. (The model with PRTCL1 setting.)	RY	Change the PRTCL1 setting. Relation between PRTCL1 setting and available transmission protocol is referred to the following table.			
				RS485 port at the PRTCL1 PRTCL1 sack of the relay =HDLC =IEC			
				COM1 (CH1) HDLC IEC			
				COM2 (CH2) IEC -			
		RS485 or optical cable interconnection is incorrect.	Cable	- Check the connection port.(CH1/CH2) - Check the interconnection of RS485 A/B/COM - Check the send and received interconnection of optical cable.			
		The setting of converter is incorrect. (RS485/optic conversion is executed with the transmission channel, etc.)	Converter	In the event of using G1IF2, change the DIPSW setting in reference to INSTRUCTION MANUAL (6F2S0794).			
		The relationship between logical "0/1" of the signal and Sig.on/off is incorrect. (In the event of using optical cable)	BCU	Check the following; Logical0 : Sig.on Logical1:Sig.off			
		Terminal resistor is not offered. (Especially when RS485 cable is long.)	cable	Impose terminal resistor (150[ohms]) to both ends of RS 485 cable.			
		Relay cannot receive the requirement frame from BCU. (The timing coordination of sending and receiving switch control is irregular in half-duplex communication.)	BCU	Check to secure the margin more than 15ms between receiving the reply frame from the relay and transmitting the next requirement frame on BCU.			
		The requirement frame from BCU and the reply frame from relay contend.	BCU	Check to set the time-out of reply frame from the relay.			
	2	(The sending and receiving timing coordination is irregular in half-duplex communication.)		Time-out setting: more than 100ms (acceptable value of response time 50ms plus margin)			

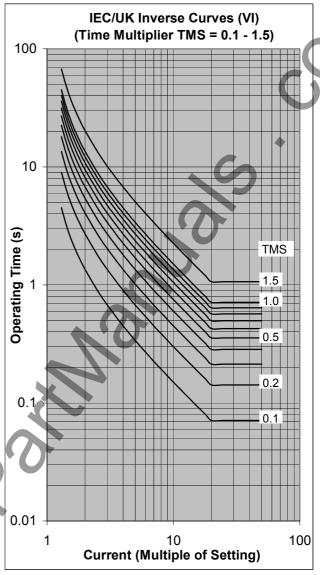
No.	Phenomena	Supposed causes	Check / Confirmation		
			Object	Procedure	
2	HMI does not display IEC103 event on the SAS side. The relevant event sending condition is not valid.		RY	Change the event sending condition (signal number) of IEC103 configurator if there is a setting error. When the setting is correct, check the signal condition by programmable LED, etc.	
		The relevant event Information Number	RY	Match the relevant event Information Number	
		(INF) and/or Function Type (FUN) may be different between the relay and SAS.	SAS	(INF) or Function Type (FUN) between the relay and SAS.	
		The relay is not initialised after writing IEC103 configurator setting.	RY	Check the sum value of IEC103 setting data from the LCD screen. When differing from the sum value on IEC103 configurator, initialise the relay.	
		It changes to the block mode.	RY	Change the IECBR settling to Normal.	
3	Time can be synchronised with	BCU does not transmit the frame of time synchronisation.	BCU	Transmit the frame of time synchronisation.	
	IEC103 communication.	The settling of time synchronisation source is set to other than IEC.	RY	Change the settling of time synchronisation source to IEC.	

(Note) BCU: Bay control unit, RY: Relay

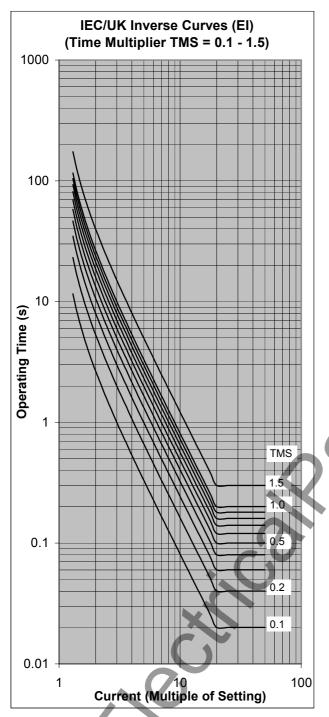
Appendix P

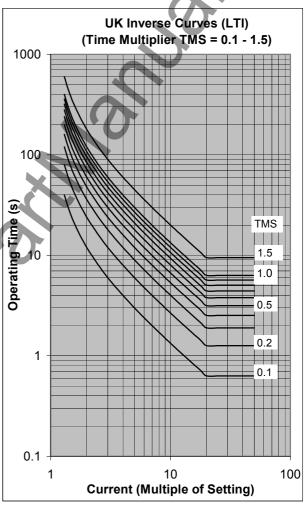
Inverse Time Characteristics





Normal Inverse





Extremely Inverse

Long Time Inverse

Appendix Q

Failed Module Tracing and Replacement

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1. Failed module tracing and its replacement

If the "ALARM" LED is ON, the following procedure is recommended. If not repaired, contact the vendor.

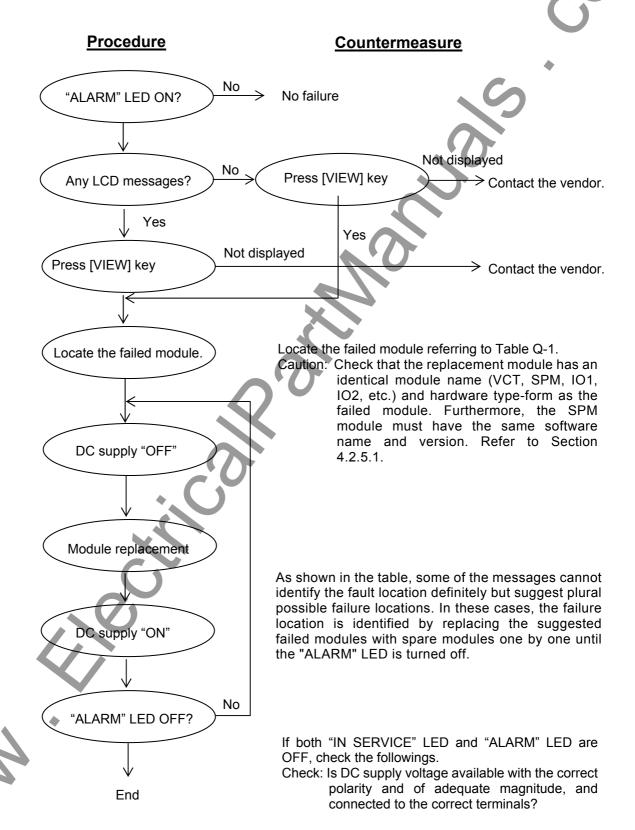


Table Q-1 LCD Message and Failure Location

Message				Failure	location		
	VCT	SPM	IO1	102	103	НМІ	AC cable
Checksum err		×					
ROM-RAM err		×					
SRAM err		×					
BU-RAM err		×					
DPRAM err		×					10
EEPROM err		×					
A/D err		×					
CT1 err	× (2)	× (1)			_ (7	× (2)
CT2 err	× (2)	× (1)					× (2)
CT3 err	× (2)	× (1)			1	•	× (2)
Sampling err		×					
DIO err		× (2)	× (1)	× (1)	× (1)		
RSM err		× (2)	×(1)	U			
No-working of LCD		× (2)				× (1)	

Note: This table shows the relationship between messages displayed on the LCD and the estimated failure location. Locations marked with (1) have a higher probability than locations marked with (2).

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2. Methods of Replacing the Modules

A CAUTION When handling a module, take anti-static measures such as wearing an earthed

wrist band and placing modules on an earthed conductive mat. Otherwise, many

of the electronic components could suffer damage.

CAUTION After replacing the SPM module, check all of the settings including the data

related the PLC and IEC103, etc. are restored the original settings.

The initial replacement procedure is as follows:

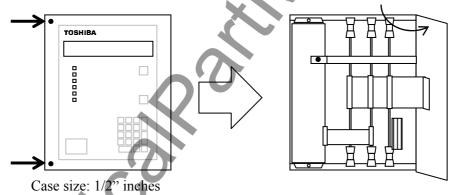
1). Switch off the DC power supply.

A WARNING Hazardous voltage may remain in the DC circuit just after switching off the DC power supply. It takes about 30 seconds for the voltage to discharge.

2). Remove the front panel cover.

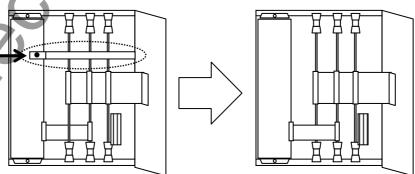
3). Open the front panel.

Open the front panel of the relay by unscrewing the binding screw located on the left side of the front panel.



4). Detach the holding bar.

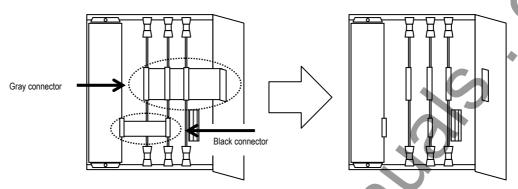
Detach the module holding bar <u>by unscrewing the binding screw</u> located on the left side of the bar.



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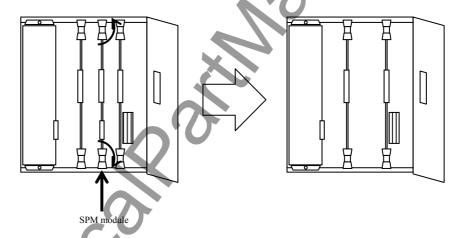
5). Unplug the cables.

Unplug the ribbon cable running among the modules by nipping the catch (in case of black connector) and by pushing the catch outside (in case of gray connector) on the connector.



6). Pull out the module.

Pull out the failure module by pulling up or down the top and bottom levers (white).



7). Insert the replacement module.

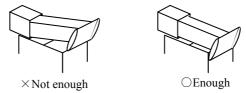
Insert the replacement module into the same slots where marked up.

8). Do the No.5 to No.1 steps in reverse order.

A CAUTION

Supply DC power after checking that all the modules are in their original positions and the ribbon cables are plugged in. If the ribbon cables are not plugged in enough (especially the gray connectors), the module could suffer damage.

Details of the gray connector on modules (top side)



9). Lamp Test

- RESET key is pushed 1 second or more by LCD display off.
- It checks that all LCDs and LEDs light on.

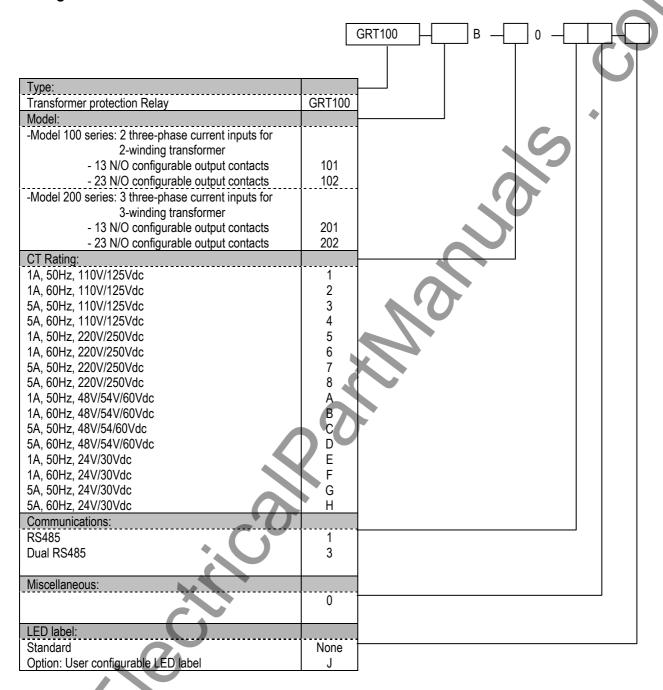
10). Check the automatic supervision functions.

- LCD not display "Auto-supervision" screens in turn, and Event Records
- Checking the "IN SERVICE" LED light on and "ALARM LED" light off.

Appendix R
Ordering

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Ordering



Version-up Records

Version No.	Date	Revised Section	Contents		
0.0	Feb. 4, 2004		First issue		
0.1	Apr. 21, 2004	2.3.1	Modified the description and the Figure 2.3.2.		
		2.3.2.2	Modified the description.		
		2.3.4	Modified the setting table.		
		4.2.5.1, 4.2.6.7	Modified samples of LCD screens.		
		Appendices	Modified the Appendix E, H, K and P, and added the Appendix P		
0.2	Aug. 23, 2004	3.2.1	Modified the description.		
		3.2.3	Added the Section 3.2.3.		
		4.5	Modified the description.		
		6.7.3	Modified the description.		
		Appendices	Modified the Appendix H, K and O. Added the Appendix Q.		
0.3	May. 30, 2005	2.3.1	Modified Table 2.3.1 and 2.3.2.		
		2.3.4	Modified the description of 'Setting for CT ratio matching'.		
		3.2.1	Modified the description of 'Binary input signals'.		
		5.1	Modified the description.		
		6.7.3	Modified the description.		
		Appendices	Modified the Appendix K, O and P.		
0.4	Sep. 06, 2005	4.2.6.5	Modified the description. (Disturbance record)		
		Appendices	Modified the Appendix O and P.		
0.5	Jan. 31, 2006	2.3.1	Modified the description.		
		2.3.4	Modified the description.		
		2.4	Modified the description of the 'Setting'.		
		2.5	Modified the description.		
		2.11.2	Modified the description.		
		Appendices	Modified the Appendix B (Signal name of No. 242 and 248), J and K.		
0.6	Aug. 29, 2006	4.2.5.1	Modified the LCD sample screen. (Relay version)		
		Appendices	Modified the Appendix P and Q.		
0.7	Aug. 10, 2007	3.4.3	Modified the description.		
		4.2.6.7	Added 'CAUTION' in the 'Setting the transformer parameters'.		
		4.4	Modified the description.		
		6.7.2	Modified the description and Table 6.7.1.		
		6.7.3	Modified the description of 'CAUTION'.		
		Appendices	Modified Appendix E, G, K, O, Q and R, and added Appendix P.		
0.8	Oct. 2, 2007	4.2.4.3	Modified the description.		

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